Combining ID & AD: simultaneous particle identification and anomaly detection at collider experiments using Bayesian neural networks

Wiehl 2022

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- Bayesian vs. Detern
- Our example use c
 - Multiclass classific
- Classification Perfo
- Anomaly Detection
- Conclusions









Out

















- Which parameters w of a function f are likely to have generated Y from X?

$$p(w|X,Y) = \frac{p(X,Y|w)p(w)}{p(X,Y)} = \frac{p(Y|X,w)p(X|w)p(w)}{p(Y|X)p(X)} = \frac{p(Y|X,w)p(w)}{\int p(Y|X,w)p(w)dw}$$

with for example $p(y = d|\mathbf{x}, \omega) = \frac{\exp(f_d^{\omega}(\mathbf{x}))}{\sum_{d'} \exp(f_{d'}^{\omega}(\mathbf{x}))}$

$$\operatorname{KL}(q_{\theta}(\boldsymbol{\omega}) \mid\mid p(\boldsymbol{\omega} \mid \mathbf{X}, \mathbf{Y})) = \int q_{\theta}(\boldsymbol{\omega}) \log \frac{q_{\theta}(\boldsymbol{\omega})}{p(\boldsymbol{\omega} \mid \mathbf{X}, \mathbf{Y})} d\boldsymbol{\omega} = -\int q_{\theta}(\boldsymbol{\omega}) \log p(\mathbf{Y} \mid \mathbf{X}, \boldsymbol{\omega}) d\boldsymbol{\omega} + \operatorname{KL}(q_{\theta}(\boldsymbol{\omega}) \mid\mid p(\boldsymbol{\omega} \mid \mathbf{X}, \mathbf{Y})) d\boldsymbol{\omega} + \operatorname{KL}(q_{\theta}(\boldsymbol{\omega}) \mid p(\boldsymbol{\omega} \mid \mathbf{X}, \mathbf{Y})) d\boldsymbol{\omega} + \operatorname{KL}(q_{\theta}(\boldsymbol{\omega} \mid \mathbf{X}, \mathbf{Y})) d\boldsymbol{\omega} + \operatorname{KL}(q_{\theta}(\boldsymbol{\omega}) \mid p(\boldsymbol{\omega} \mid \mathbf{X}, \mathbf{Y})) d\boldsymbol{\omega} + \operatorname{KL}(q_{\theta}(\boldsymbol{\omega} \mid \mathbf{X}, \mathbf{Y})) d\boldsymbol{\omega} d\boldsymbol{\omega} + \operatorname{KL}(q_{\theta}(\boldsymbol{\omega} \mid \mathbf{X}, \mathbf{Y})) d\boldsymbol{\omega} d\boldsymbol{\omega} + \operatorname{KL}(q_{\theta}(\boldsymbol{\omega} \mid \mathbf{X}, \mathbf{Y})) d\boldsymbol{\omega} d\boldsymbol{\omega} d\boldsymbol{\omega} + \operatorname{KL}(q_{\theta}(\boldsymbol{\omega} \mid \mathbf{X}, \mathbf{Y})) d\boldsymbol{\omega} d\boldsymbol{\omega}$$

• Sampling from optimal $q_{\theta}^*(w) \rightarrow distribution$ of predictions instead of a point estimate $p(\mathbf{y}^*|\mathbf{x}^*, \mathbf{X}, \mathbf{Y}) \approx \int p(\mathbf{y}^*|\mathbf{x}^*, \boldsymbol{\omega}) q_{\theta}^*(\boldsymbol{\omega}) \mathrm{d}\boldsymbol{\omega}$

Description from Yarin Gal, Uncertainty in Deep Learning, PhD thesis, Cambridge, 2016 and arXiv:0712.4042.

• Basic idea: learn the whole distribution over the NN weights w given training data {X,Y}

• Often intractable \rightarrow approximate with simpler function $q_{\theta}(w)$ minimizing KL divergence









- Which parameters w of a function f are likely to have generated Y from X?

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 $p(\mathbf{y}^*|\mathbf{x}^*,\mathbf{X},\mathbf{Y}) \approx$

Description from Yarin Gal, Uncertainty in Deep Learning, PhD thesis, Cambridge, 2016 and arXiv:0712.4042.

Bayesian Neural Networks

• Basic idea: learn the whole distribution over the NN weights w given training data {X,Y}

 $\frac{|X,w)p(X|w)p(w)}{p(Y|X)p(X)} = \frac{p(Y|X,w)p(w)}{\int p(Y|X,w)p(w)dw}$

• Often intractable \rightarrow approximate with simpler function $q_{\theta}(w)$ minimizing KL divergence

• Sampling from optimal $q_{\theta}^*(w) \rightarrow distribution$ of predictions instead of a point estimate

$$\int p(\mathbf{y}^*|\mathbf{x}^*, \boldsymbol{\omega}) q_{\theta}^*(\boldsymbol{\omega}) \mathrm{d}\boldsymbol{\omega}$$





 Small training datasets lead to larger uncertainties in the BNN predictions (example from top-tagging in 1904.10004)

 BNNs predictions for out-of-distribution test samples can have large uncertainties



(a) Standard deep learning model

Y. Gal, PhD thesis, Cambridge

Bayesian Neural Networks

1904.10004







- Classification of images in EM calorimeters = photon identification
- Main background:
 - High-energy $\pi^0 \rightarrow \gamma\gamma$
- Toy EM calorimeter à la 1712.10321
 - ATLAS-like: 3 layers of LAr+Pb
 - I m from Geant4 particle gun



Our Example Use Case











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- Main background:
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Our Example Use Case









Particle gun kinetic energy: 20 GeV

- Single photon (signal)
- 8 physical background classes:
 - Different purely EM decays of mesons with different masses \rightarrow different opening angles
- + noise background class (noise burst in 2nd layer with 1% cross talk to neighbouring cells)

 Photon ID algorithm at LHC would be trained on effective mixture via parton shower programs

Our Example Use Case









- Setup: 2D CNN with 8 filters and 3x3 kernel size for each calorimeter layer
 - + 10 output nodes all using Flipout (1803.04386)
- Assume weights to be Gaussian distributed, uncorrelated and with Gaussian priors Very similar performance to deterministic NN

Deterministic NN







• For each image, sample from the weight distributions \rightarrow mean & variance per image













• For each image, sample from the weight distributions \rightarrow mean & variance per image



Std. Dev.











• Now: remove one class at a time during training = anomaly (here: $J/\psi \rightarrow e^+e^-$)

Mean



Results

Std. Dev.







- In general, larger uncertainty than before
- Stems from three different cases:
 - A) Examples with ~0 variance
 - B) Examples with >1 active output node
 - Examples with "jumpy decisions" **C**)





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- Stems from three different cases:
 - A) Examples with ~0 variance



Another example: noise burst as anomaly

Mean

Removed class: Noiseburst



Results

#Events

Std. Dev.

Removed class: Noiseburst







Standard deviations when each class is removed one-by-one

• Some anomalies are easier to identify than others











- Bayesian network's uncertainty estimate may help to identify anomalies
- Semisupervised approach (LHC Olympics 2020,
- We don't know, yet, if it can compete with specialized AD algorithms

• One advantage:

Provides AD capabilities as a sanitiy/DQ cross check

for standard classification tasks (such as ID)

At some additional training and prediction costs

Conclusions

2101.08320)

Section	Short Name	Method Type
3.1	VRNN	Unsupervised
3.2	ANODE	Unsupervised
3.3	BuHuLaSpa	Unsupervised
3.4	GAN-AE	Unsupervised
3.5	GIS	Unsupervised
3.6	LDA	Unsupervised
3.7	PGA	Unsupervised
3.8	Reg. Likelihoods	Unsupervised
3.9	UCluster	Unsupervised
4.1	CWoLa	Weakly Supervi
4.2	CWoLa AE Compare	Weakly/Unsuper
4.3	Tag N' Train	Weakly Supervi
4.4	SALAD	Weakly Supervi
4.5	SA-CWoLa	Weakly Supervi
5.1	Deep Ensemble	Semisupervise
5.2	Factorized Topics	Semisupervise
5.3	QUAK	Semisupervise
5.4	LSTM	Semisupervise



