





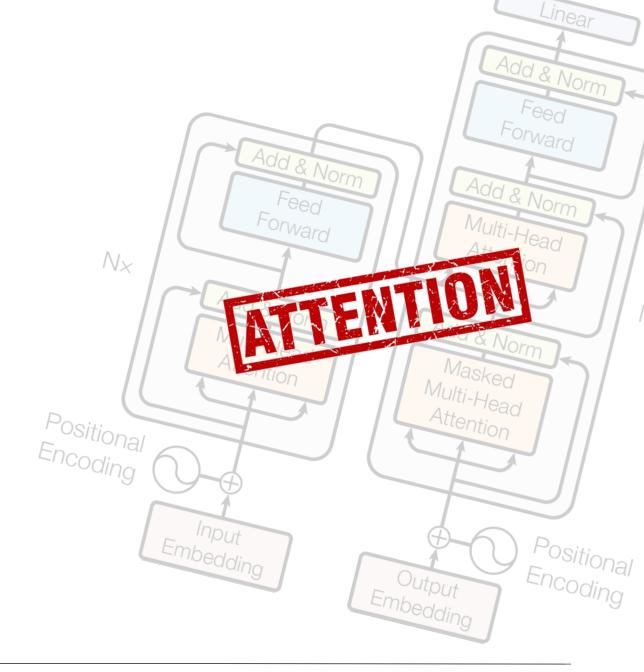
# **Transformers**

**Conceptual Advances in Deep Learning for Research on Universe and Matter** 





RWTH Aachen University



# **Current Hype: Text-to-Image Models**

#### **Text Prompt**

Photography of an Astronaut wearing a green spacesuit standing in front of the Colosseum on the moon, with a bouquet of roses in his hand

Text Analysis
(Typically *Transformer*)

Image Generation (Typically *Diffusion*)

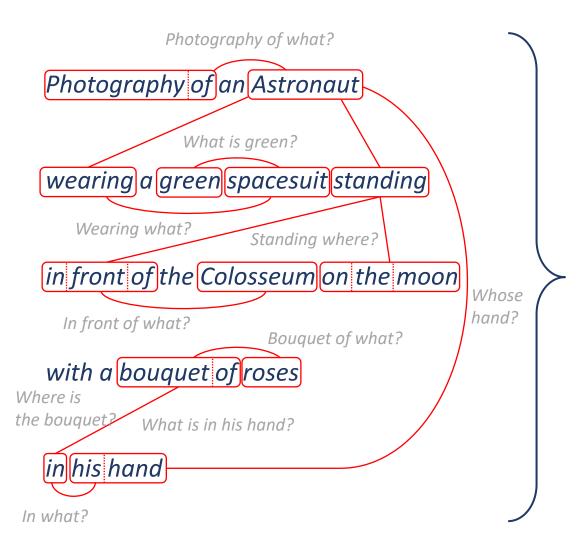
Unusual color, unusual location, unusual item

→ Network must understand prompt well!



https://arxiv.org/abs/2112.10752 https://github.com/CompVis/stable-diffusion

## **Understanding the Text Prompt**



#### **Cherry-picked examples:**

Successful generations:



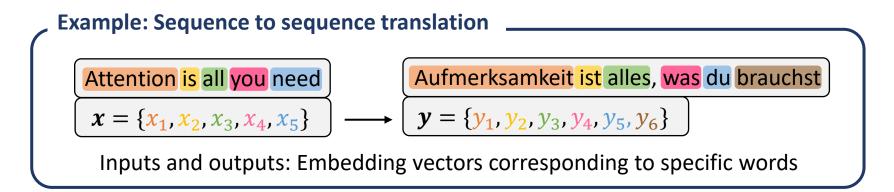
#### Misunderstandings:



https://github.com/CompVis/stable-diffusion

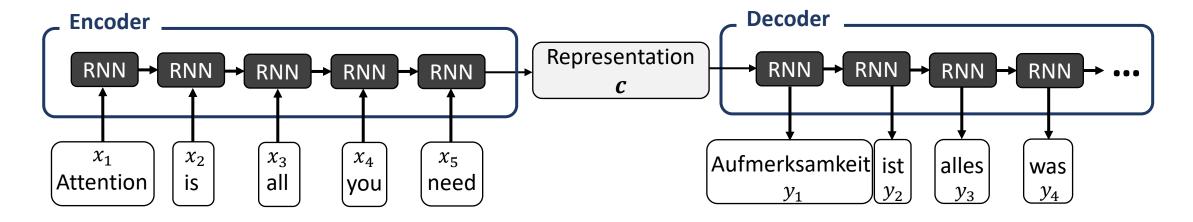
Understanding a long text is **hard**, but network (often) manages to do it  $\rightarrow$  **How does it work?** 

### **Natural Language Processing**



Before transformers: Recurrent Neural Networks ("RNNs", e.g. LSTMs)

Approach: Analyze the data **sequentially** → current step always depends on all previous steps



## **Sequential Data Processing**

Sequential analysis is helpful to understand **context**!

I like your house, **it** is great!

I like your dog, **it** is great!

I like your cat, **it** is great!

Correct translations of words can depend on **previous** or **following** words

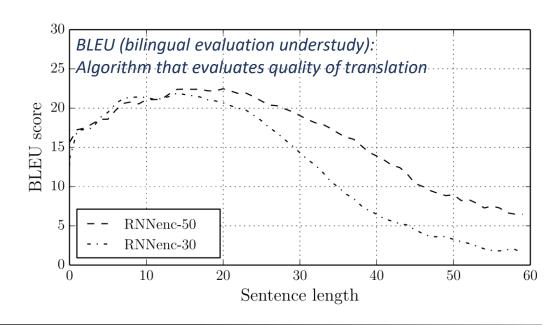
In theory: Using an RNN, current step has access to

information from all previous steps

**In practice:** Only works well for **small sequences** 

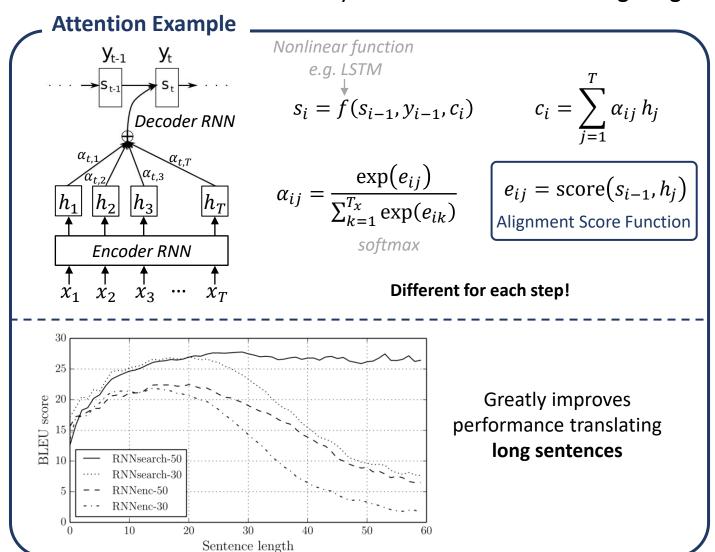
(<20 timesteps) due to too small gradients

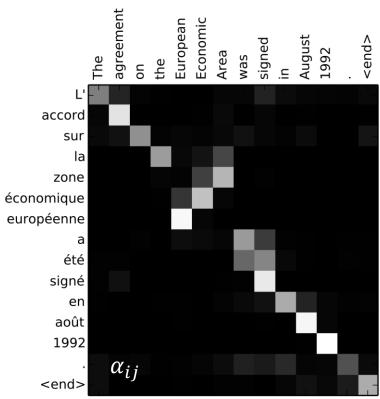
in regard to far away timesteps



### **Solution: Attention**

Use intermediate results of RNN layers and combine them using weights  $\alpha$  (alignment score)





https://arxiv.org/abs/1409.0473

### **Attention Mechanisms**

$$s_i = f(s_{i-1}, y_{i-1}, c_i)$$

$$c_i = \sum_{j=1}^T \alpha_{ij} h_j$$

$$s_i = f(s_{i-1}, y_{i-1}, c_i)$$
  $c_i = \sum_{j=1}^{T} \alpha_{ij} h_j$   $\alpha_{ij} = \frac{\exp(e_{ij})}{\sum_{k=1}^{T_x} \exp(e_{ik})}$ 

$$e_{ij} = \operatorname{score}(s_{i-1}, h_j)$$

Commonly used neural network approach

Alignment score: Many different options

| Name                   | Alignment score function  | Citation           |  |  |
|------------------------|---|--------------------|--|--|
| Content-base attention | $\mathrm{score}(s_{i-1}, h_i) = \mathrm{cos}(\theta)$ where $\theta$ is the angle between $s_{i-1}$ and $h_j$   | Graves2014         |  |  |
| Additive               | $score(s_{i-1}, h_j) = v_a^{T} \tanh(W_a[s_{i-1}; h_j])$  | Bahdanau2015       |  |  |
| Location-Based         | $lpha_{ij}=\mathrm{softmax}(W_as_i)_{\mathrm{j}}$ Note: This simplifies the softmax alignment to only depend on the target position.  | <u>Luong2015</u>   |  |  |
| General                | $\operatorname{score}(s_{i-1},h_j) = s_{i-1}^{T} W_a h_j$ where $W_a$ is a trainable weight matrix in the attention layer.  | <u>Luong2015</u>   |  |  |
| Dot-Product            | $score(s_{i-1}, h_j) = s_{i-1}^{T} h_j$   | Luong2015          |  |  |
| Scaled Dot-Product     | $score(s_{i-1},h_j) = \frac{s_{i-1}^T h_j}{\sqrt{n}}$ Note: very similar to the dot-product attention except for a scaling factor; where $n$ is the dimension of the source hidden state. | <u>Vaswani2017</u> |  |  |

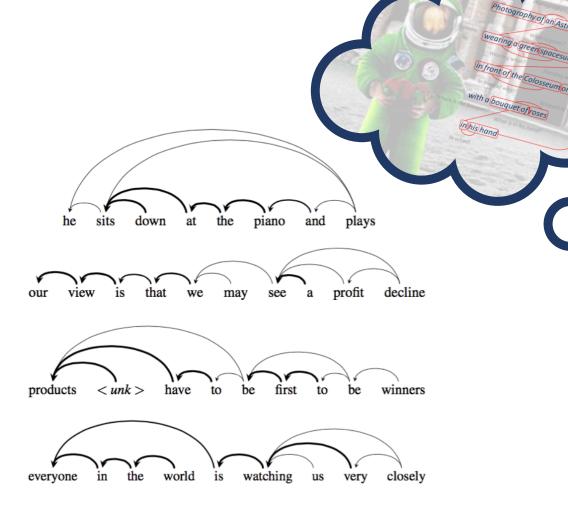
**Important for Transformer** 

https://lilianweng.github.io/posts/2018-06-24-attention/

### **Self-Attention**

Relate input **to itself** to determine **self-attention**:

```
The FBI is chasing a criminal on the run.
The FBI is chasing a criminal on the run.
     FBI is chasing a criminal on the run.
The
     FBI is chasing a criminal on the run.
The
              chasing a criminal on the run.
The
     FBI is
     FBI is
              chasing a criminal on the run.
The
The
     FBI
              chasing a criminal on the run.
          is
     FBI is
                          criminal on the run.
The
              chasing
              chasing a
                          criminal on
                                        the run.
              chasing a criminal
The
     FBI
                                        the run.
```



**Bolder** line: **Higher** attention

⇒ Adding attention mechanisms to RNNs improves the performance (especially for long sentences) and can enable interesting insights

#### **Attention Is All You Need**

Ashish Vaswani\* Google Brain

Google Brain avaswani@google.com

Noam Shazeer\*

Google Brain noam@google.com

Niki Parmar\*
Google Research

nikip@google.com

Jakob Uszkoreit\*

Google Research usz@google.com

Llion Jones\*

Google Research llion@google.com

Aidan N. Gomez\* †

University of Toronto aidan@cs.toronto.edu

Łukasz Kaiser\*

Google Brain lukaszkaiser@google.com

Illia Polosukhin\* ‡

illia.polosukhin@gmail.com

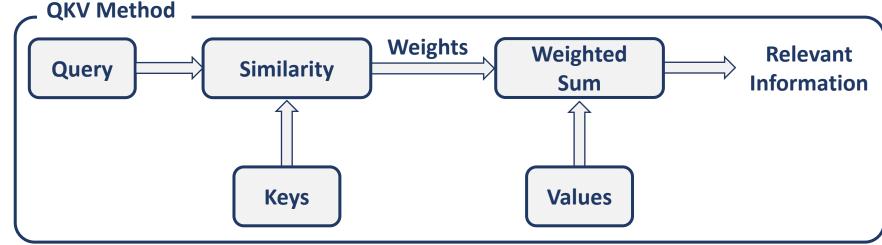
#### **Abstract**

The dominant sequence transduction models are based on complex recurrent or convolutional neural networks that include an encoder and a decoder. The best performing models also connect the encoder and decoder through an attention mechanism. We propose a new simple network architecture, the Transformer, based solely on attention mechanisms, dispensing with recurrence and convolutions entirely. Experiments on two machine translation tasks show these models to

**Introducing: The Transformer** 

#### **Transformer: Attention Mechanism**

Interpret attention as function of query Q, keys K and values V

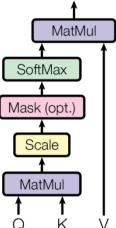


**Scaled dot-product attention:** 

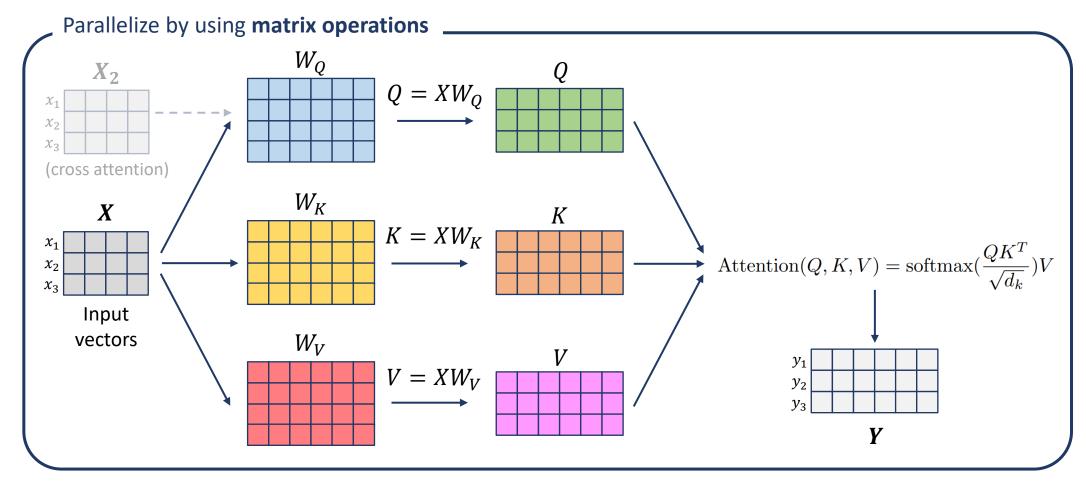
Dot-product (vector projection) as **similarity measure** 

$$score(s_{i-1}, h_j) = \frac{s_{i-1}^T h_j}{\sqrt{n}}$$
  $\longrightarrow$  Attention $(Q, K, V) = softmax(\frac{QK^T}{\sqrt{d_k}})V$ 

 $d_k$ : length of keys vector

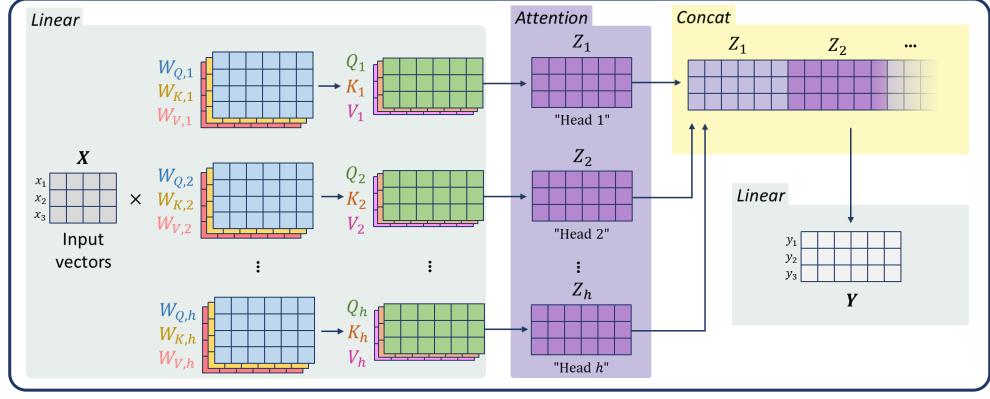


## **QKV-Self-Attention Implementation**



Here: Always use  $X \to \text{calculate self-attention}$ To relate X to different input data  $X_2$ , use  $X_2$  to calculate Q (cross attention)

#### **Multi-Head Attention**

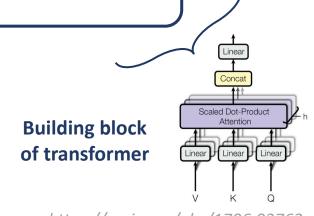


Heads are **independent** of each other!

- → Can be **trained in parallel** on multiple GPUs
- → Enables **training on huge** datasets in reasonable time

Input treated as set instead of sequence  $\rightarrow$  permutation invariant  $\ref{figure}$ 

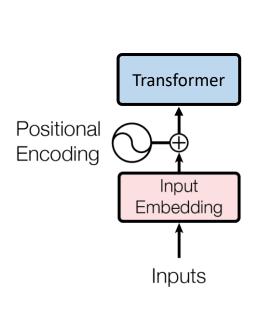
→ Use **positional encoding!** 

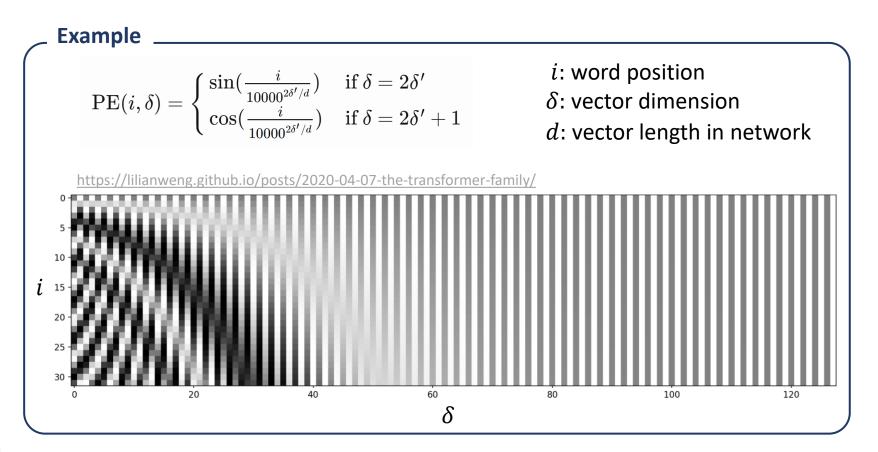


https://arxiv.org/abs/1706.03762

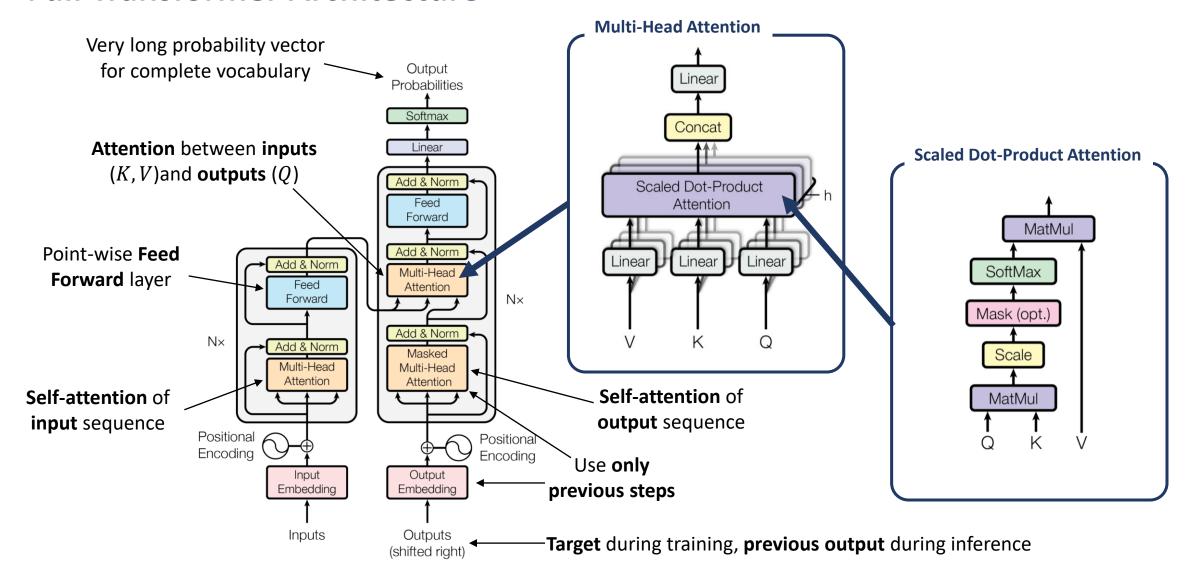
# **Positional Encoding**

Positional Encoding PE is **added to embedded vectors from inputs** to pass positional information to transformer Many different options (both **trainable** and **fixed**), paper uses **fixed encoding**:

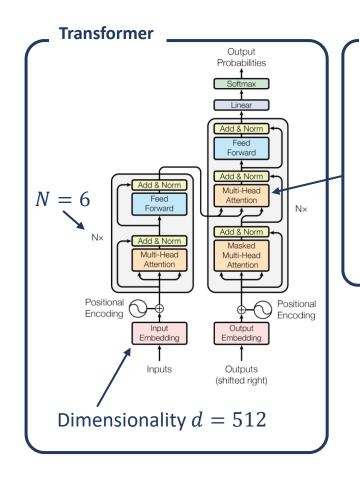




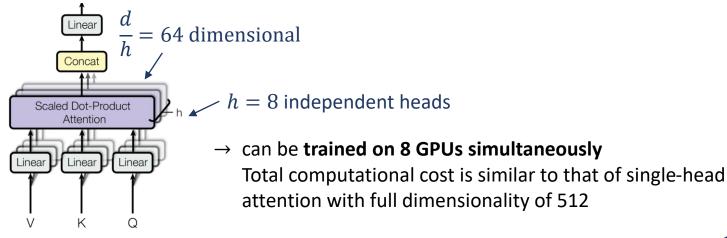
#### **Full Transformer Architecture**



### **Text Translation with Transformer**







| Model                           | BLEU  |                                 | Training Cost (FLOPs) |                     |  |
|---------------------------------|-------|---------------------------------|-----------------------|---------------------|--|
| Wodel                           | EN-DE | EN-FR                           | EN-DE                 | EN-FR               |  |
| ByteNet [18]                    | 23.75 |                                 |                       |                     |  |
| Deep-Att + PosUnk [39]          |       | 39.2                            |                       | $1.0 \cdot 10^{20}$ |  |
| GNMT + RL [38]                  | 24.6  | 39.92                           | $2.3 \cdot 10^{19}$   | $1.4 \cdot 10^{20}$ |  |
| ConvS2S [9]                     | 25.16 | 40.46                           | $9.6 \cdot 10^{18}$   | $1.5 \cdot 10^{20}$ |  |
| MoE [32]                        | 26.03 | 40.56                           | $2.0\cdot 10^{19}$    | $1.2\cdot 10^{20}$  |  |
| Deep-Att + PosUnk Ensemble [39] |       | 40.4                            |                       | $8.0 \cdot 10^{20}$ |  |
| GNMT + RL Ensemble [38]         | 26.30 | 41.16                           | $1.8 \cdot 10^{20}$   | $1.1 \cdot 10^{21}$ |  |
| ConvS2S Ensemble [9]            | 26.36 | 41.29                           | $7.7\cdot10^{19}$     | $1.2 \cdot 10^{21}$ |  |
| Transformer (base model)        | 27.3  | 38.1                            |                       | $10^{18}$           |  |
| Transformer (big)               | 28.4  | <b>41.8</b> $2.3 \cdot 10^{19}$ |                       | $10^{19}$           |  |

## **Impact of Transformers – Language Processing**



|   | Rank | Name                                | Model  | URL      | Score |
|---|------|-------------------------------------|--|----------|-------|
|   | 1    | JDExplore d-team                    | Vega v1 (Could not find architecture, but likely transformer | rs)      | 91.3  |
|   | 2    | Microsoft Alexander v-team          | Turing NLR v5  | <b>₫</b> | 91.2  |
|   | 3    | DIRL Team                           | DeBERTa + CLEVER   |          | 91.1  |
|   | 4    | ERNIE Team - Baidu                  | ERNIE  | <b>₫</b> | 91.1  |
|   | 5    | AliceMind & DIRL                    | StructBERT + CLEVER  |          | 91.0  |
|   | 6    | DeBERTa Team - Microsoft            | DeBERTa / TuringNLRv4  | <b>₫</b> | 90.8  |
|   | 7    | HFL iFLYTEK                         | MacALBERT + DKM All using transfo                            | rmers    | 90.7  |
| + | 8    | PING-AN Omni-Sinitic                | ALBERT + DAAF + NAS  |          | 90.6  |
|   | 9    | T5 Team - Google                    | T5   | <b>₫</b> | 90.3  |
|   | 10   | Microsoft D365 AI & MSR AI & GATECH | MT-DNN-SMART   | <b>₫</b> | 89.9  |
| + | 11   | Huawei Noah's Ark Lab               | NEZHA-Large  |          | 89.8  |
| + | 12   | Zihang Dai                          | Funnel-Transformer (Ensemble B10-10-10H1024)                 | <b>₫</b> | 89.7  |
|   |      |                                     |  |          |       |
|   | 21   | GLUE Human Baselines                | GLUE Human Baselines   | <b>Z</b> | 87.1  |
|   |      |                                     | 0<br>0<br>0  |          |       |
|   | 75   | GLUE Baselines                      | BiLSTM+ELMo+Attn   |          | 70.0  |
|   |      |                                     |  |          |       |

Transformers beat LSTMs/Recurrent Neural Networks as state of the art in natural language processing!

Huge transformer models are widely-used for language processing:

- Google BERT (340 Million parameters)
- Google T5
   (11 billion parameters)
- OpenAl GPT-3 (175 billion parameters)
- Microsoft Megatron-Turing NLG (530 billion parameters)
- → Models using more than one **trillion** parameters are already tested

## **Transformer for Language Processing - Overview**

- Transformers: Use attention-mechanism to analyze data → Relevance between different inputs
- Positional Encoding enables the analysis of sequences
  - → Ability to understand **long and complicated** texts
    - Transformers replaced RNNs as state-of-the-art methods for natural language processing

#### **Enabled new applications:**

#### Generating large texts

A robot wrote this entire article. Are you scared yet, human? *GPT-3* 

We asked GPT-3, OpenAI's powerful new language generator, to write an essay for us from scratch. The assignment? To convince us robots come in peace

#### Writing code

Your Al pair programmer

GitHub Copilot uses the OpenAl Codex to suggest code and entire functions in real-time, right from your editor.

#### **Understanding complex prompts**



#### **Conversational models**

Hi! I am Mount Everest. What would you like to know about me?



Why do people climb you?

Some people want to show others they could do it, others enjoy the hike and the scenery, and then some people just want to see the world.



Who was the first?

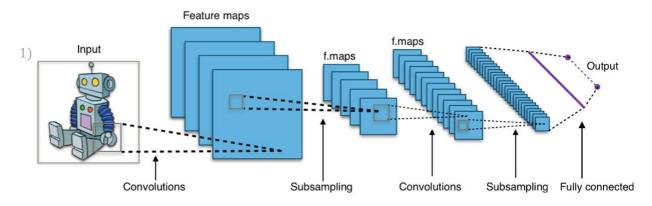
Sir Edmund Hillary and Tenzing Norgay from Nepal were the first to summit Mount Everest in May 1953. They were joined by several others at different times in the successful attempt.



...and many more

## **Image Recognition**

Previous state of the art in image recognition: Convolutional Neural Networks



- Learned filters that are used to scan images for features
- Inherently uses the **symmetries of 2D images**, i.e. which pixels are neighbors, where does the image end, etc.
- However: Can be computationally demanding

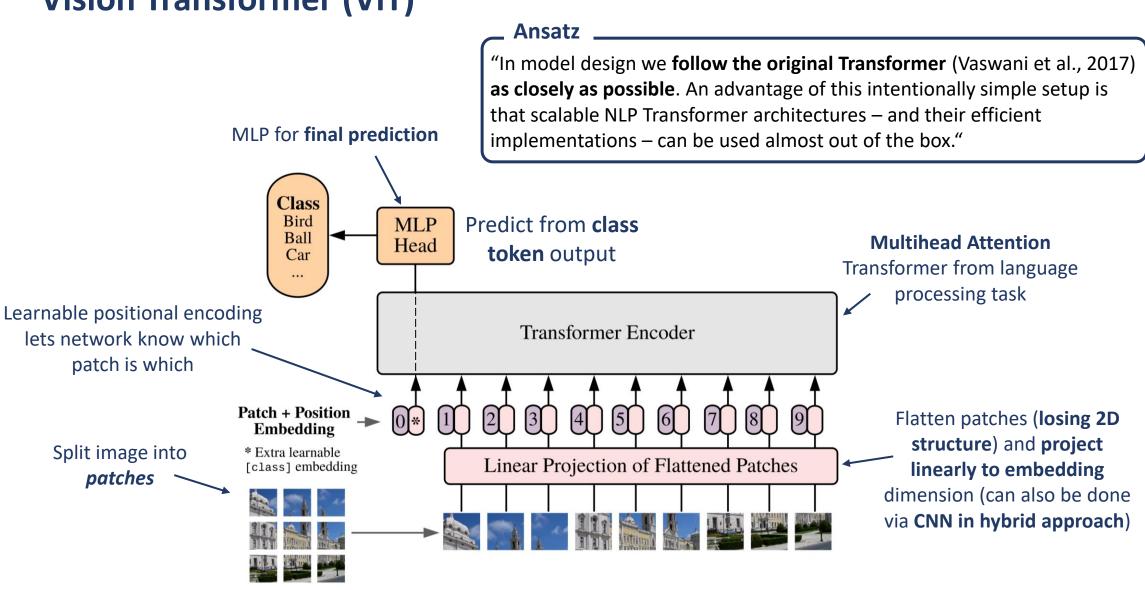
"Looking forward to the next generation of **scalable vision models**, one might ask whether this domain-specific design is necessary, or if one could successfully leverage **more domain agnostic and computationally efficient architectures** to achieve state-of-the-art results."

https://ai.googleblog.com/2020/12/transformers-for-image-recognition-at.html

#### ⇒ Vision Transformer

https://commons.wikimedia.org/wiki/File:Typical\_cnn.png

# **Vision Transformer (ViT)**



#### **Vision Transformer Performance**

| Model     | Layers | ${\it Hidden size } D$ | MLP size | Heads | Params |
|-----------|--------|------------------------|----------|-------|--------|
| ViT-Base  | 12     | 768                    | 3072     | 12    | 86M    |
| ViT-Large | 24     | 1024                   | 4096     | 16    | 307M   |
| ViT-Huge  | 32     | 1280                   | 5120     | 16    | 632M   |

|                    |                        | Transformers           |                         | CIVIVS                 |                                   |  |
|--------------------|------------------------|------------------------|-------------------------|------------------------|-----------------------------------|--|
|                    | Ours-JFT<br>(ViT-H/14) | Ours-JFT<br>(ViT-L/16) | Ours-I21k<br>(ViT-L/16) | BiT-L<br>(ResNet152x4) | Noisy Student<br>(EfficientNet-L. |  |
| ImageNet           | $88.55 \pm 0.04$       | $87.76 \pm 0.03$       | $85.30 \pm 0.02$        | $87.54 \pm 0.02$       | 88.4/88.5*                        |  |
| ImageNet ReaL      | $90.72 \pm 0.05$       | $90.54 \pm 0.03$       | $88.62 \pm 0.05$        | 90.54                  | 90.55                             |  |
| CIFAR-10           | $99.50 \pm 0.06$       | $99.42 \pm 0.03$       | $99.15 \pm 0.03$        | $99.37 \pm 0.06$       | _                                 |  |
| CIFAR-100          | $94.55 \pm 0.04$       | $93.90 \pm 0.05$       | $93.25 \pm 0.05$        | $93.51 \pm 0.08$       | _                                 |  |
| Oxford-IIIT Pets   | $97.56 \pm 0.03$       | $97.32 \pm 0.11$       | $94.67 \pm 0.15$        | $96.62 \pm 0.23$       | _                                 |  |
| Oxford Flowers-102 | $99.68 \pm 0.02$       | $99.74 \pm 0.00$       | $99.61 \pm 0.02$        | $99.63 \pm 0.03$       | _                                 |  |
| VTAB (19 tasks)    | $77.63 \pm 0.23$       | $76.28 \pm 0.46$       | $72.72 \pm 0.21$        | $76.29 \pm 1.70$       | _                                 |  |
| TPUv3-core-days    | 2.5k                   | 0.68k                  | 0.23k                   | 9.9k                   | 12.3k                             |  |

Transformers

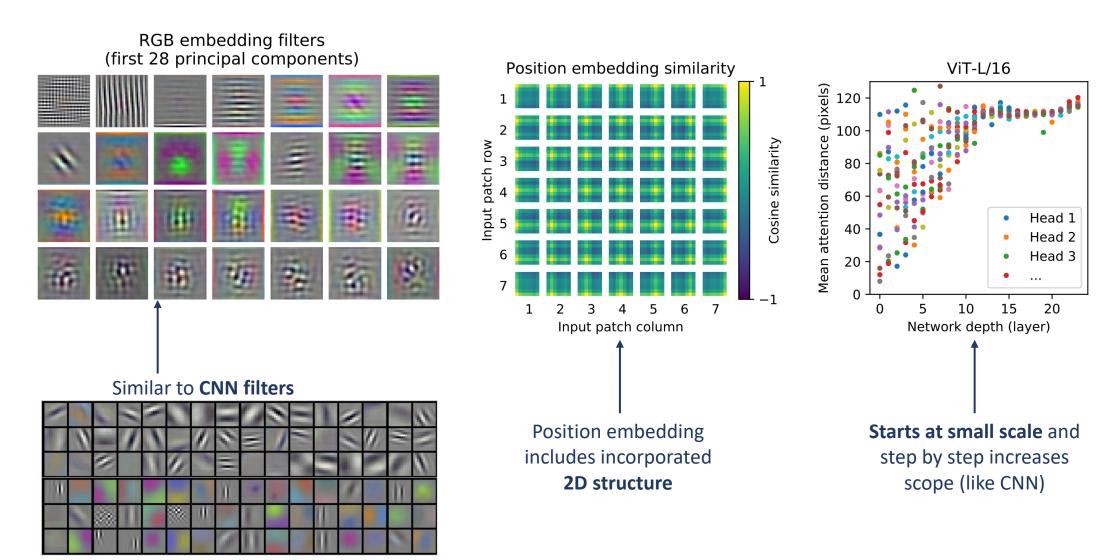
Transformer: More efficient

"ViT performs **significantly worse** than the CNN equivalent (BiT) when **trained on ImageNet** (1M images). However, on **ImageNet-21k** (14M images) performance is **comparable**, and on **JFT** (300M images), **ViT now outperforms BiT**."

⇒ Vision Transformer already outperforms (highly-optimized) CNNs, despite using architecture created for language processing

CNNs

# **Vision Transformer Insight**



https://papers.nips.cc/paper/2012/file/c399862d3b9d6b76c8436e924a68c45b-Paper.pdf

https://arxiv.org/abs/2010.11929

# **Vision Transformer Insight**

Input

Attention













**Global** self-attention, in contrast to local filters of CNN

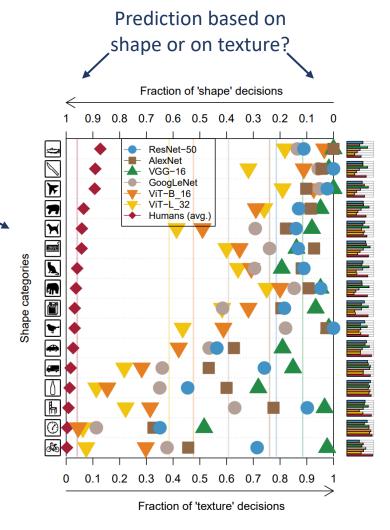
Shape = Cat, Texture = Elephant





Are Vision Transformers more similar to human vision than CNNs?

Ongoing research...

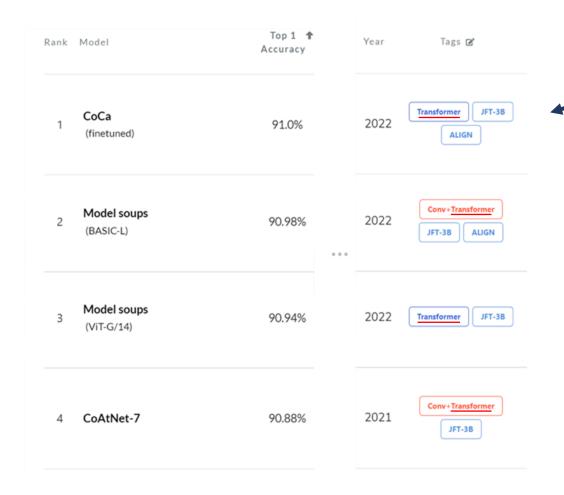


https://arxiv.org/abs/2010.11929

https://arxiv.org/abs/2105.07197

## **ImageNet Leaderboard**

Image Classification on ImageNet:

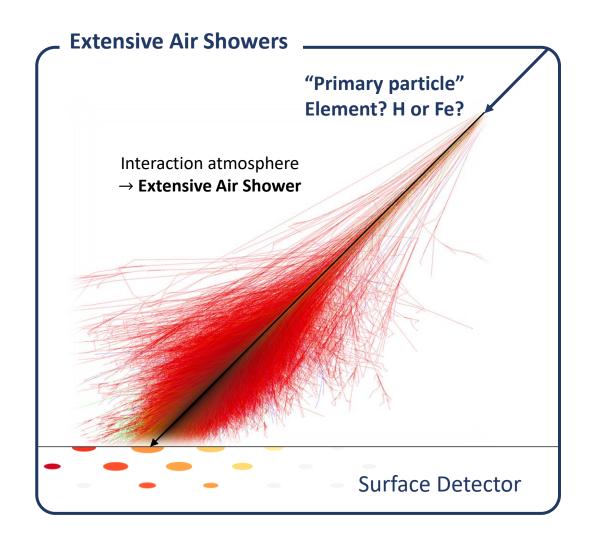


CoCa "Contrastive Captioners are Image-Text Foundation Models" **Captioning Loss** Cross-Attention Multimodal Text Decoder classification **Contrastive Loss** Unimodal Image Image Encoder Text Decoder Encoder image image text Visual Recognition CoCa (single-encoder models) "These results suggest the proposed framework efficiently combines text training signals and thus is able to learn high-quality visual representation better than the classical single-encoder approach." https://arxiv.org/abs/2205.01917

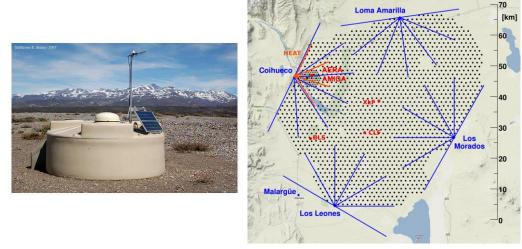
Transformers beat CNNs as state of the art in image recognition!

https://paperswithcode.com/sota/image-classification-on-imagenet

#### **Application Example: Cosmic-Ray Element Reconstruction at Pierre Auger Observatory**

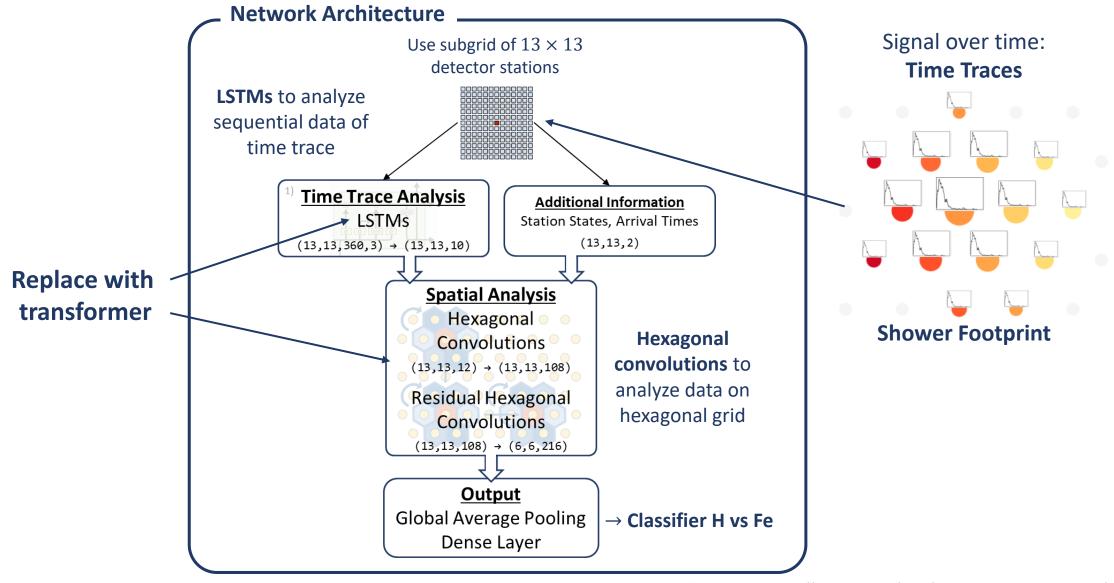


#### **Pierre Auger Observatory Surface Detector**

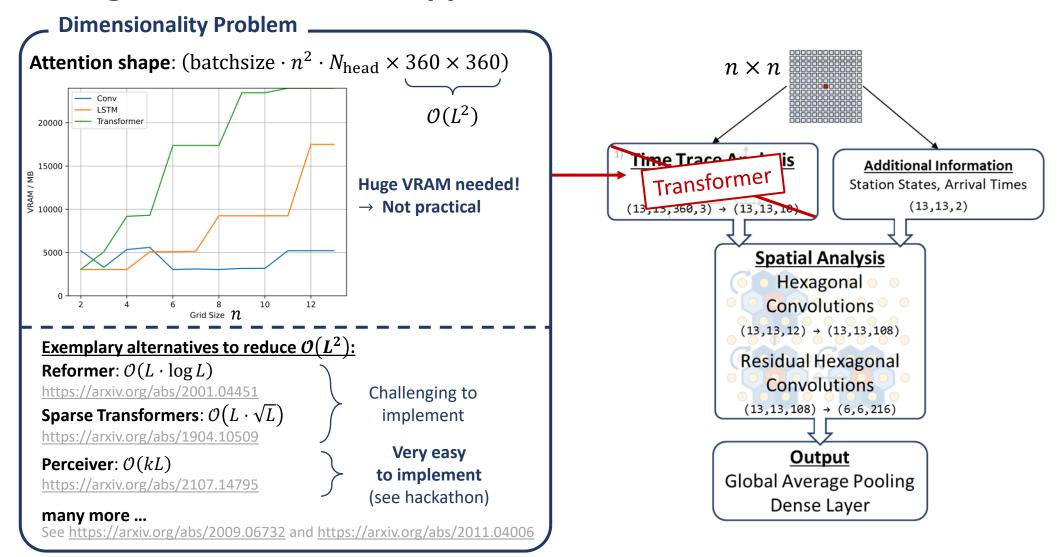


- Located in the *Pampa Amarilla* near Malargüe, Argentina
- Covers an area of roughly 3000 km<sup>2</sup>
- Hexagonal grid of 1660 water-Cherenkov stations
- Sample air shower footprint

## **Cosmic-Ray Mass Reconstruction Neural Network**

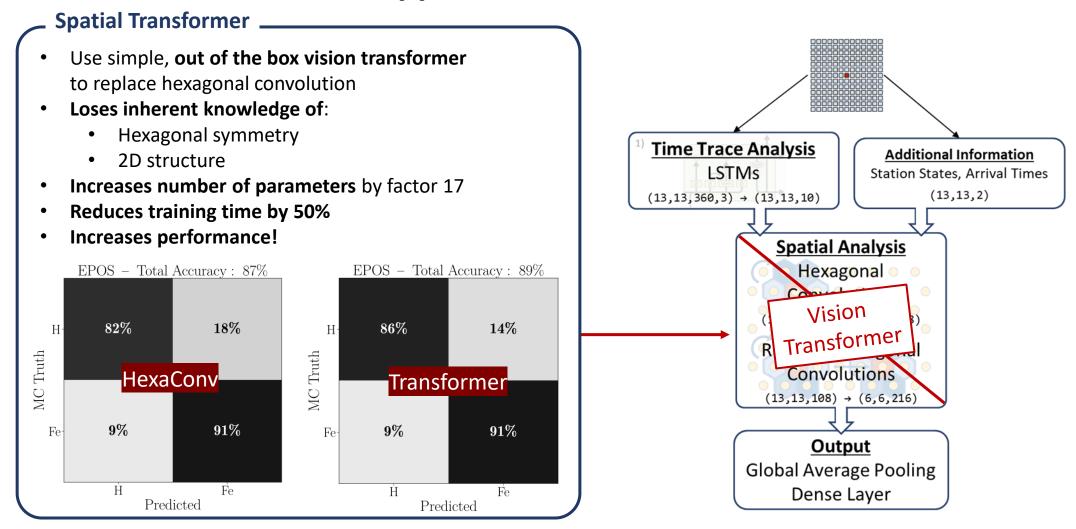


# **Challenges of Transformer Application**



⇒ Default attention quickly needs very large amounts of VRAM if data structure is too large, alternatives exist

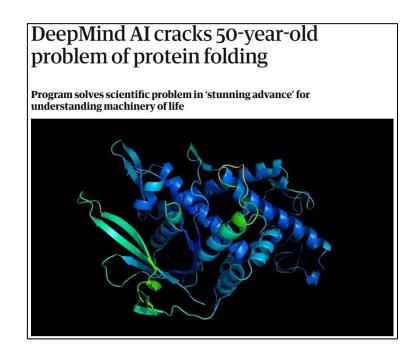
## **Chances of Transformer Application**

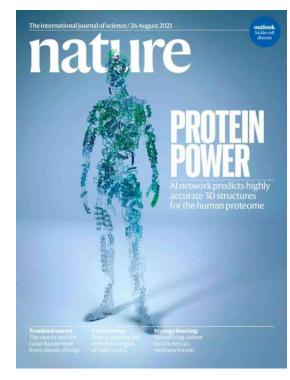


⇒ **Domain agnostic transformer** can be trained quickly, and **outperforms approach focused on data symmetry** (similar to Vision Transformer on images)

#### **Transformers in Science**

Similar to other fields, transformers are used **instead of LSTMs or CNNs**, as well as for **new applications**:



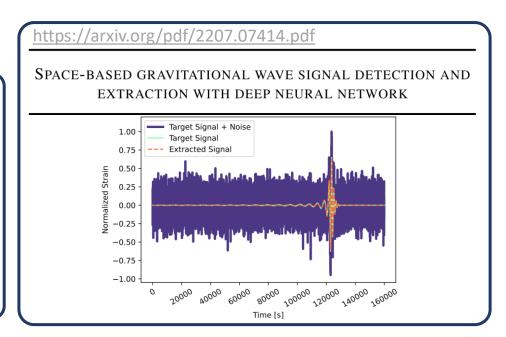


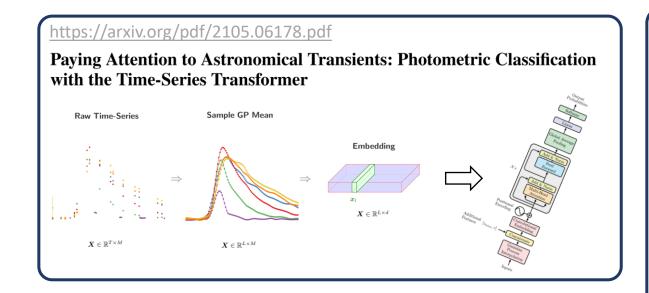
Famous science application: Protein unfolding

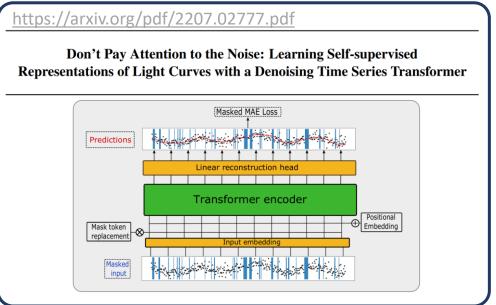
**Applications in Astro- and Particle Physics are becoming more common:** 

## **Time Sequence Analyses**

 $\begin{array}{c} \text{https://arxiv.org/pdf/2201.08482.pdf} \\ \overline{\text{Deep Attention-Based Supernovae}} & \text{Classification of Multi-Band Light-Curves} \\ \\ \boldsymbol{\bar{\psi}}_{i} & \boldsymbol{\bar{$ 

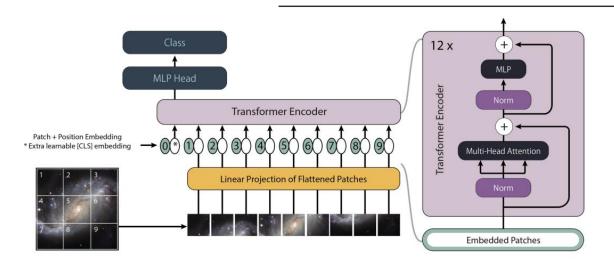


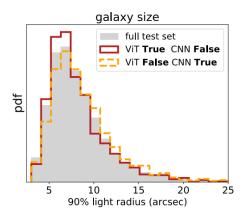


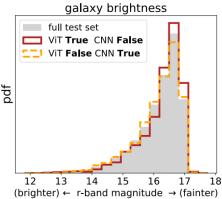


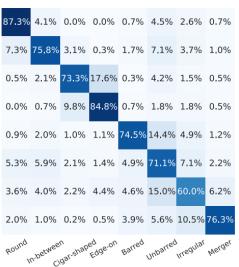
## **Vision Transformer Application**

#### Galaxy Morphological Classification with Efficient Vision Transformer



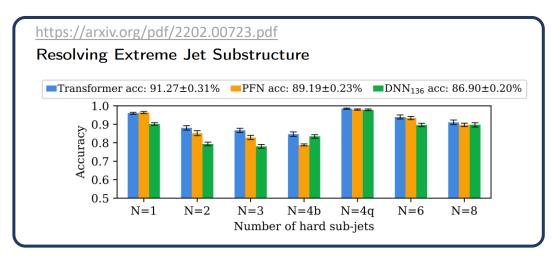


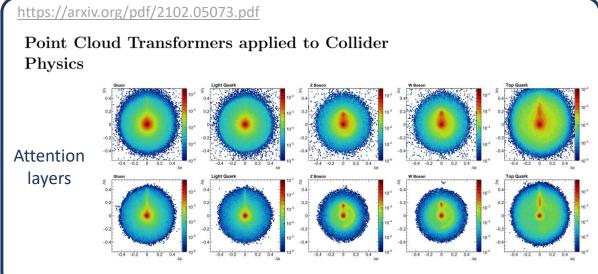




https://arxiv.org/pdf/2110.01024.pdf

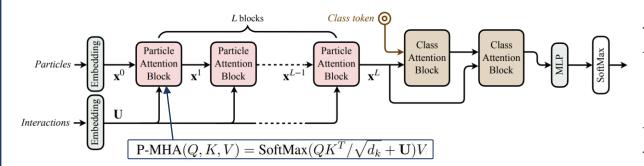
## **Particle Physics**





https://arxiv.org/pdf/2202.03772.pdf

#### **Particle Transformer for Jet Tagging**



 $\mbox{\it "P-MHA},$  an augmented version that can also exploit the pairwise particle interactions directly [...]

Essentially, we add the interaction matrix  $\boldsymbol{U}$  [...]. This allows P-MHA to incorporate particle interaction features designed from physics principles ..."

#### **JetClass Classification**

|              | Accuracy | # params         | FLOPs           |
|--------------|----------|------------------|-----------------|
| PFN          | 0.772    | 86.1 k           | 4.62 M          |
| P-CNN        | 0.809    | 354 k            | 15.5 M          |
| ParticleNet  | 0.844    | 370 k            | 540 M           |
| ParT         | 0.861    | $2.14\mathrm{M}$ | $340\mathrm{M}$ |
| ParT (plain) | 0.849    | 2.13 M           | 260 M           |

#### Top-Tagging

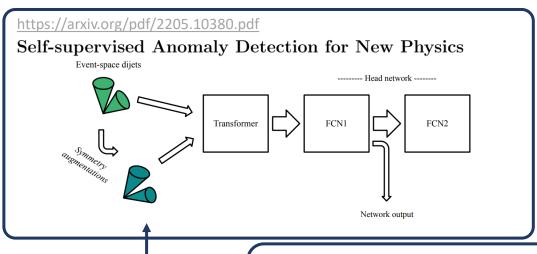
|                         | Accuracy |
|-------------------------|----------|
| P-CNN                   | 0.930    |
| PFN                     | _        |
| ParticleNet             | 0.940    |
| JEDI-net (w/ $\sum O$ ) | 0.930    |
| PCT                     | 0.940    |
| LGN                     | 0.929    |
| rPCN                    | _        |
| LorentzNet              | 0.942    |
| ParT                    | 0.940    |
| ParticleNet-f.t.        | 0.942    |
| ParT-f.t.               | 0.944    |

(Also best in quark-gluon tagging)

# **Particle Physics**

**Contrastive** 

Learning



https://arxiv.org/pdf/2203.05687.pdf A Holistic Approach to Predicting Top Quark Kinematic Properties with the Covariant Particle Transformer Top quarks Final state objects Top quarks Covariant Self-attention Covariant Self-attention Decoder 6 layers x 6 blocks Covariant Cross-attention Encoder Covariant Self-attention Final state objects Final state objects

(b) Encoder

https://arxiv.org/pdf/2108.04253.pdf

#### Symmetries, Safety, and Self-Supervision

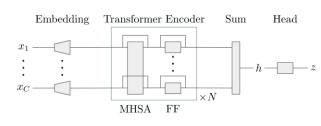
The goal of our network is to define a mapping between the jet constituents and a representation space,

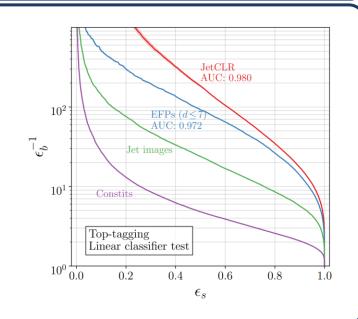
$$f: \mathcal{J} \to \mathcal{R}$$
, (1)

(a) CPT

which is, both,

- 1. invariant to symmetries and theory-driven augmentations, and
- 2. discriminative within the dataset it is optimized on.





(c) Decoder

### **Summary**

- Transformer: Based on attention mechanism
- New State-of-the art in many fields
  - Natural language processing
  - Image recognition
  - ...
- Large amounts of VRAM needed to analyze long sequences
  - Alternatives (Reformer, Sparse Transformer, Perceiver) exist, but some are less accessible
- Easily applicable to many different tasks, due to being domain agnostic
  - Quickly spreading to more branches of machine learning
  - Usage of transformers in physics at an early stage with promising results

