

Acoustic particle detection

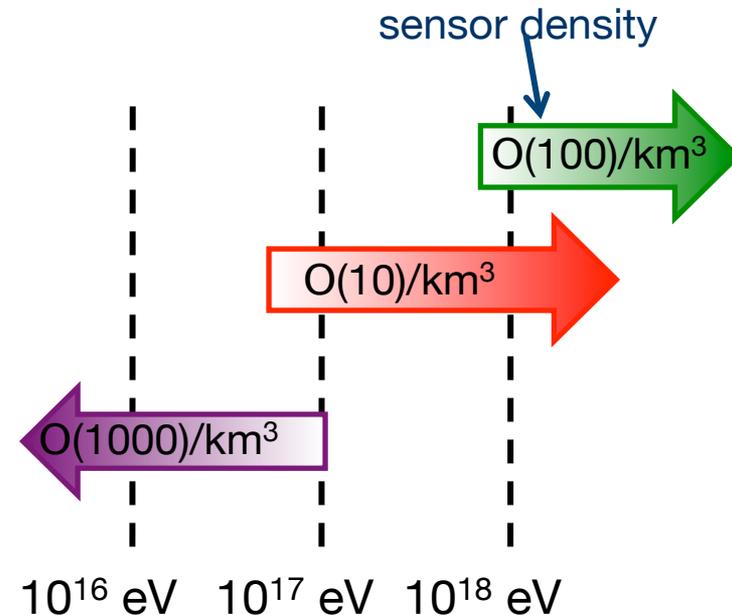
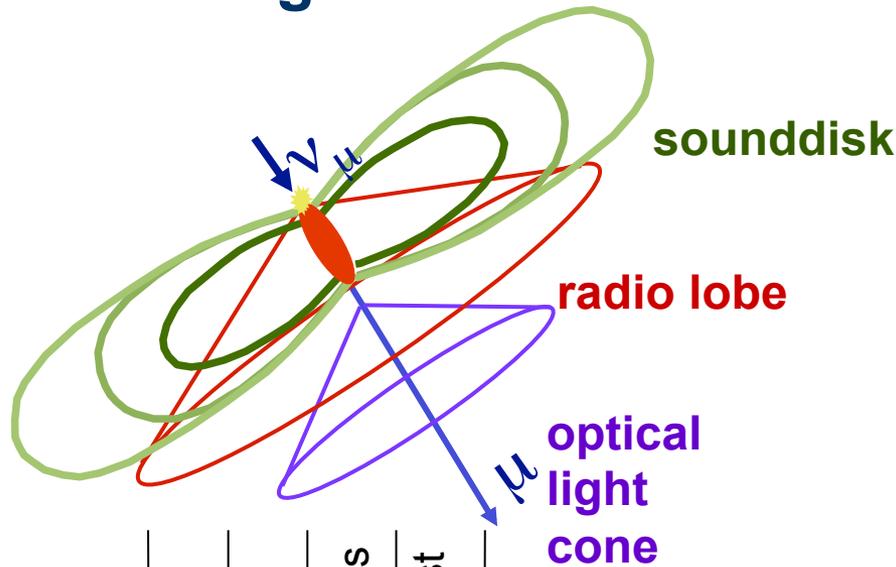
Robert Lahmann
HAP Workshop: The Non-Thermal Universe
Erlangen, 21-Sept-2016



Outline

- Introduction: acoustic neutrino detection
- The “first generation” of acoustic neutrino test setups
- Lessons learned and future activities
- Conclusions

Neutrino signatures in different media



	Ice	Water	Salt domes	Permafrost
light	✓	✓		
radio	✓		✓	✓
sound	✓	✓	✓	✓

adapted from: R. Nahnauer, ARENA Conf. 2010

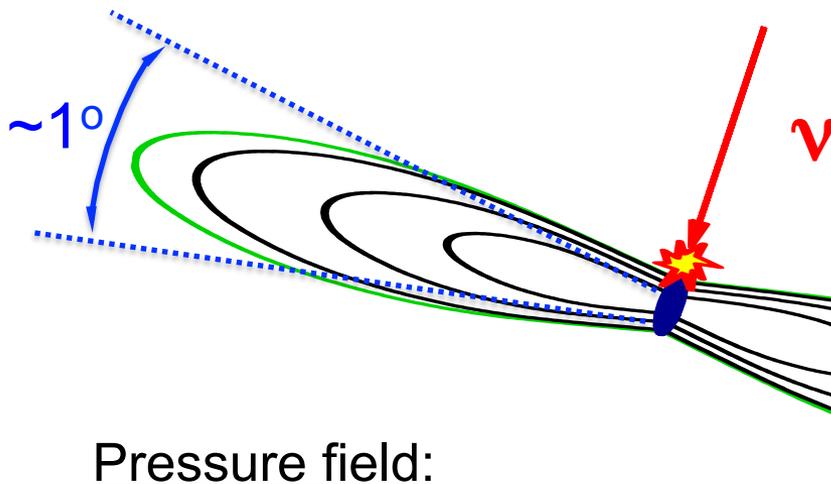
Advantages of acoustic detection:

- long attenuation length
- simple, robust technology
- multi purpose applications

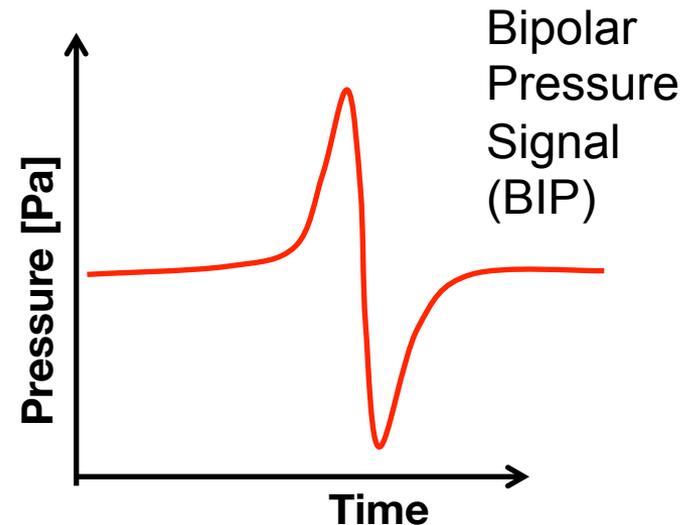
Acoustic signals of neutrino interactions

Thermo-acoustic effect: (Askariyan 1979)
energy deposition \Rightarrow local heating ($\sim \mu\text{K}$) \Rightarrow expansion \Rightarrow pressure signal

Hadronic cascade:
 $\sim 10\text{m}$ length, few cm radius

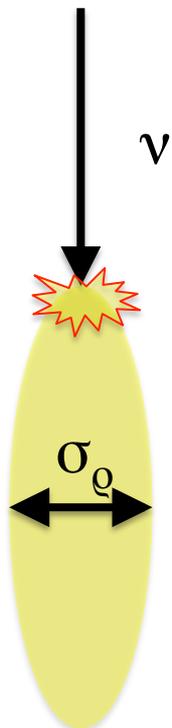


Pressure field:
Characteristic “pancake” pattern



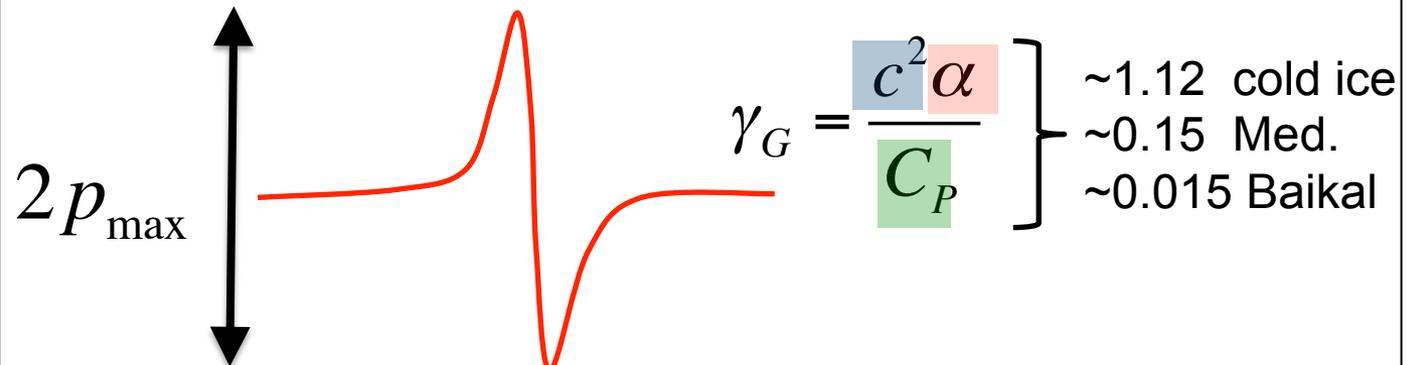
$$f_{\max} = O(10\text{kHz})$$

The bipolar pulse



$$E_0 = \int \varepsilon dV \quad (\varepsilon : \text{energy density})$$

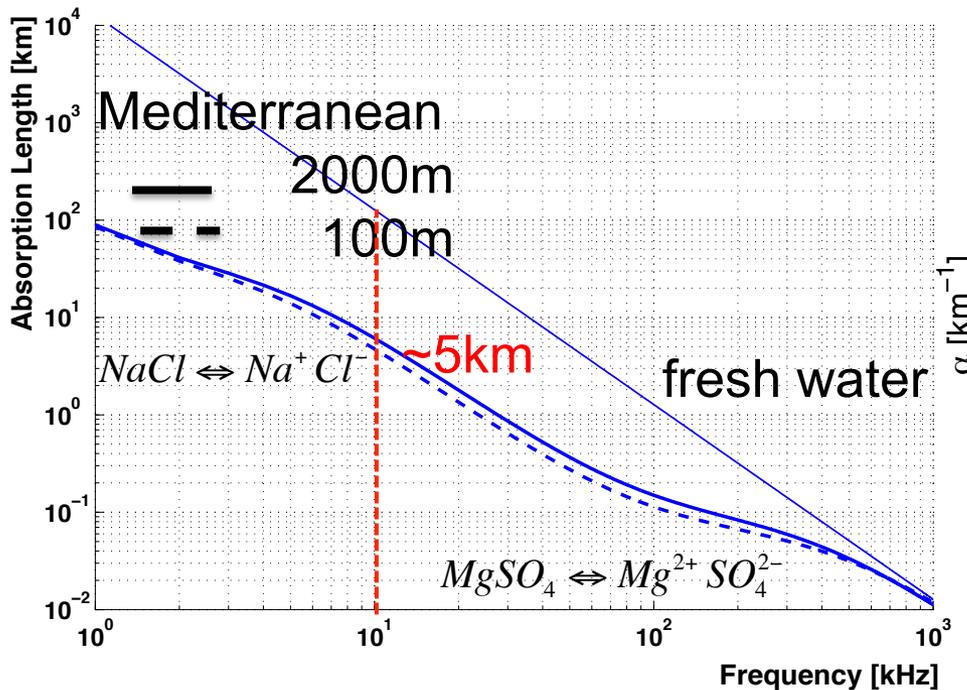
Analytical calculation of a signal in the far field for a Gaussian energy density



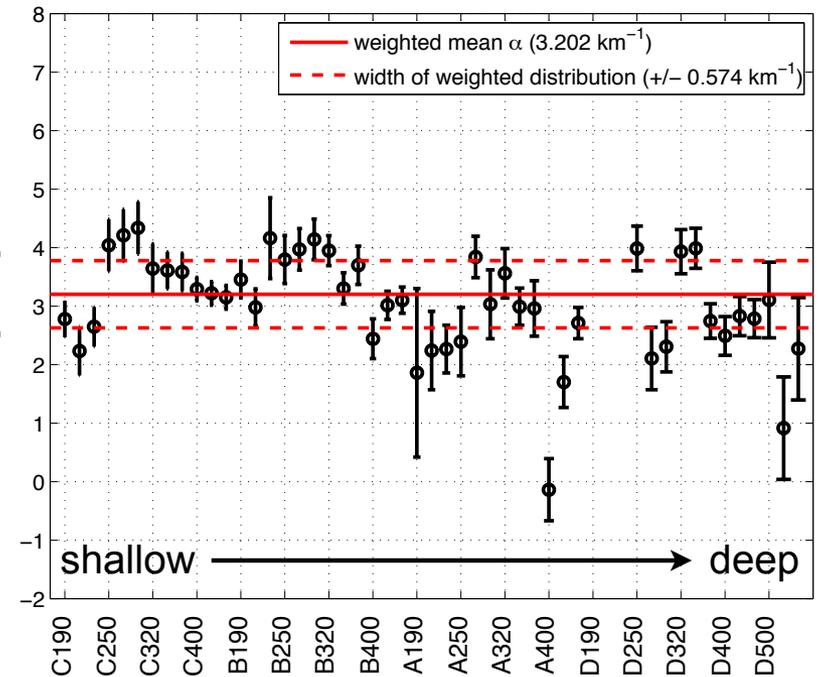
- α = Volume expansion coefficient
- C_P = specific heat capacity (at constant pressure)
- c = speed of sound (ca. 1500 m/s in water)

Attenuation length

water



IceCube site (SPATS)



(from: T. Karg, ARENA2012)

module
 $\lambda = 312_{-47}^{+68} \text{ m}$
 shorter than expected,
 but no show stopper

Acoustic detection test setups

“First generation” acoustic test setups for feasibility studies (background), developing techniques/algorithms

Two approaches:

- Use of existing (military) arrays
- piggybacking on neutrino telescope infrastructure

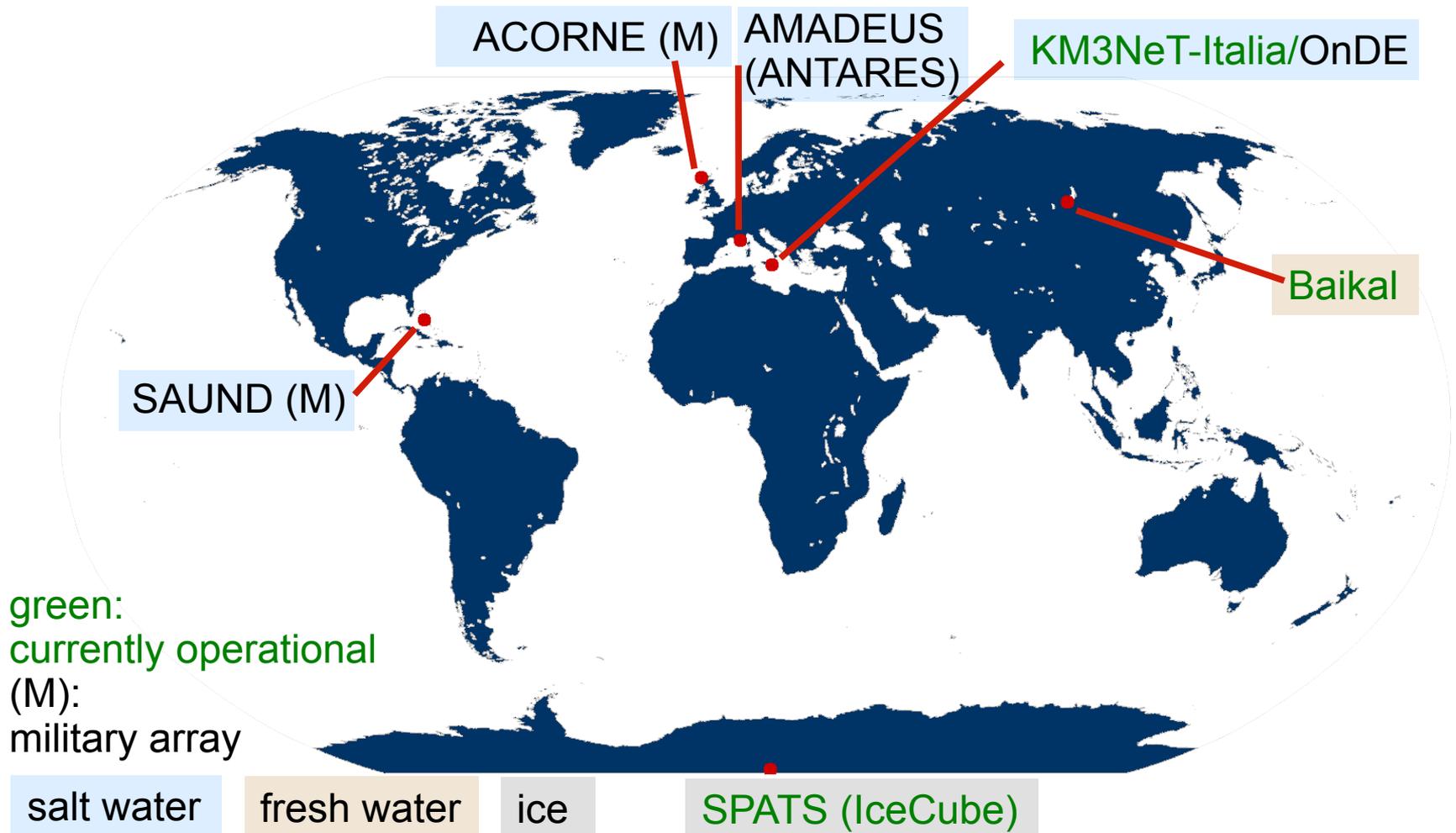
Technology:

Hydrophones (in water) and glaciophones (in ice) using piezo ceramics

Array size:

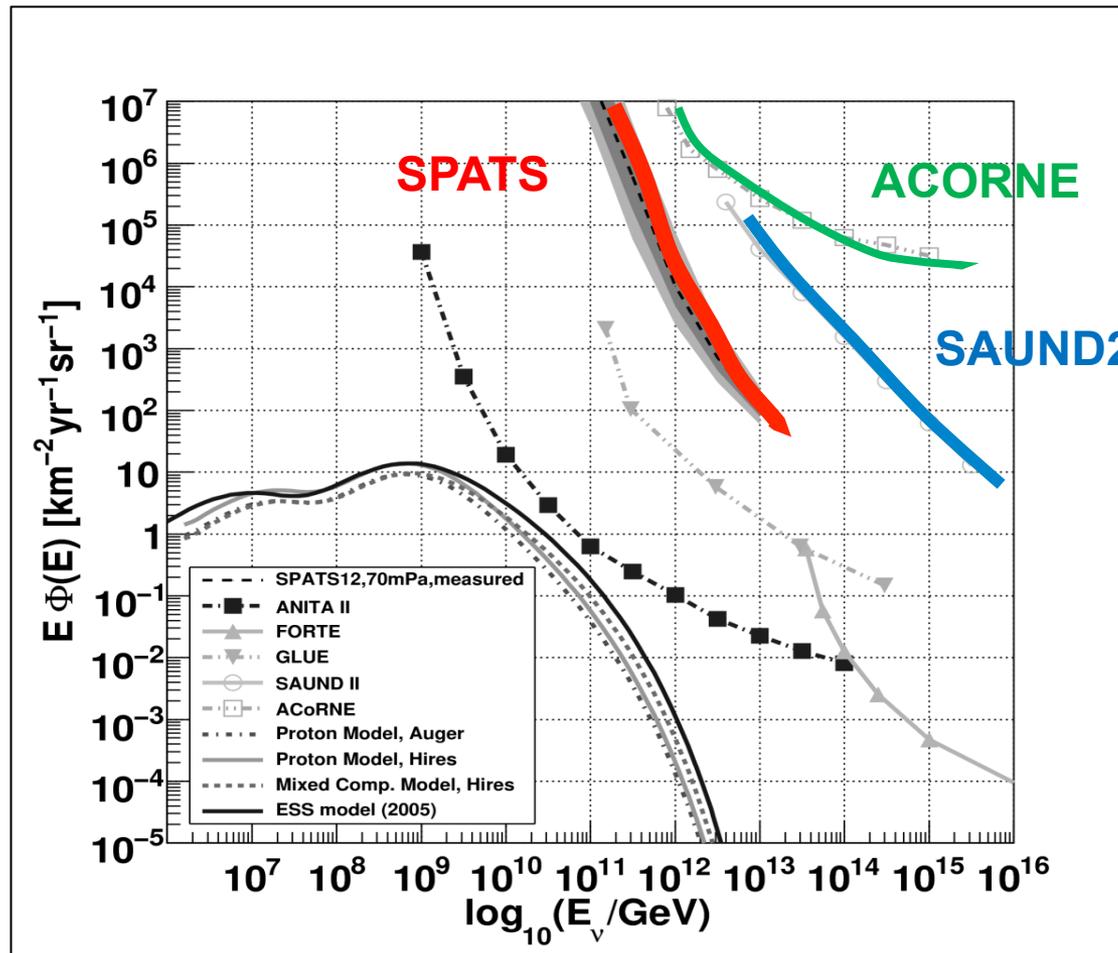
$O(10)$ sensors

Test setups in ice and water



Limits on UHE neutrino flux

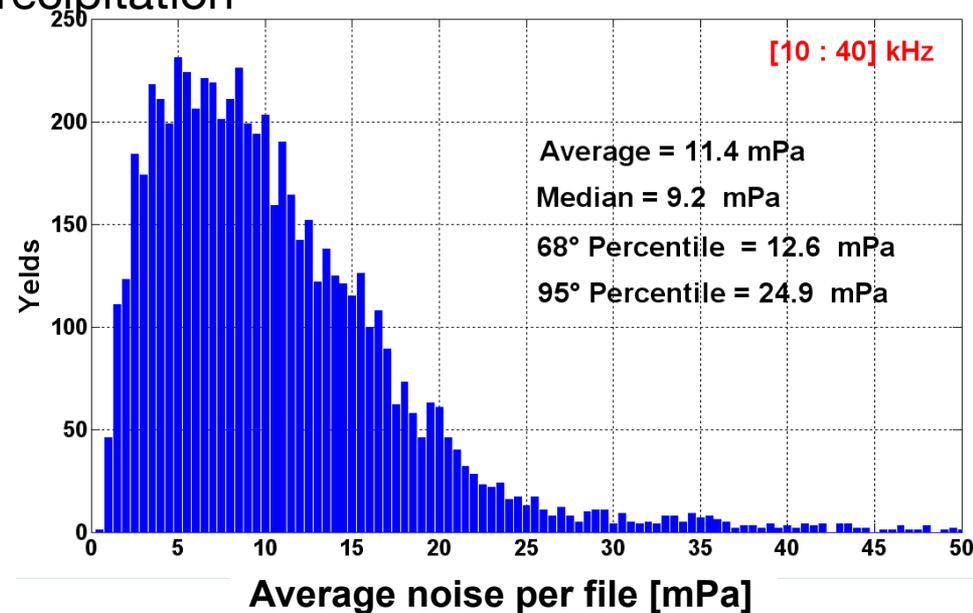
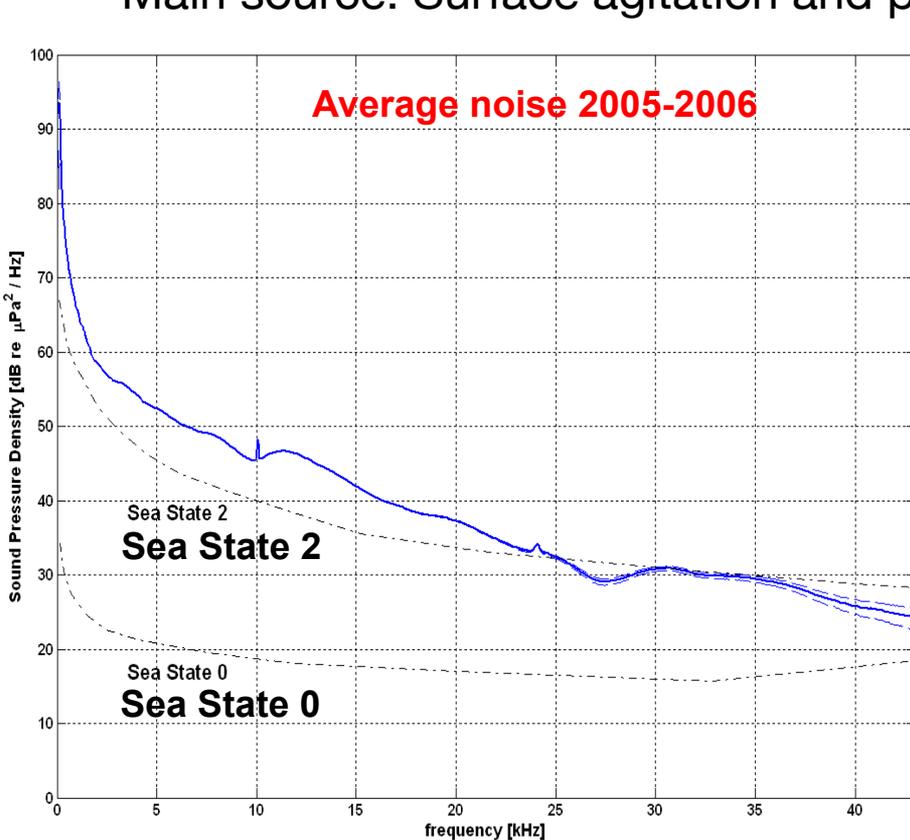
SPATS, ARENA 2012



R. Abbasi et al., arXiv:astro-ph/1103.1216

OnDE ambient noise (ARENA 2008)

Main source: Surface agitation and precipitation



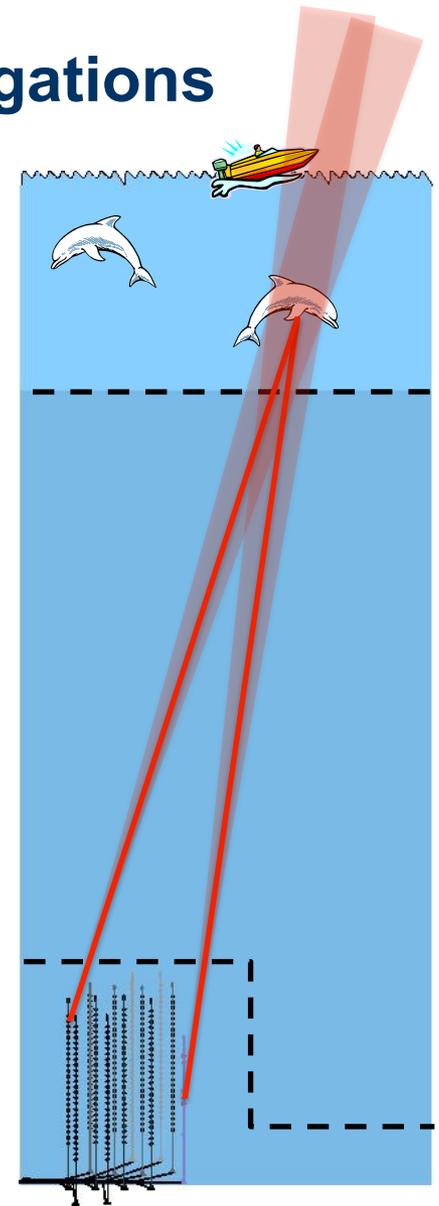
astro/ph 0804.2913

$$A_p(f_1, f_2) = \left[\int_{f_1}^{f_2} PSD \cdot (f) df \right]^{\frac{1}{2}}$$

The average noise in the [20:43] kHz band is $5.4 \pm 2.2_{\text{stat}} \pm 0.3_{\text{sys}}$ mPa

AMADEUS transient background investigations

- Sources: Very diverse;
Shipping traffic, marine mammals, ...
⇒ Mostly originating from near surface
- Suppression:
 - signal classification
 - Project reconstructed signals to surface,
perform clustering



Lessons learned and future experiments

Mediterranean (→ KM3NeT):

- Ambient noise low and stable;
reduction of SNR for signal detection crucial
- Transient background:
High level of (mainly dolphins);
Recognition of “acoustic pancake” crucial

Lake Baikal (→ GVD):

- Good background conditions, easy deployment, but low signal amplitude due to low temperature in lake

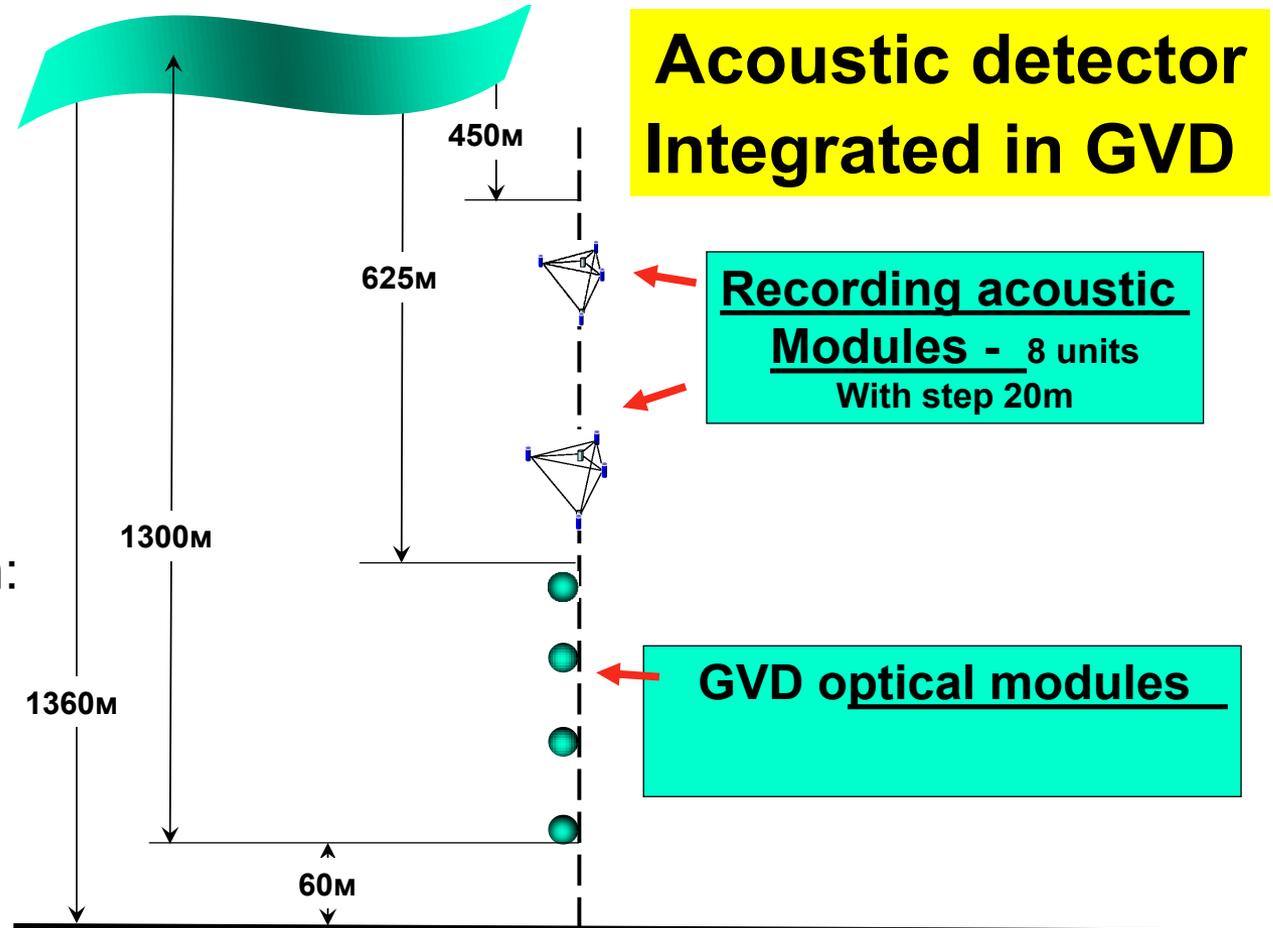
Ice (→ IceCube-Gen2 ?):

- Attenuation length shorter than expected, but no show stopper;
combination optical/radio/acoustic provides unique potential

Lake Baikal

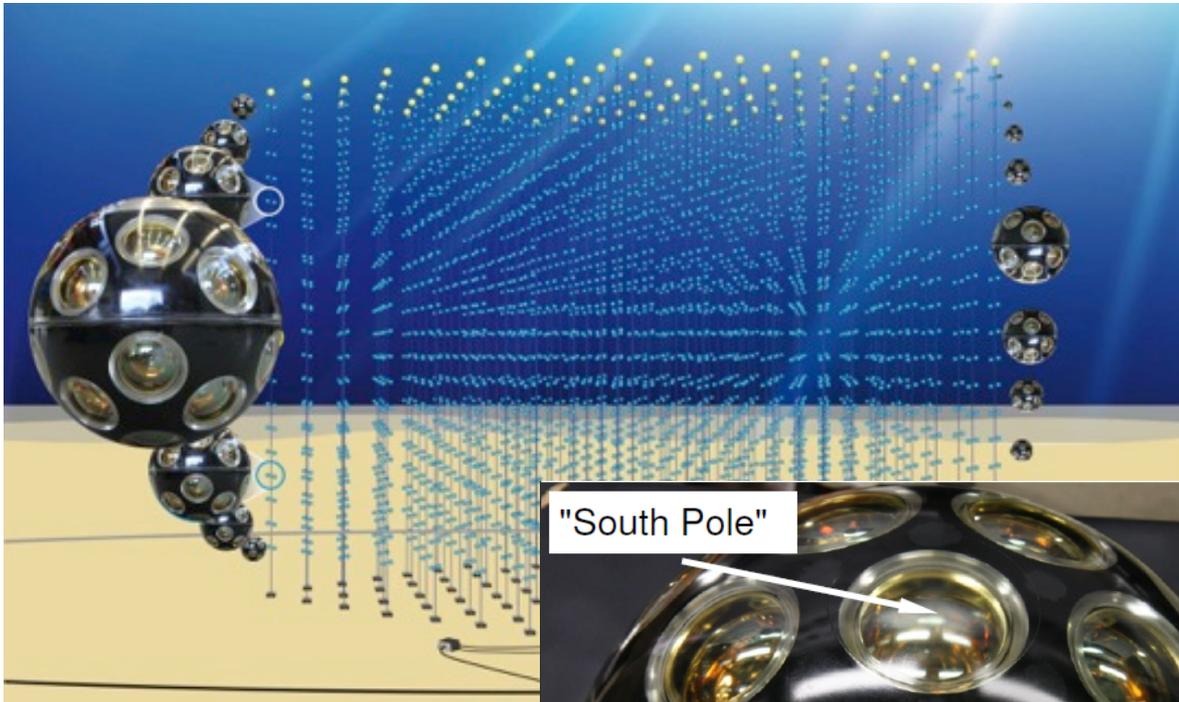
GVD:
Gigaton Volume
Detector;
Planned for 2020

Main problem for
acoustic detection:
low temperature

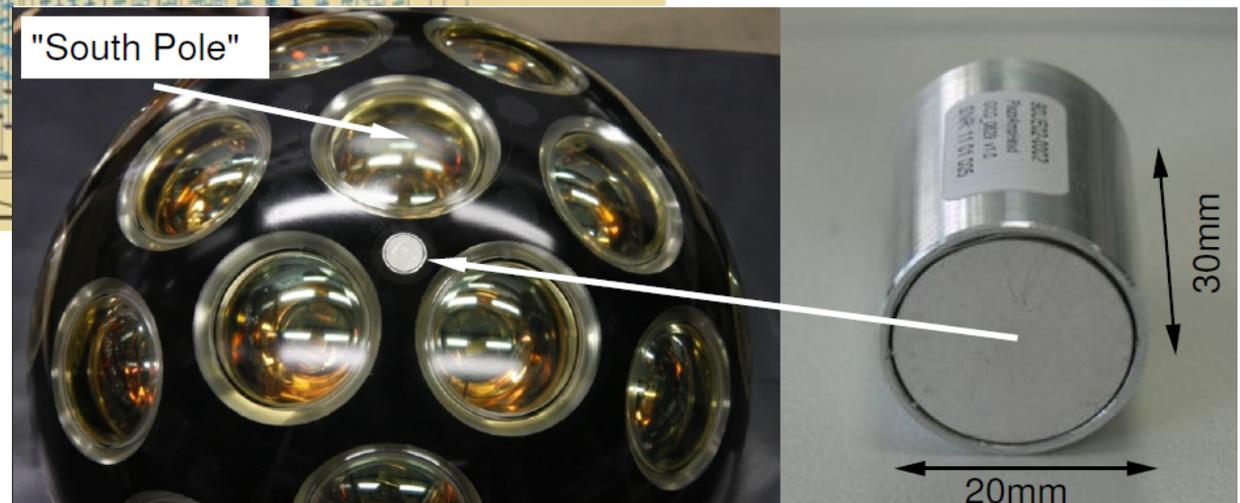


(from: N.Budnev, ARENA2016)

KM3NeT design

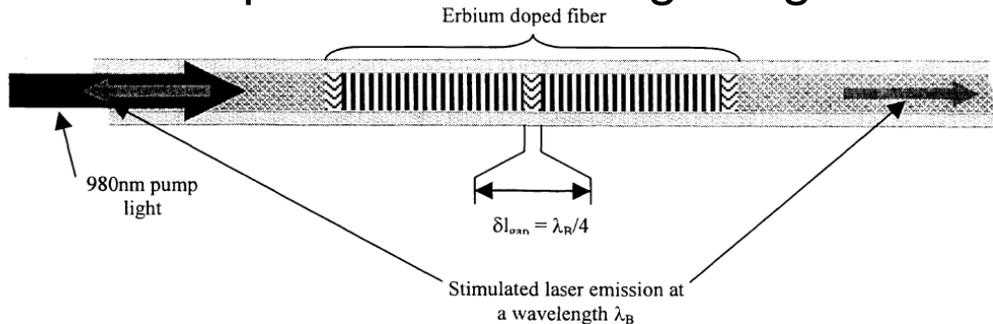


piezo sensor
integrated into OM



Potential fiber hydrophone system for KM3NeT

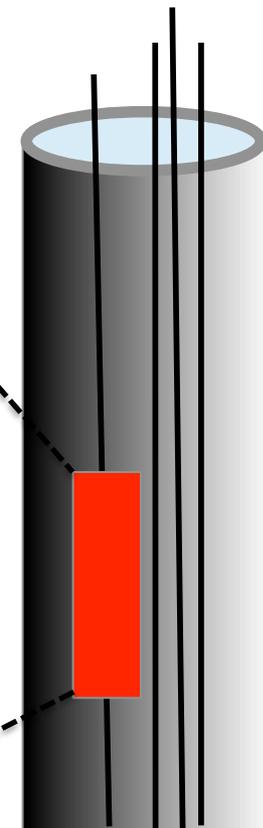
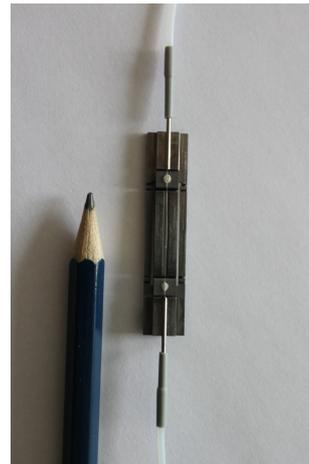
- Erbium doped fibers with a grating



- Sensor
Convert pressure pulse to a mechanical deformation of the fiber: strain

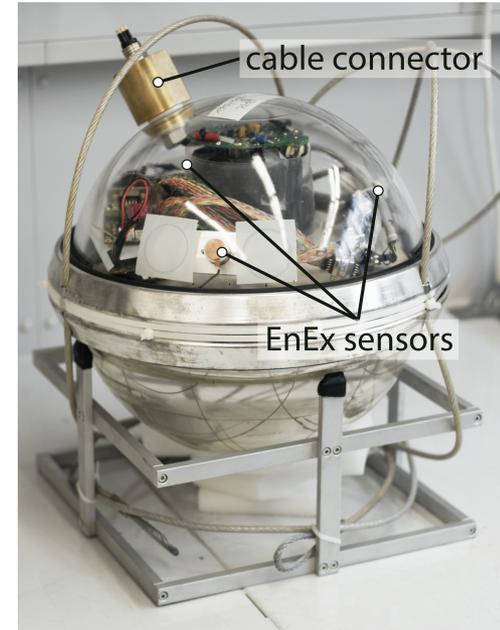
- Interrogator
on-shore system

TNO (Dutch organization for applied scientific research) joined KM3NeT to pursue this technique



*oil filled hose
or solid cable*

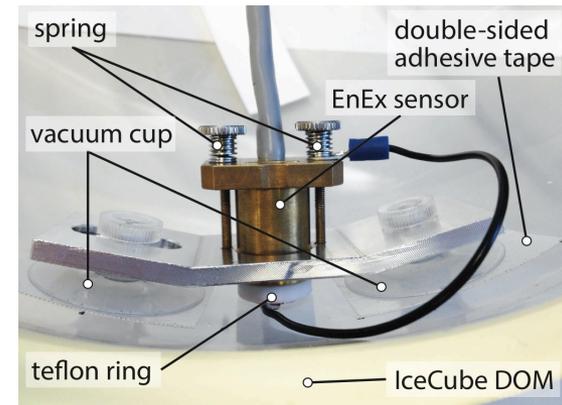
- IceCube-Gen2 is a planned extension of IceCube Neutrino Observatory
- Increased detector volume ($\sim 10 \text{ km}^3$) in the Antarctic ice
 - Increased spacing between detector modules ($\sim 240 \text{ m} - 300 \text{ m}$)
 - Optical geometry calibration (accuracy $< 1 \text{ m}$) is expected to deteriorate
- Use acoustic signals, due to larger extinction length ($\sim 300 \text{ m}$ [SPATS]) for geometry calibration
- Develop acoustic positioning concept for IceCube-Gen2
- Use sensors for acoustic neutrino detection



Up to now: (master's thesis S. Wickmann)



- Modified existing acoustic sensor from the EnEx project
 - Two channels: Channel 1 for positioning, channel 2 for neutrino detection
 - Substantially reduced power consumption
- Integrated modified sensor into an IceCube DOM
- Tested the acoustic positioning concept in water



Conclusions

- “First generation” acoustic arrays have been used to investigate neutrino detection methods and provide input for simulations
- Extension of investigations possible with KM3NeT, GVD and IceCube-Gen2



Thank you for your attention!

ecap



Bundesministerium
für Bildung
und Forschung



FRIEDRICH-ALEXANDER
UNIVERSITÄT
ERLANGEN-NÜRNBERG

Acoustic signals of neutrino interactions in water I

Thermo-acoustic effect: (Askariyan 1979)
energy deposition \Rightarrow local heating ($\sim \mu\text{K}$) \Rightarrow expansion \Rightarrow pressure signal

Wave equation for the **pressure** p for deposition of an **energy density** ε :

$$\nabla^2 p - \frac{1}{c^2} \frac{\partial^2 p}{\partial t^2} = - \frac{\alpha}{C_p} \frac{\partial^2 \varepsilon}{\partial t^2}$$

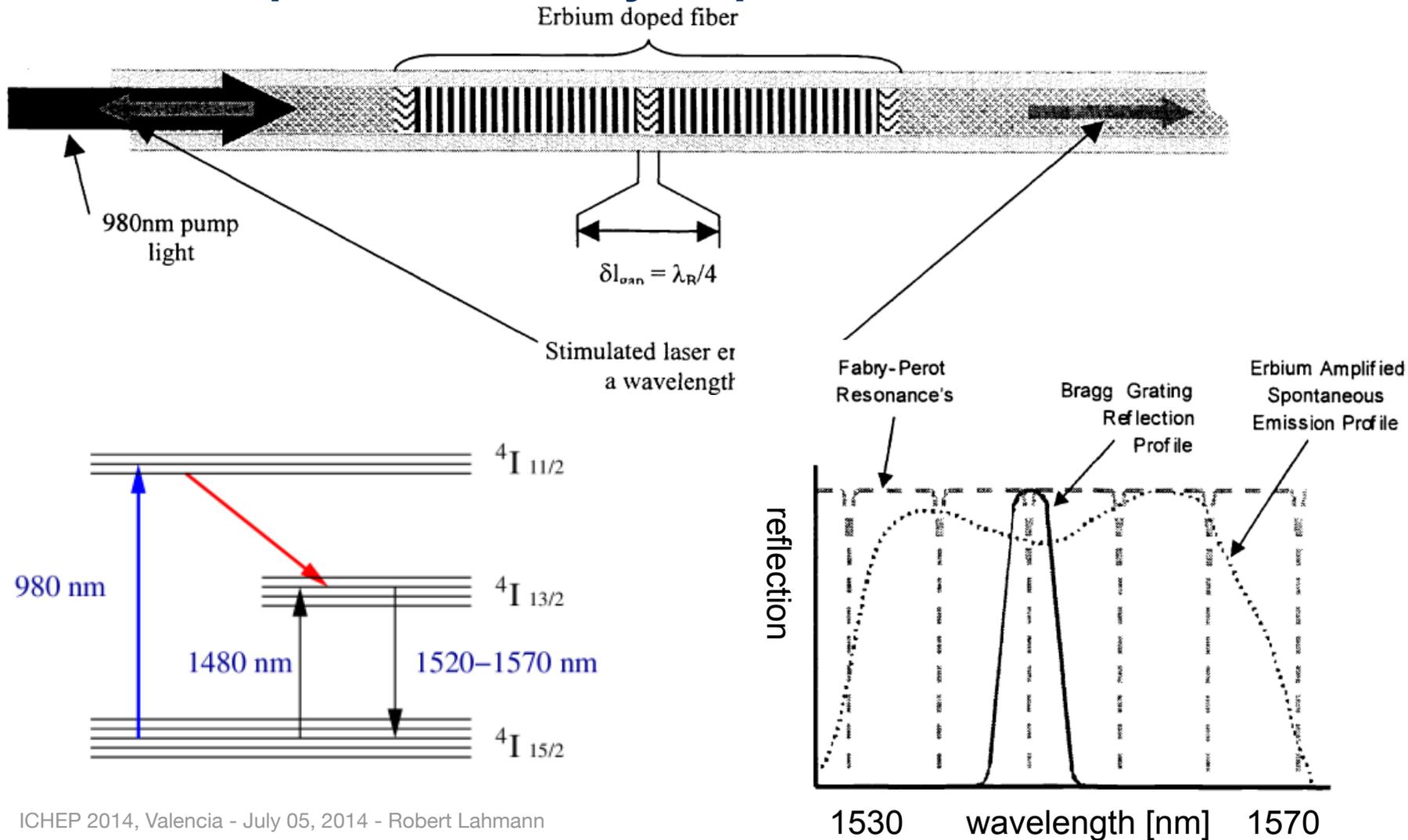
α = Volume expansion coefficient

C_p = specific heat capacity (at constant pressure)

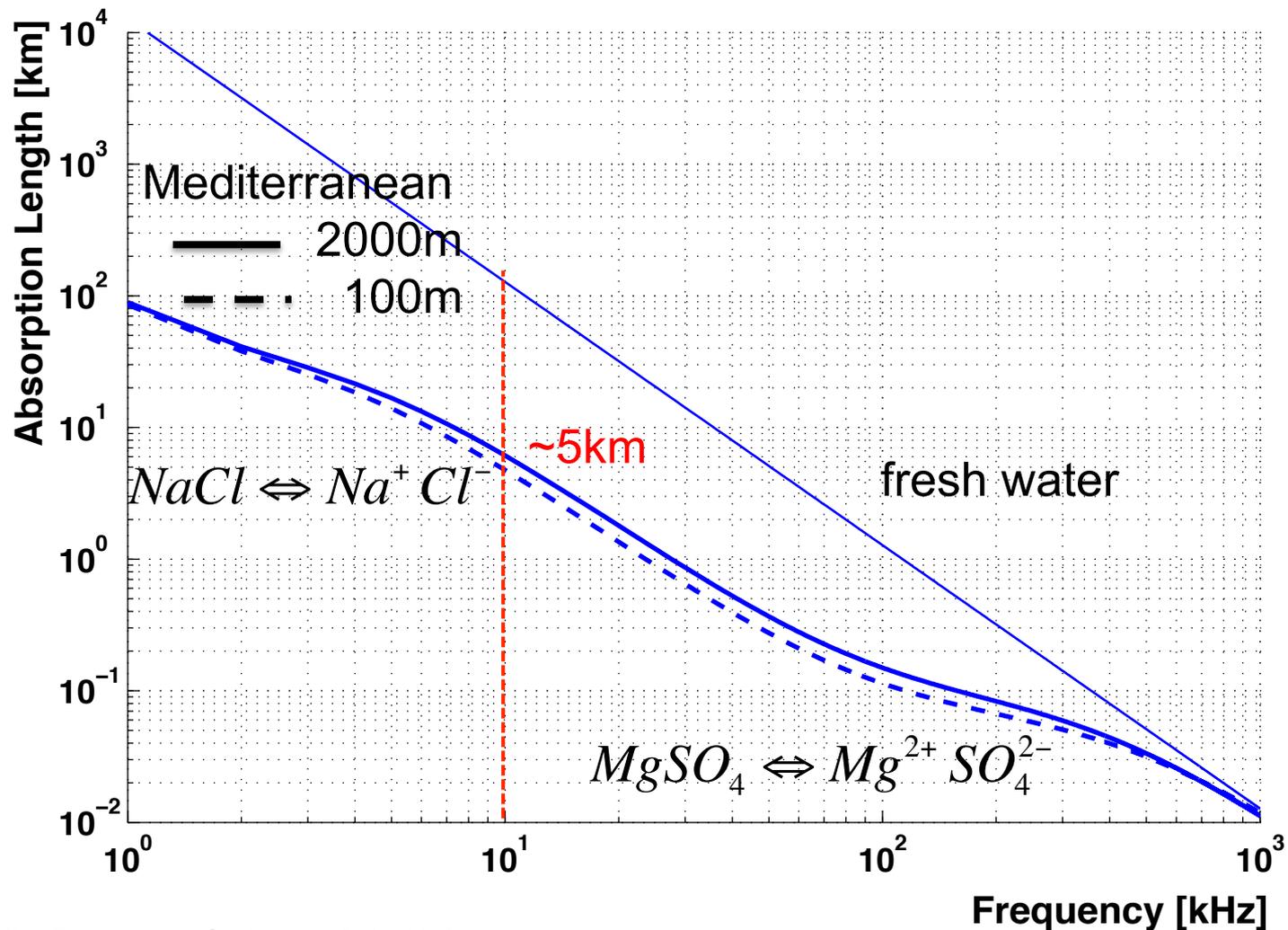
c = speed of sound in water (ca. 1500 m/s)

Solution (analytical/numerical) with assumption of an instantaneous energy deposition

Erbium doped fibers as hydrophones for KM3NeT?



Sound absorption length in water



Acoustic signals of neutrino interactions in water I

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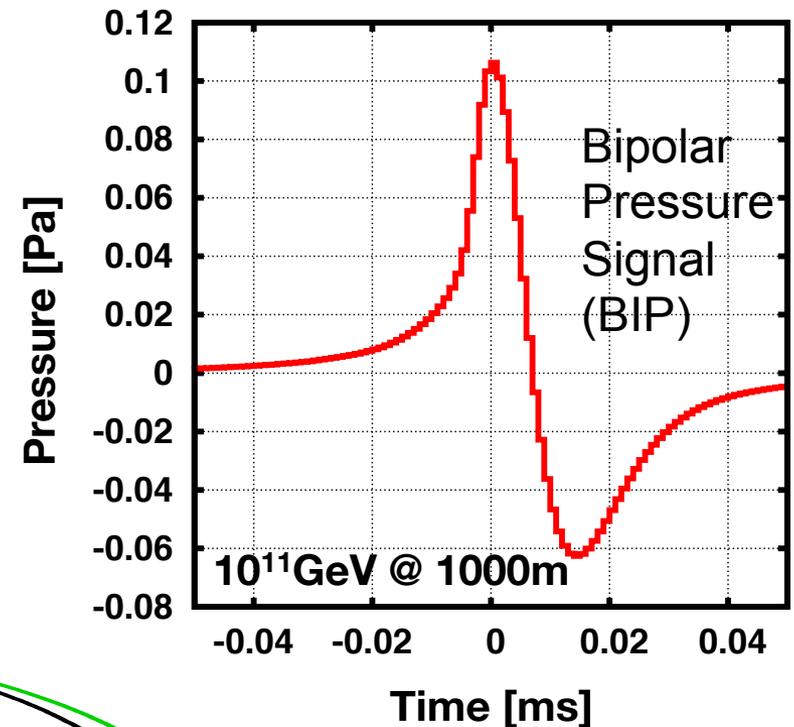
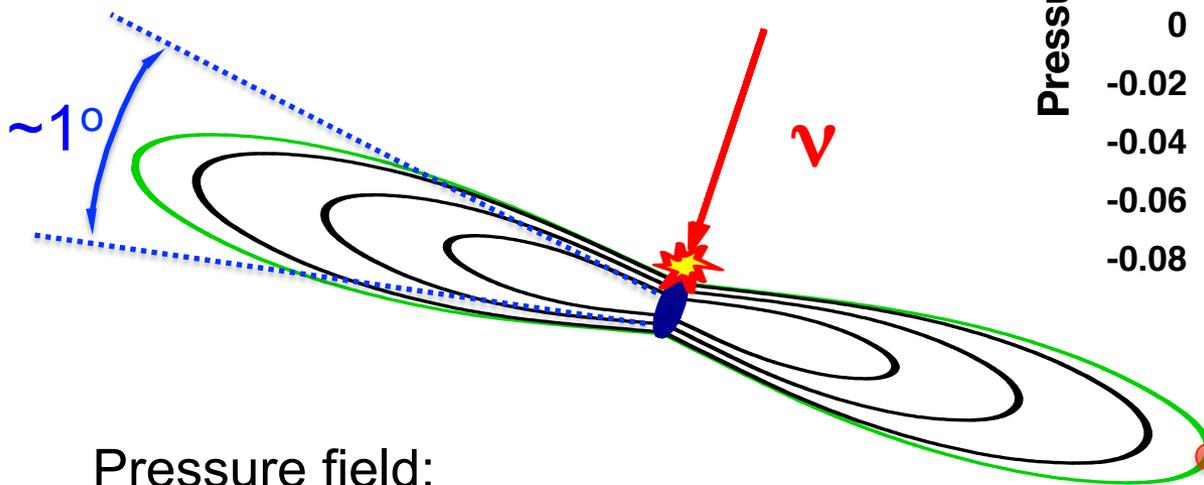
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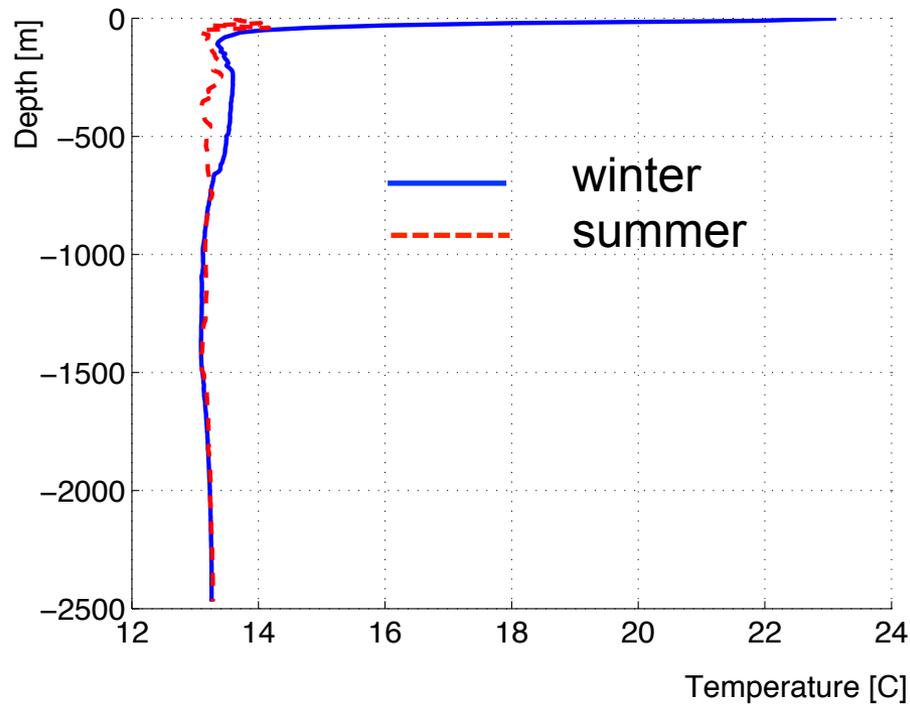
Acoustic signals of neutrino interactions in water II

Hadronic cascade:
 ~10m length, few cm radius
 (simulations by ACoRNE Coll.)

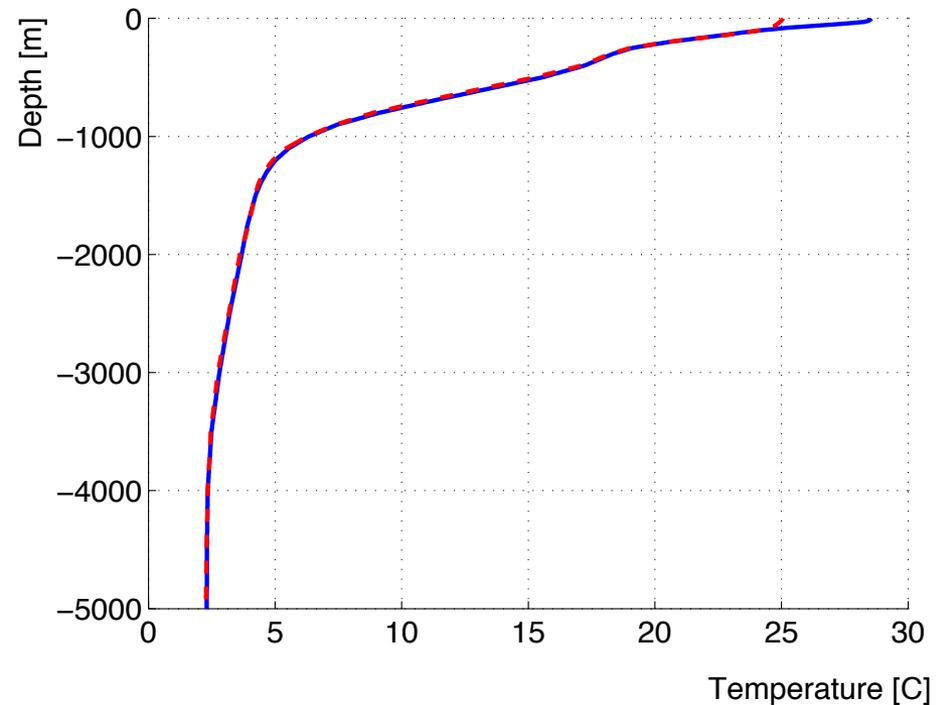


Pressure field:
 Characteristic “pancake” pattern
 Long attenuation length (~ 5 km @ 10 kHz)

Temperature profile

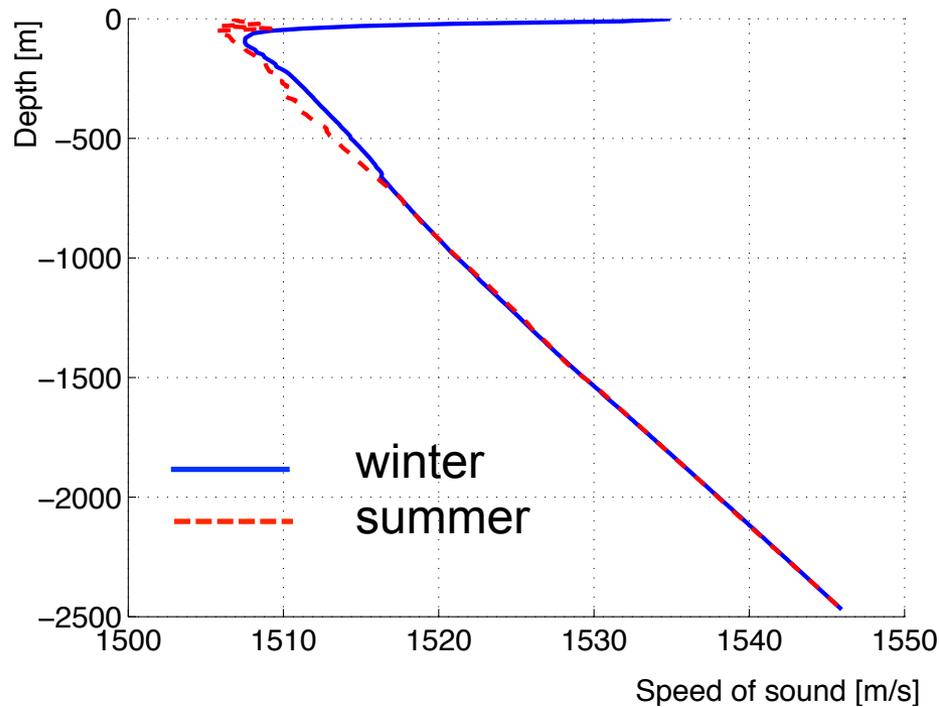


Mediterranean Sea

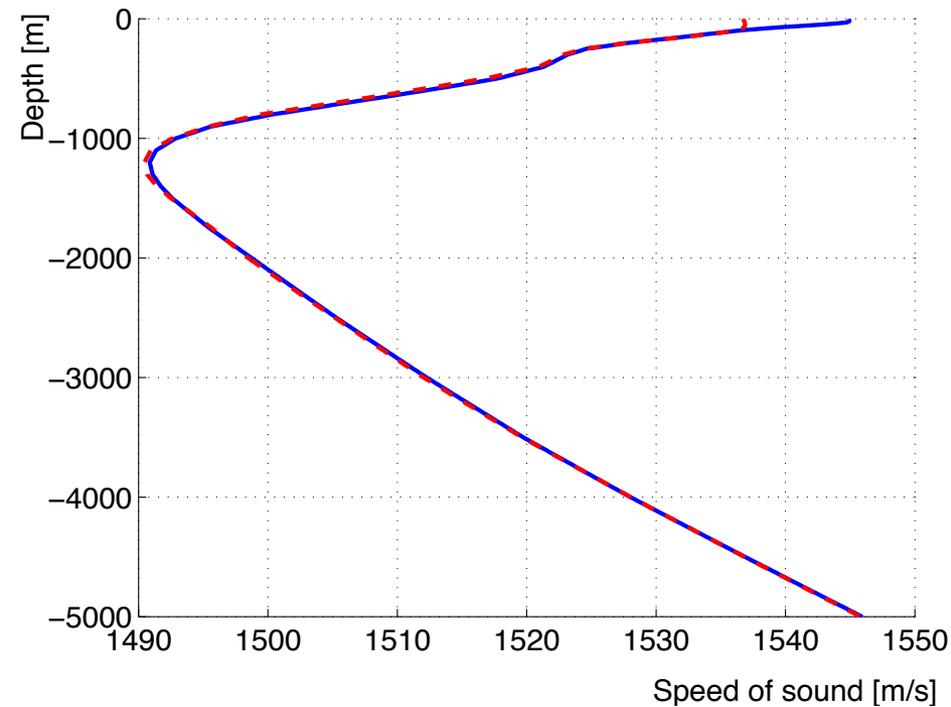


Tropical Ocean
24°30'N and 72°30'W

Speed of sound vs. depth

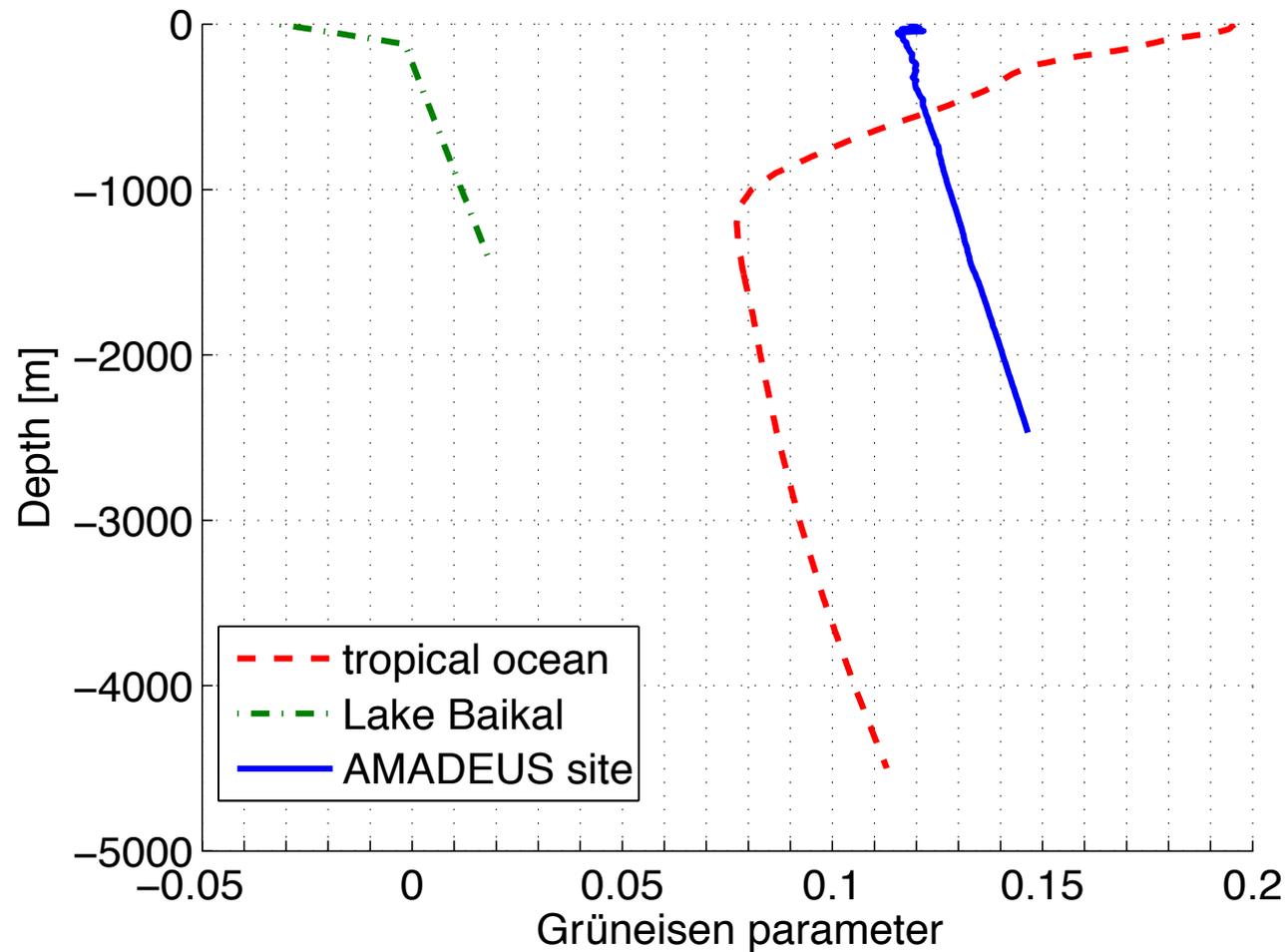


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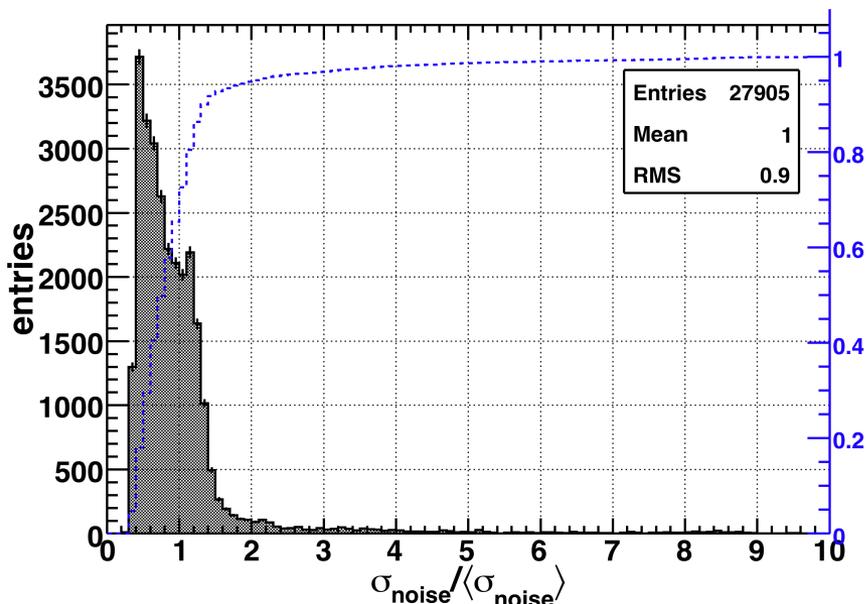
Tropical Ocean
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Grüneisen parameter



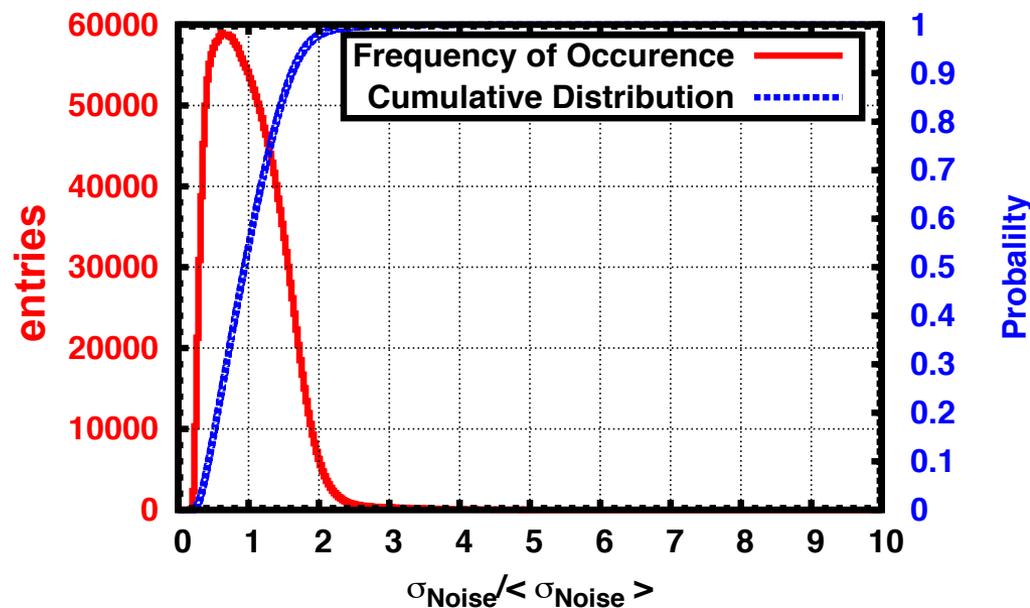
AMADEUS ambient noise

Measurement



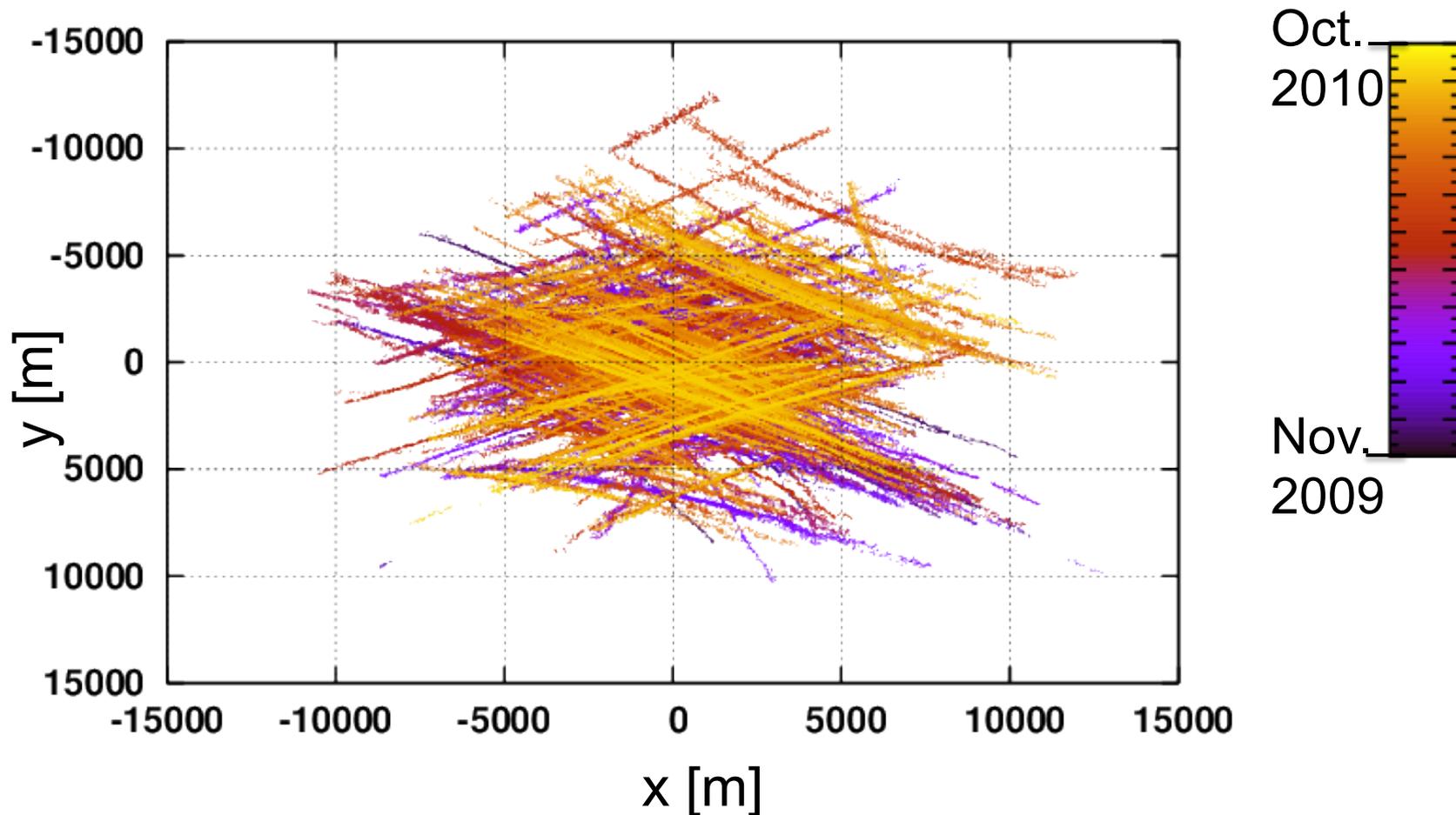
Data of 2008-2010

Simulation

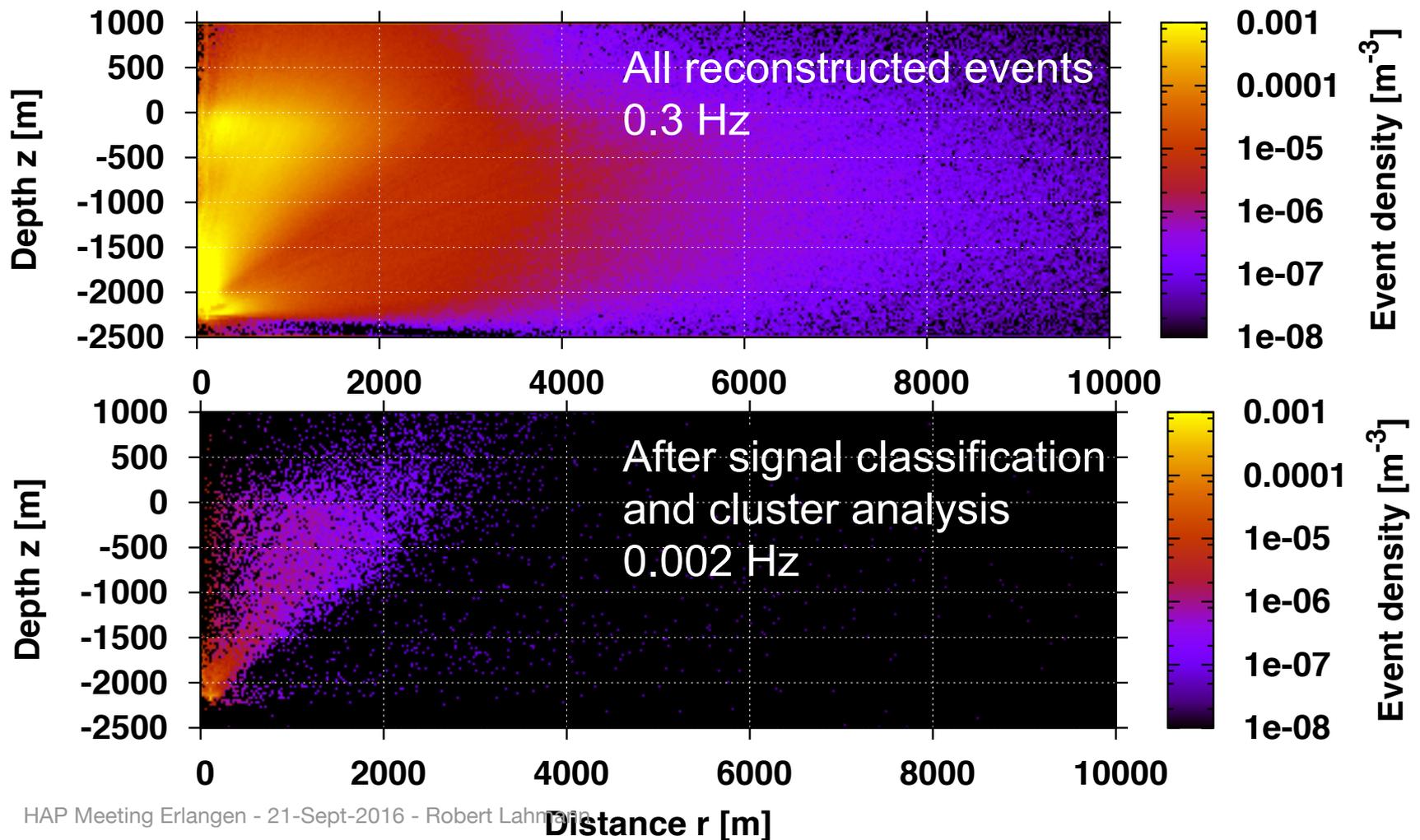


$\langle \sigma_{\text{noise}} \rangle$ is about 10 mPa (10-50 kHz) and 95% of the time below $2 \langle \sigma_{\text{noise}} \rangle$

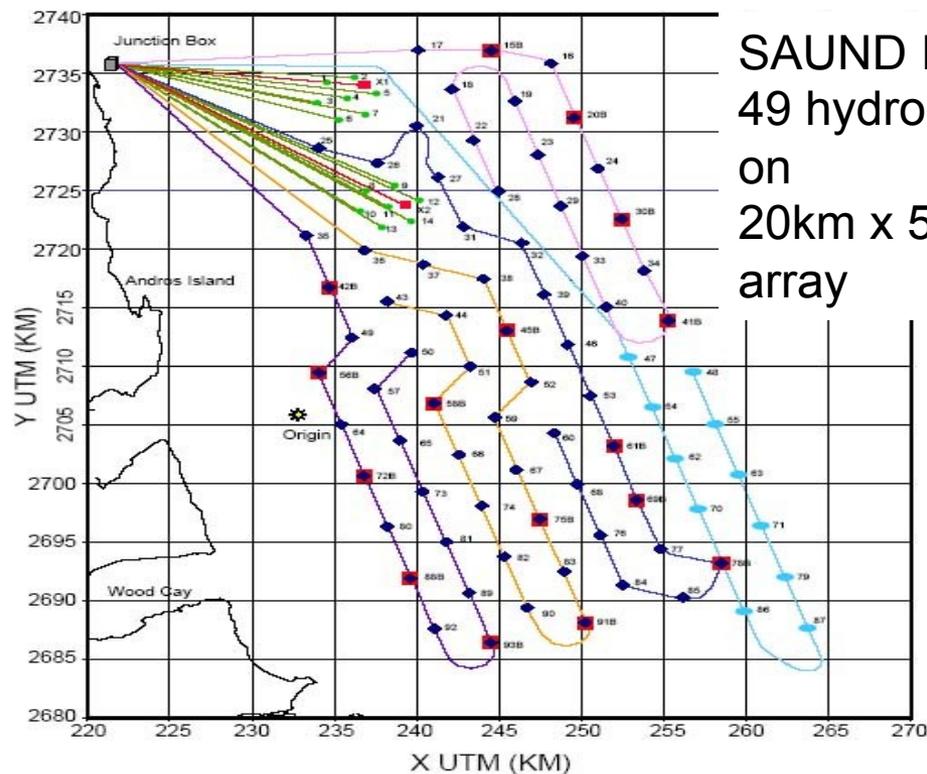
Cluster analysis of moving sound emitting objects



Spatial distribution of transient background



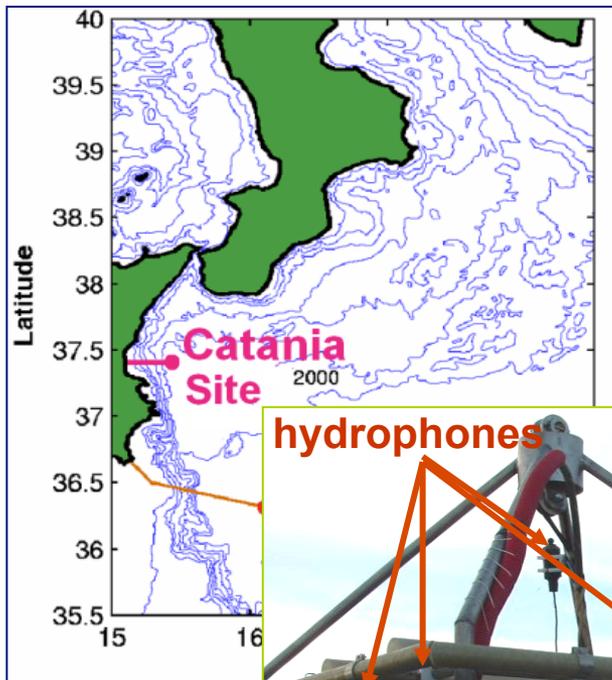
SAUND and AUTEC



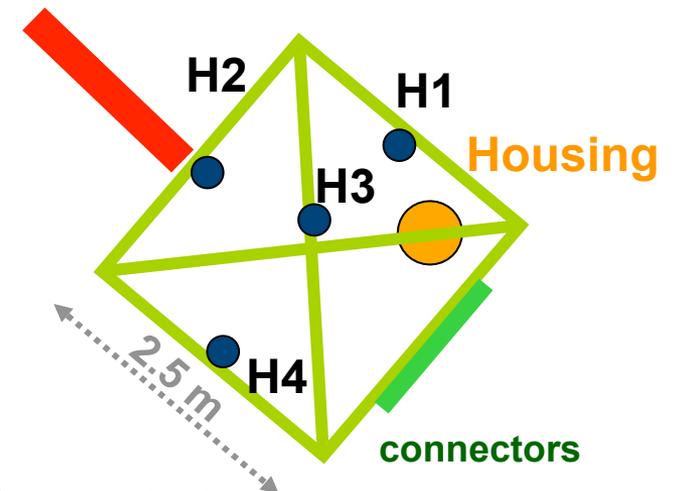
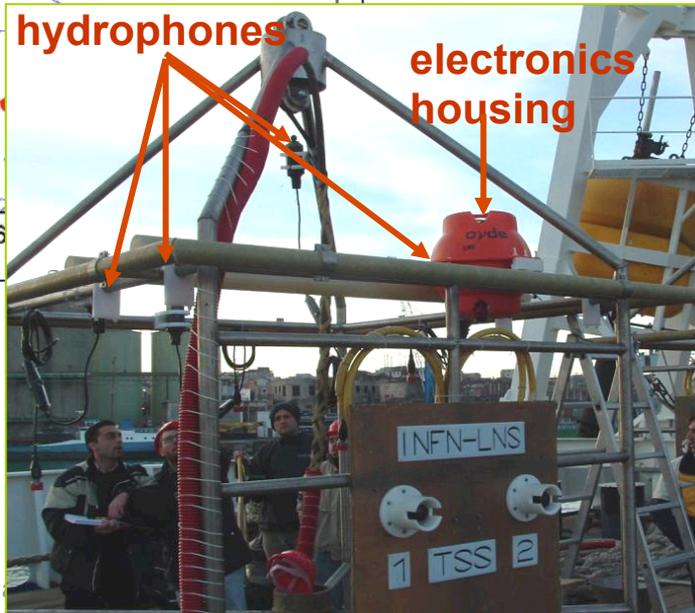
SAUND II :
 49 hydrophones
 on
 20km x 50km
 array

OnDE and KM3NeT-Italia

- Test Site at 2000 m depth, 25 km offshore Catania
- Operation of test setup OnDE (4 hydrophones) from 2005 -2006



Cable from shore



Height from seabed :

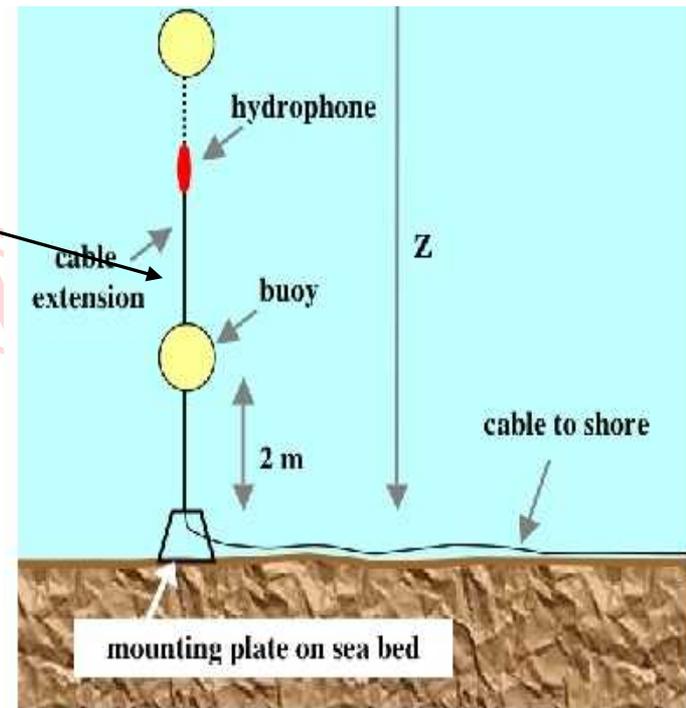
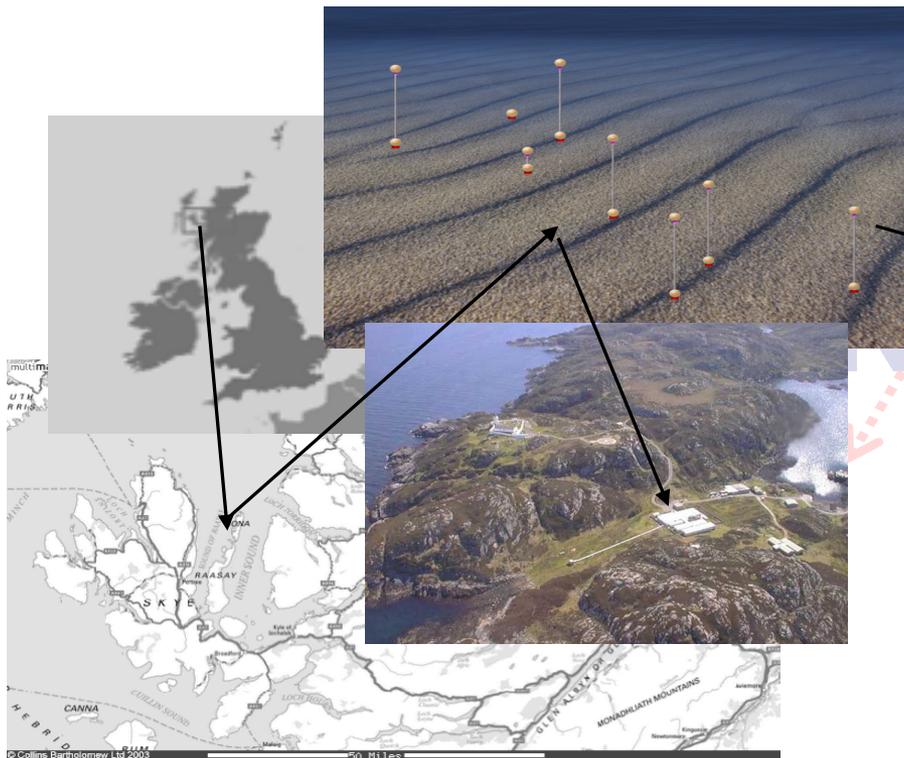
H1, H2, H4: ~ 2.6 m H3: ~ 3.2 m

KM3Net-Italia activities covered by F. Simeone

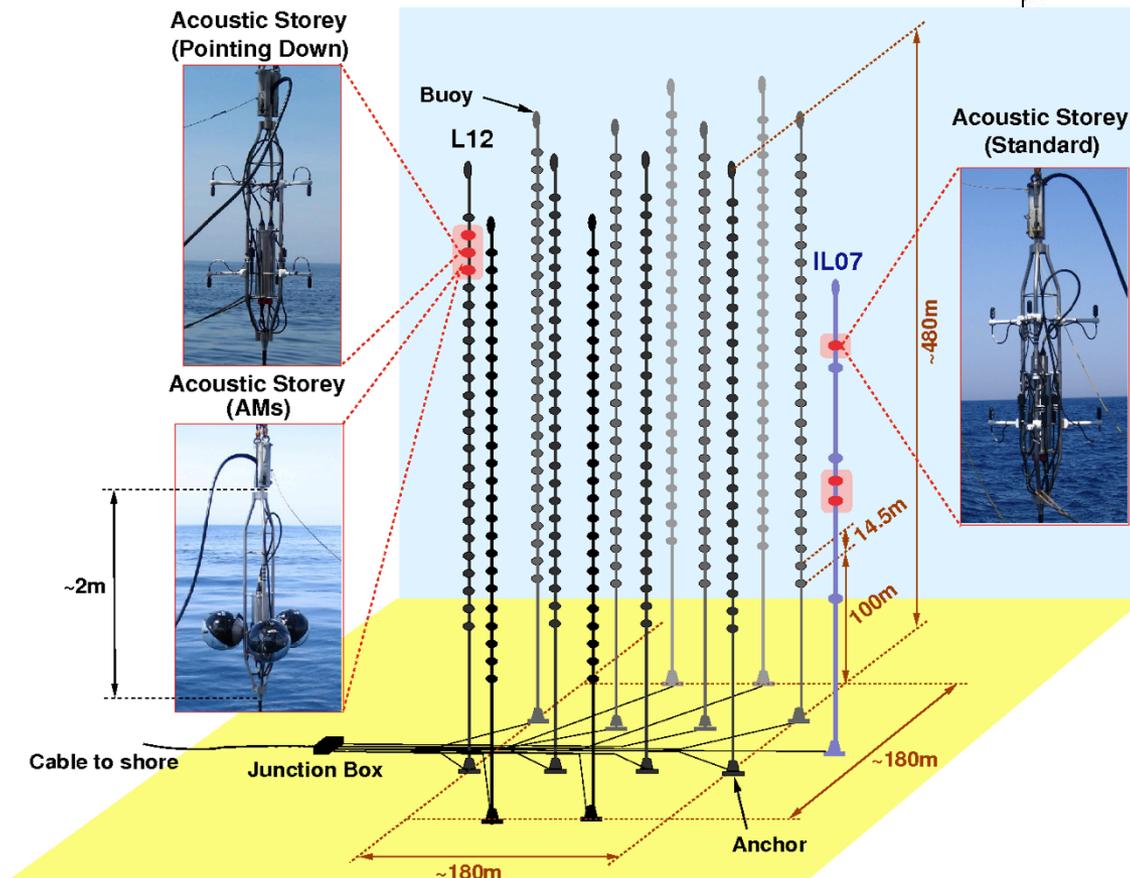
The Rona Array (ACoRNE Collaboration)

Off the Isle of Skye, 8 sensors

total cable length =
2m + cable extension + cable to shore



AMADEUS – ANTARES



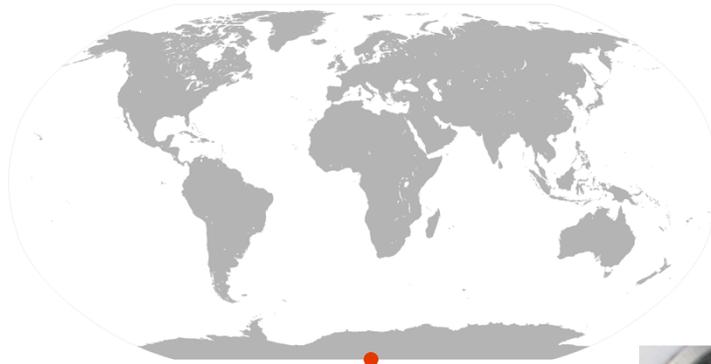
Operational 2007-15

36 acoustic sensors on
6 stories

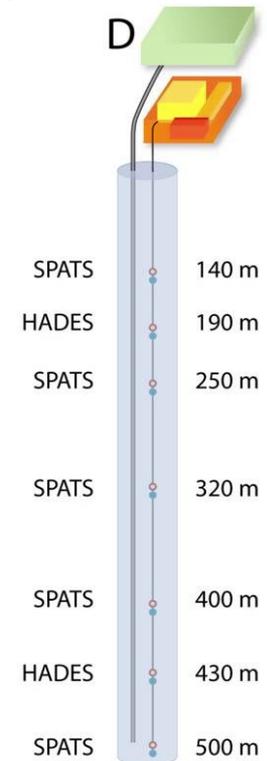
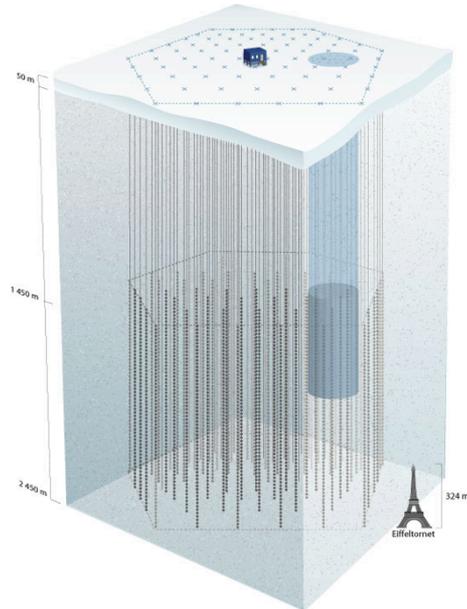
Local clusters for
direction reconstruction

Depth 2300 – 2100 m

SPATS – IceCube



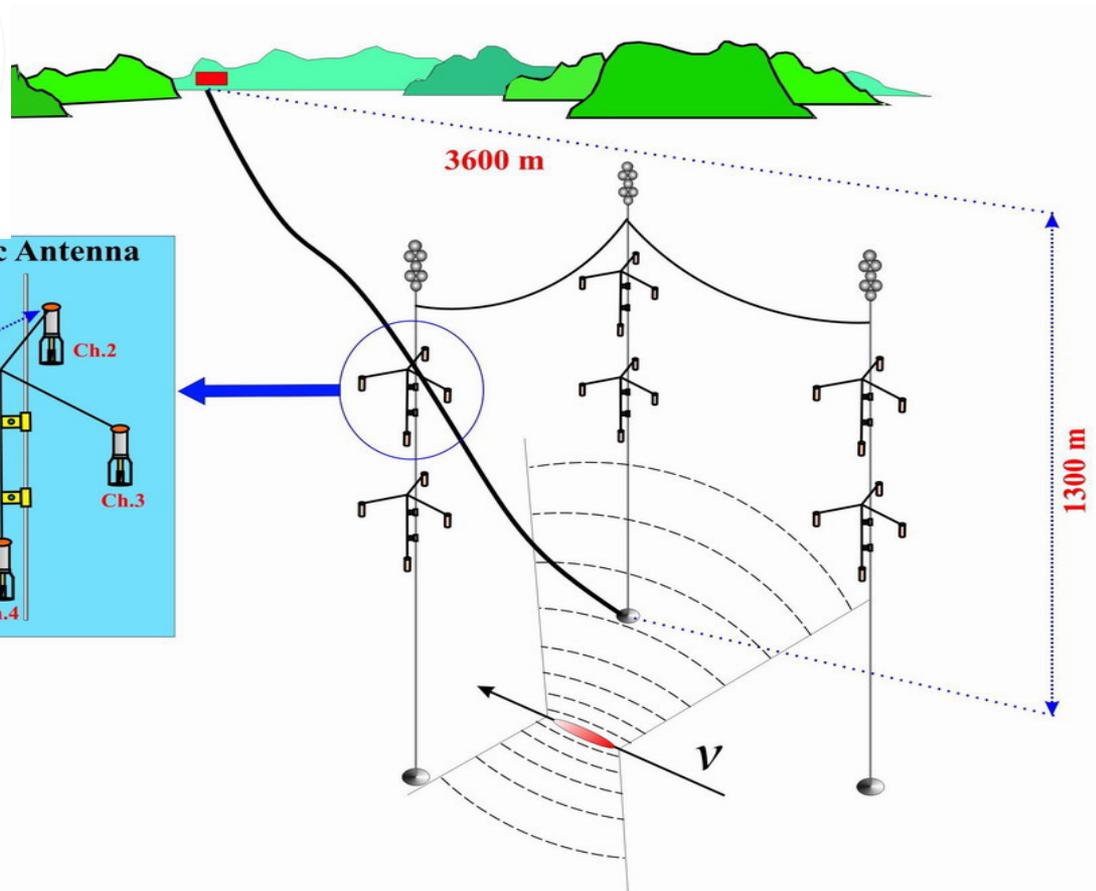
- Ice as detector medium
- 4 strings with 7 “stages” each
- A stage consists of a transmitter module and a receiver module (attenuation length measurements)
- Taking data since 2006, currently no further developments planned



Lake Baikal



- Planned: 6 tetrahedral antennae with 4 hydrophones each in >500m depth
- Currently one antenna installed



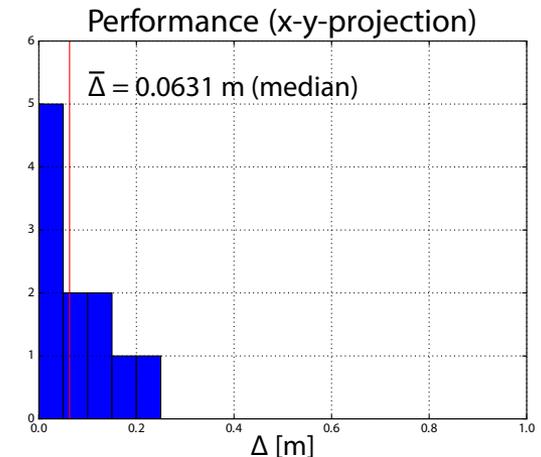
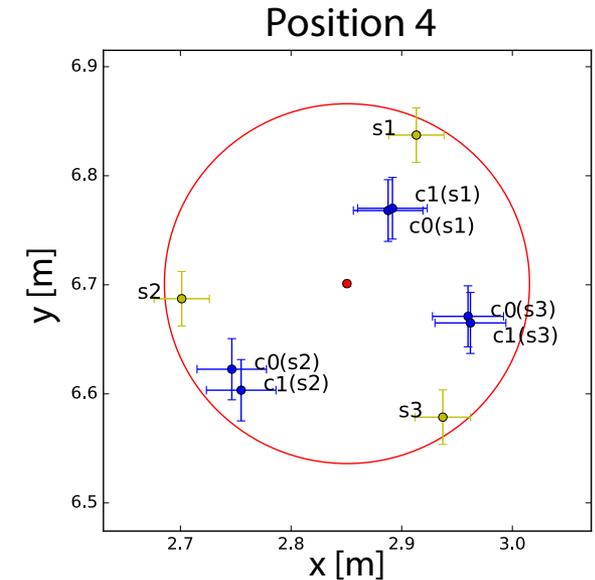
- Evaluation of the acoustic positioning concept in a swimming pool
 - 6 acoustic emitters
 - 1 Acoustic DOM (IceCube DOM with 3 acoustic sensors)
 - Acoustic positioning via trilateration
 - Compare reconstructed positions with reference
- Reconstructed positions are in good agreement with the reference positions (even without further corrections)
- Systematic errors are not yet fully understood
- Heading of the Acoustic DOM can be estimated
- Accuracy better than 7cm (x-y-plane) on average

Next steps:

- Integrate acoustic sensors into Icecube-Gen2 DOM
- Develop concept for acoustic emitters for IceCube-Gen2

S. Wickmann, master's thesis, RWTH Aachen University 2016

S. Wickmann et al., EPJ Web of Conferences, ARENA 2016 (in review)



Motivation for acoustic detection

Advantages of acoustic detection:

- long attenuation length
- simple, robust technology
- multi purpose applications

