

OpenSearch

Introduction and overview



www.kit.edu

Components of monitoring architecture







Agenda

- What is OpenSearch?
- History of OpenSearch
- Use cases
- Features
- Basic concepts:
 - Cluster and nodes
 - Indices and documents
 - Shards
- Adding data to OpenSearch



OpenSearch

https://opensearch.org/

OpenSearch is a community-driven, Apache 2.0-licensed open source search and analytics suite that makes it easy to ingest, search, visualize, and analyze data.

Steinbuch Centre for Computing

What is OpenSearch?



- Launched in July 2021 by Amazon Web Services (AWS)
- It is a forked project based on old versions of Elasticsearch and Kibana (v. 7.10.2)
- Interact via REST API
- Built in Java using Lucene
- Consists of:
 - a search engine, **OpenSearch** (based on Elasticsearch);
 - a visualization user interface, OpenSearch Dashboards (based on Kibana);
 - as well as a series functionality-adding tools and plugins.

From Elasticsearch to OpenSearch





History of OpenSearch





Why was OpenSearch created?



- Elasticsearch made its debut in 2010 and established itself as the most popular search engine. Early iterations of Elasticsearch were open source and a combination of multiple products known as the ELK Stack (Elasticsearch, Logstash, Kibana).
- AWS launched in 2019 Open Distro for Elasticsearch, a value-added distribution of Elasticsearch 100% open source.
- On January 21 2021, Elastic NV announced that they would change their software licensing strategy and not release new versions of Elasticsearch and Kibana under the permissive Apache License, Version 2.0 (ASLv2).
- The move away from open source code by Elastic prompted AWS to roll out an open source, community-driven fork of Elasticsearch and Kibana called OpenSearch.

Uses cases



Logging Centralize and search application logs at scale Infrastructure Analyze system metric Application monitoring Monitor software services and applications in real-time Full-text search Application, websites Infrastructure Analyze system metric Examining Second

Infrastructure monitoring

Analyze system metrics (CPU and memory usage)

Security analytics

Network traffics, authentication logs

Business analytics

Examining business data for the purpose of gaining useful information

Root causes analysis

Quickly identify to resolve issues











Basic Concepts: Cluster and nodes

Cluster and nodes



- The distributed design means that you interact with OpenSearch *clusters*.
- Each cluster is a collection of one or more *nodes*, servers that store your data and process search requests.



OpenSearch Cluster with 3 nodes

Cluster and nodes



- The cluster is horizontally scalable, and adding additional nodes to the cluster allows the cluster capacity to increase linearly while maintaining similar performance.
- Nodes in the cluster can be differentiated based on the specific type of operations that they perform (cluster manager, data, ingest, coordinating node).





Basic Concepts: Data organizations

Steinbuch Centre for Computing

Indices and documents



- OpenSearch is a document oriented database.
- Documents are JSON structures that hold a collection of fields and their values.
- A document is like a row in a table in a relational database.

"Name": "John Smith", "Age": 37, "Street":"123 Main St" "City":"Boston", "State": "MA"

Indices and documents



- OpenSearch organizes data into indices.
- An index is a logical collection of documents.
- An index is like to a database table.
- Although an index could have documents with entirely different content, for efficiency purposes, you would typically store similar documents in the same index.

Indices and documents



As an example, the following people index has documents about persons. Though the documents will all have similar content, some fields may only appear only in certain documents.



Fields



- A document contains a list of fields or key-value pairs.
- A field is similar to a column in a table in a relational database.
- Fields can be of several different types such as numbers, text, keywords, geo points, etc.



Mapping



- OpenSearch also has the ability to be schema-less, which means that documents can be indexed without explicitly specifying how to handle each of the different fields that might occur in a document.
- When dynamic mapping is enabled (by default), OpenSearch automatically detects and adds new fields to the index.
- However, if you know exactly what types your data falls under and want to enforce that standard, then you can use explicit mappings.

PUT sample-index1
{
"mappings": {
"properties": {
"year": { "type" : "text" },
"age": { "type" : "integer" },
<pre>"director":{ "type" : "text" }</pre>
}
}
}

RDBMS vs Document-Oriented Database



RDBMS



OpenSearch index" : "accounts", : " doc", : 2, sea no" : 2, primary term" : 1, "found" : true, " source" : "fistname" : "Virginia", "lastname" : "Alaya", "email" : "virginiaayala@filodyne.com", "age" : 25, "hobbies" : ["Volleyball"

table=>index

- A document is similar to a row in the relational databases
- Fields are similar to columns in the relational databases
- An *index* is like to a database *table*



RDBMS vs Document-Oriented Database

Relational model	Document model
Stores data in a schema that uses tables with columns and rows	Stores entities as documents – like a JSON documents
Predefined schema	Dynamic schema
Based structured query language (SQL)	Querying through an API or unstructured query language
Vertically scalable	Horizontally scalable
It is slower	It is faster than relational model
Supports complex joins	Does not support complex joins







Basic Concepts: Internal Data Structures

Steinbuch Centre for Computing

Shards



- The shard is the atomic part of an index, which can be distributed over the cluster.
- Every index can be split into several shards to be able to distribute data.
- OpenSearch distributes shards almost all nodes in the cluster and can move shards automatically from one node to another in case of node failure, or the addition of new nodes.



Index with 3 primary shards

Primary and Replica Shards



There are two types of shards: primaries and replicas.

- **Primary shard:** each document in an index belongs to one primary shard.
- **Replica shard:** a replica shard is a copy of a primary shard.
 - ☑ increase failover: a replica shard can be promoted to a primary shard.
 - ☑ increase performance: get and search requests can be handled by primary or replica shards.



Index with 3 primary shards and 1 replica each

Adding data to OpenSearch



There are a number of options for getting your data into OpenSearch, which is commonly referred to as **ingesting or indexing data.**

For example:

- Send data directly to OpenSearch from your application using one of the language clients (Python, Java, Ruby, PHP, etc...)
- Use **Agents and Ingestion Tools** for timestamped data:
 - Beats are data shippers designed to collect and ship a particular type of data from a server. Install a separate Beat for each type of data you want to collect
 - Logstash is an open source data collection engine which transforms and prepares data and supports a wide variety of data sources.

OpenSearch Cluster at SDM





- 5-node cluster
- About 17,5 TB space per node
- Authentication and Authorization via KIT OpenID
- Deployment and configuration of OpenSearch via Puppet
- Security plugin enabled

Contact: <u>elk-sdm-team@lists.kit.edu</u>



Grafana OpenSearch SDM Cluster Dashboard

Steinbuch Centre for Computing

Useful links



OpenSearch SDM Cluster Documentation: <u>https://docs-sdm.scc.kit.edu/DocumentationELKClusterSDM/</u>

OpenSearch project website and technical documentation: <u>https://opensearch.org/</u> <u>https://opensearch.org/docs/latest/</u>

OpenSearch Community forum: <u>https://forum.opensearch.org/</u>

Elasticsearch project: <u>https://www.elastic.co/</u>