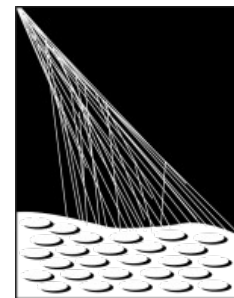


Potential of neural network triggers for the Water-Cherenkov detector array of the Pierre Auger Observatory

IAP HEU seminar 2024/01/25



PIERRE
AUGER
OBSERVATORY

Paul Filip, David Schmidt

Acknowledgements: Markus Roth, Darko Veberič, Dave Nitz



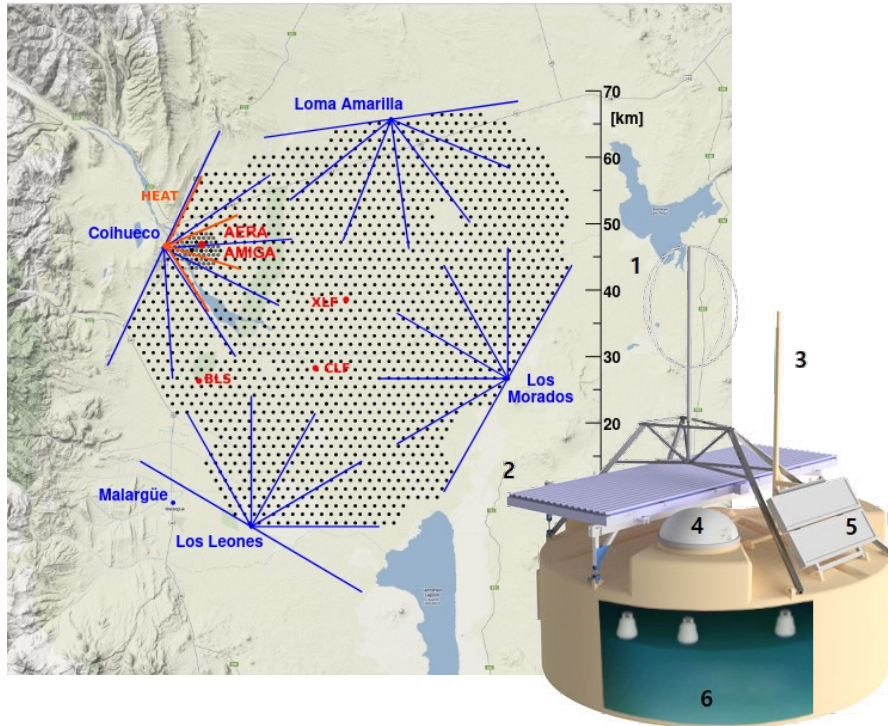
Goals

- **Are NN-based triggers feasible SD/WCD triggers?**
- **Test feasibility with (for now) simulated proton showers**

Requirements

- **Limited computational power in FPGAs/UUB electronics**
- **Limited choice in candidate network architectures!**
- **Limited number of trainable parameters!**

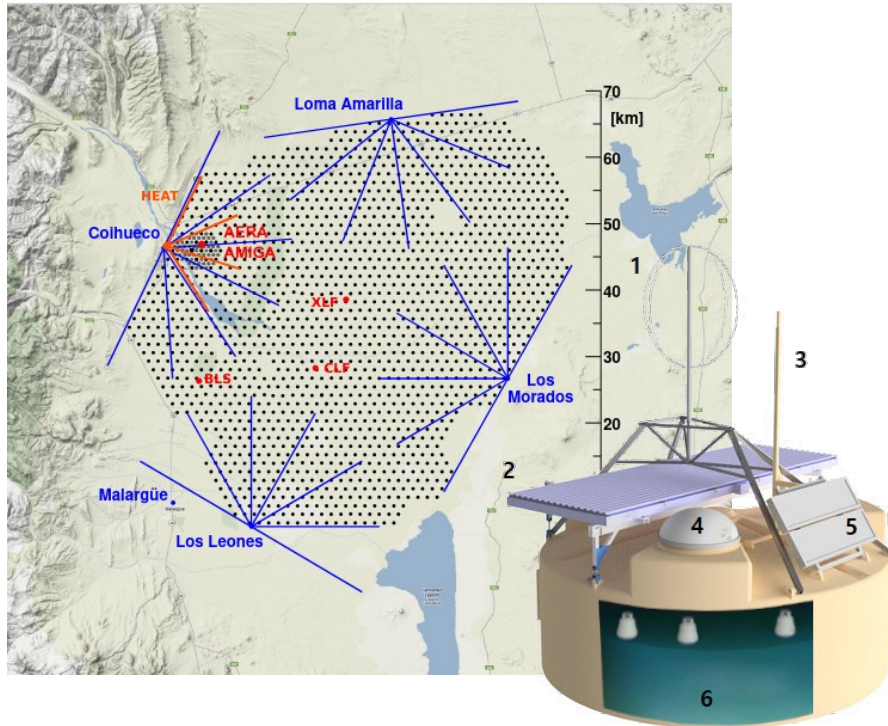
SD Array / trigger hierarchy / WCD time traces



- Around ~1600 stations
- Triangular 1500 m grid spacing
- Quasi 100% uptime

1 RD	2 SSD
3 Comms Antenna	4 Electronics Box
5 Solar Panel	6 WCD

SD Array / trigger hierarchy / WCD time traces

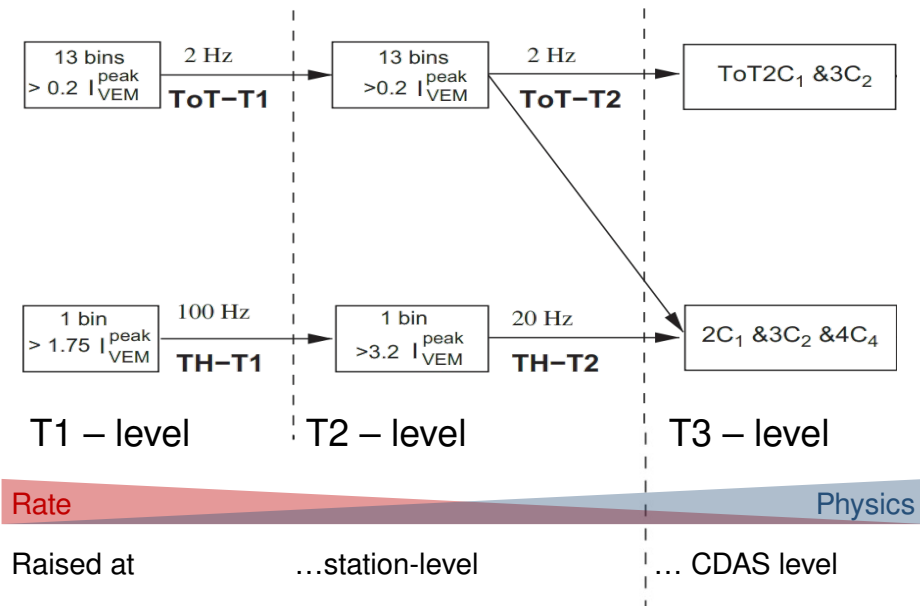


- Around ~1600 stations
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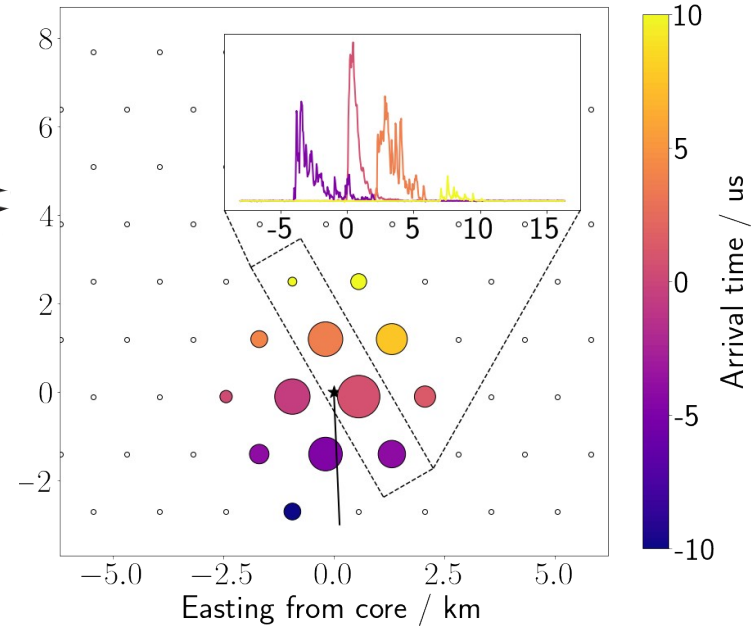
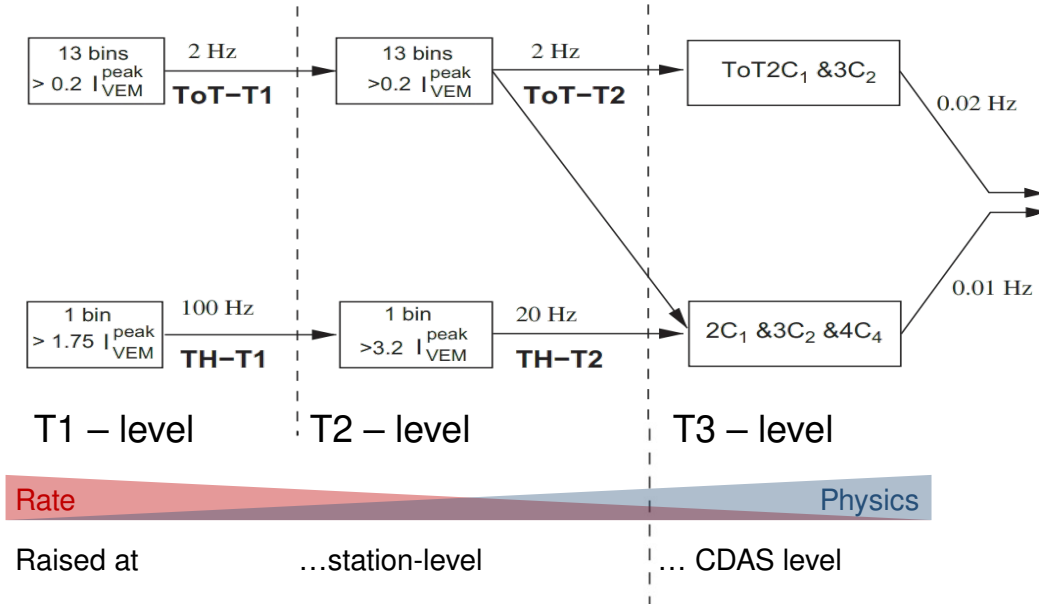
Too comput. expensive to read all measured data at all times!
➔ Implement **trigger hierarchy**

1 RD	2 SSD
3 Comms Antenna	4 Electronics Box
5 Solar Panel	6 WCD

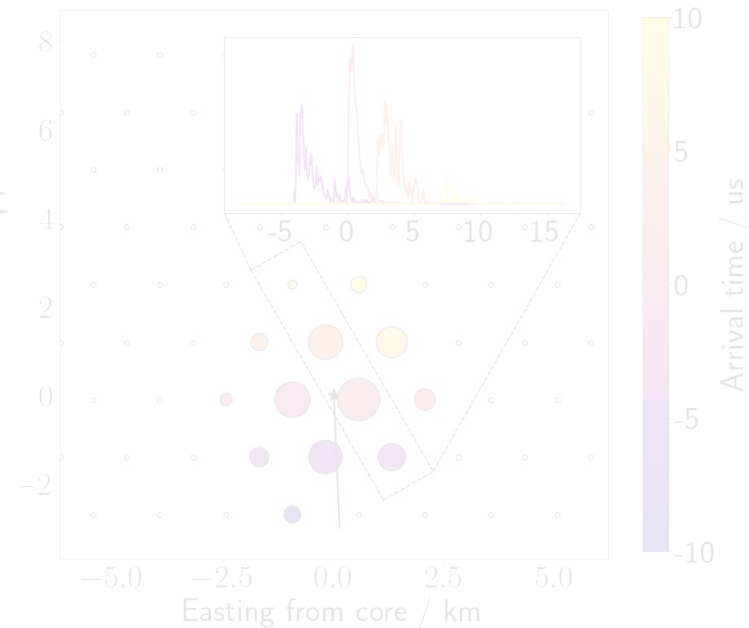
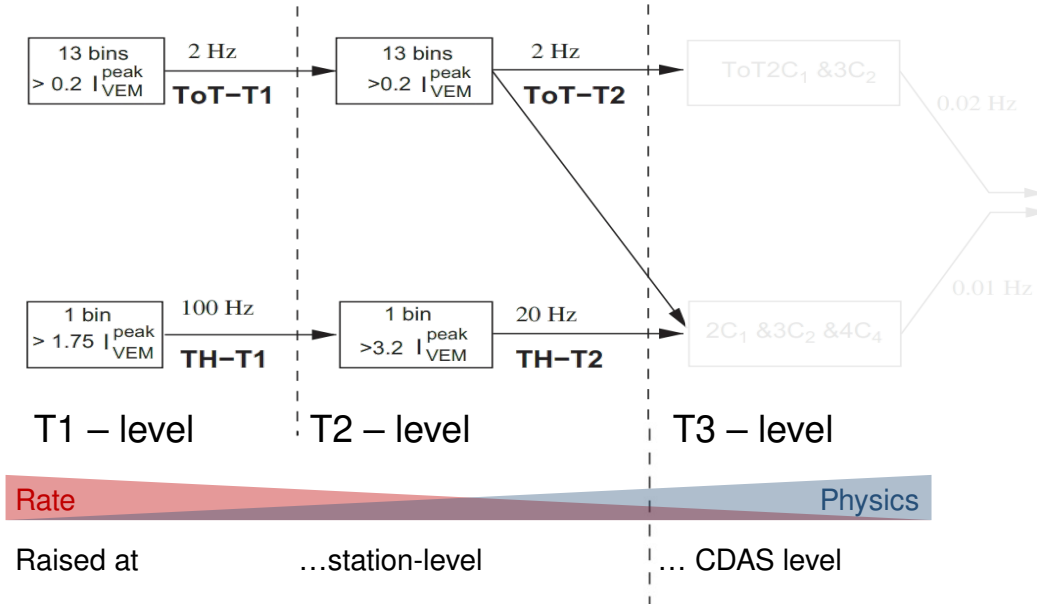
SD Array / trigger hierarchy / WCD time traces



SD Array / trigger hierarchy / WCD time traces



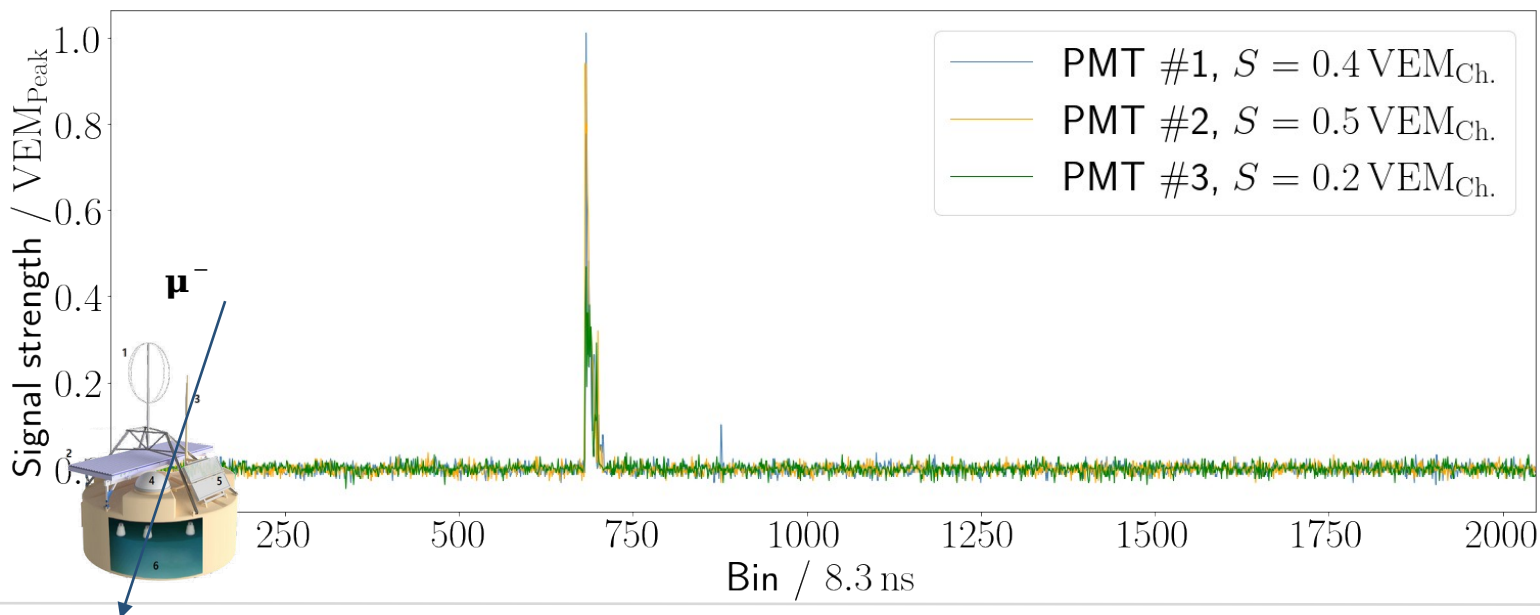
SD Array / trigger hierarchy / WCD time traces



- Limited computational power in FPGAs/UUB electronics
- Limited choice in candidate network architectures/size

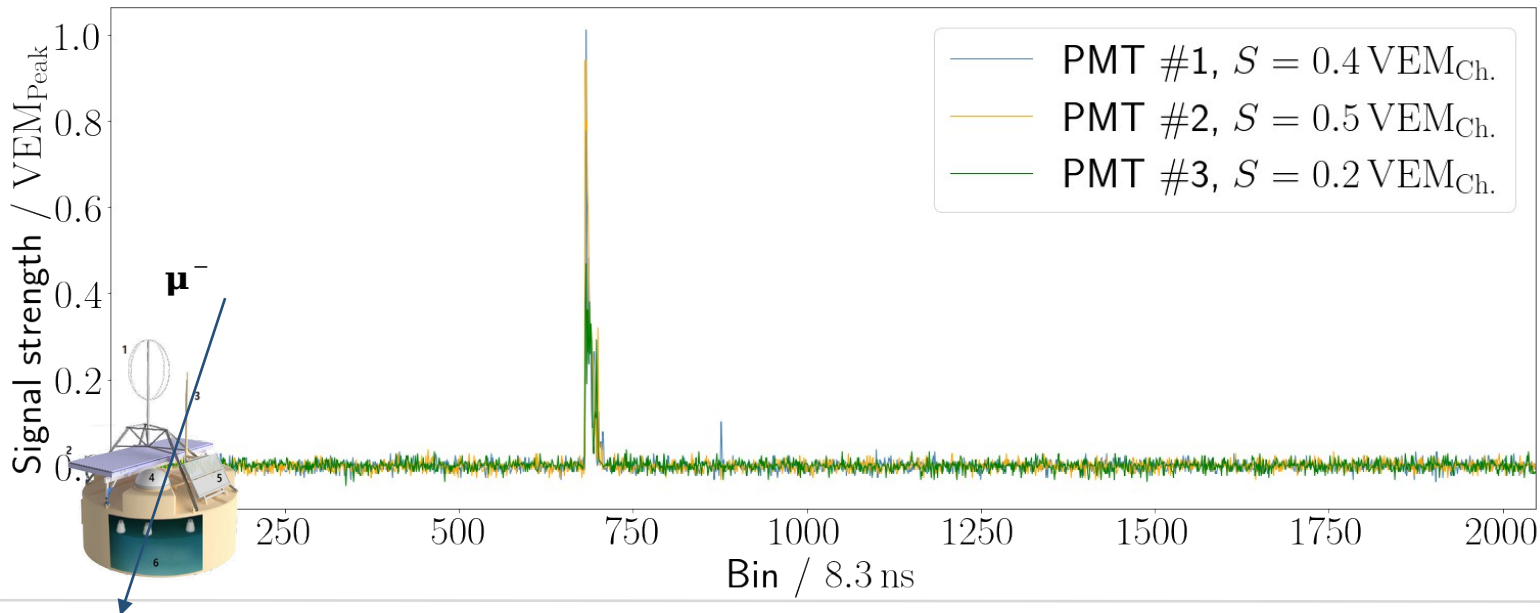
■ Threshold trigger (Th)

- PMTs register signal $3.2 VEM_{Peak}$ ($1.75 VEM_{Peak}$ for T1)
- Threshold must be exceeded simultaneously for all PMTs



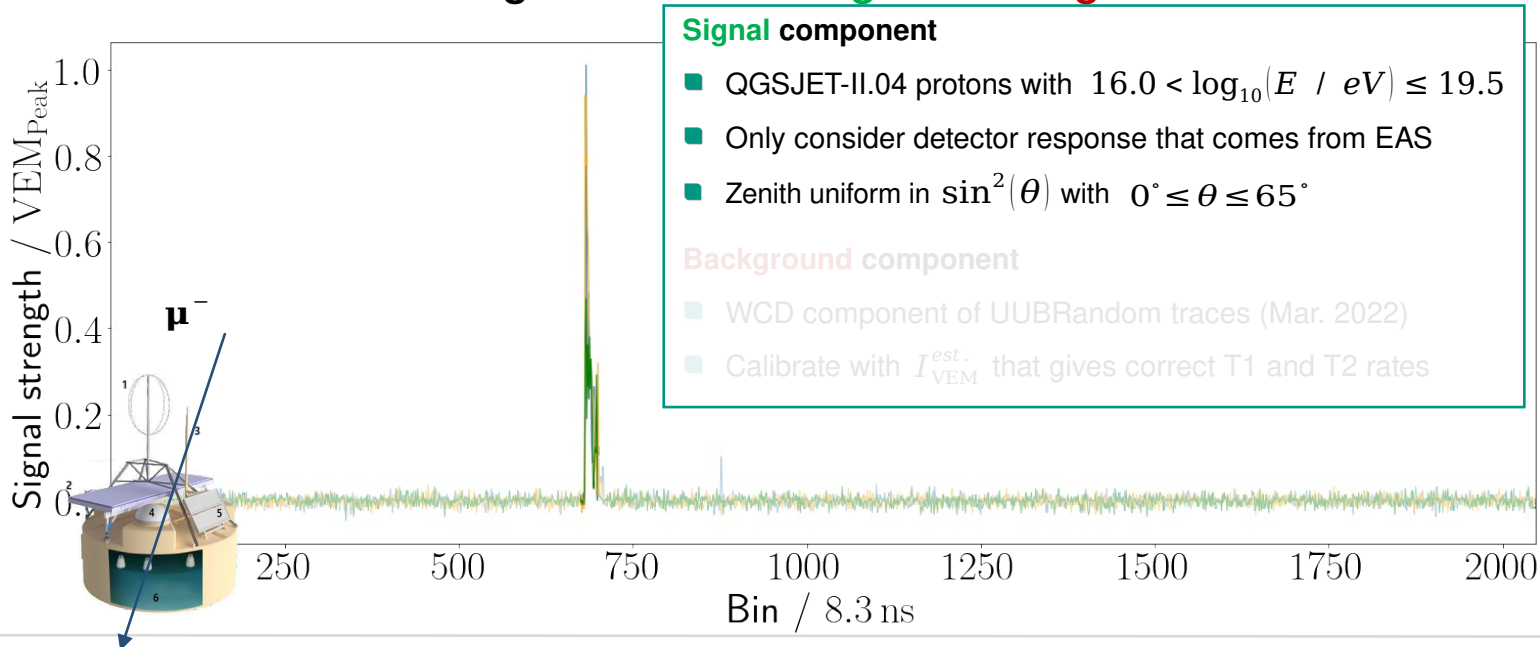
■ NN triggers

- Feed labelled subset of trace to neural network architecture
- Teach it to distinguish between **Signal** / **Background**



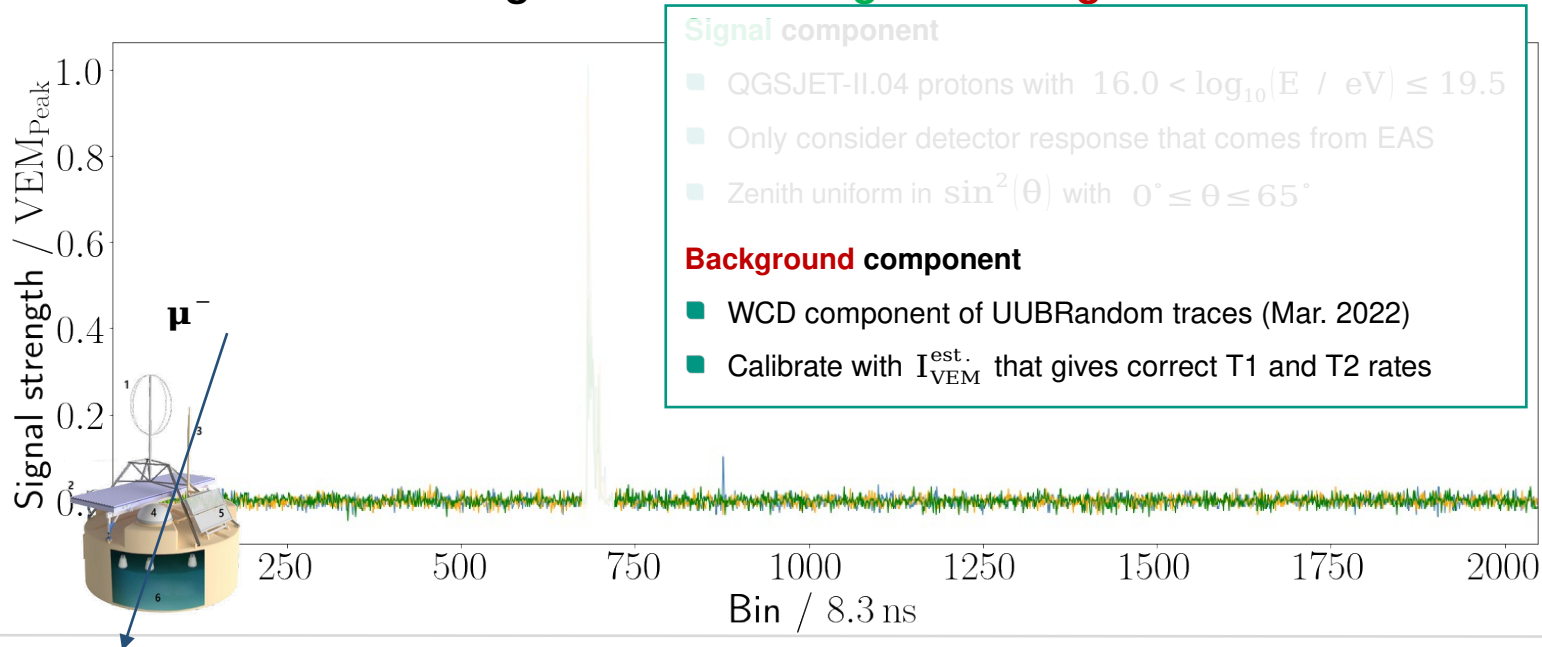
■ NN triggers

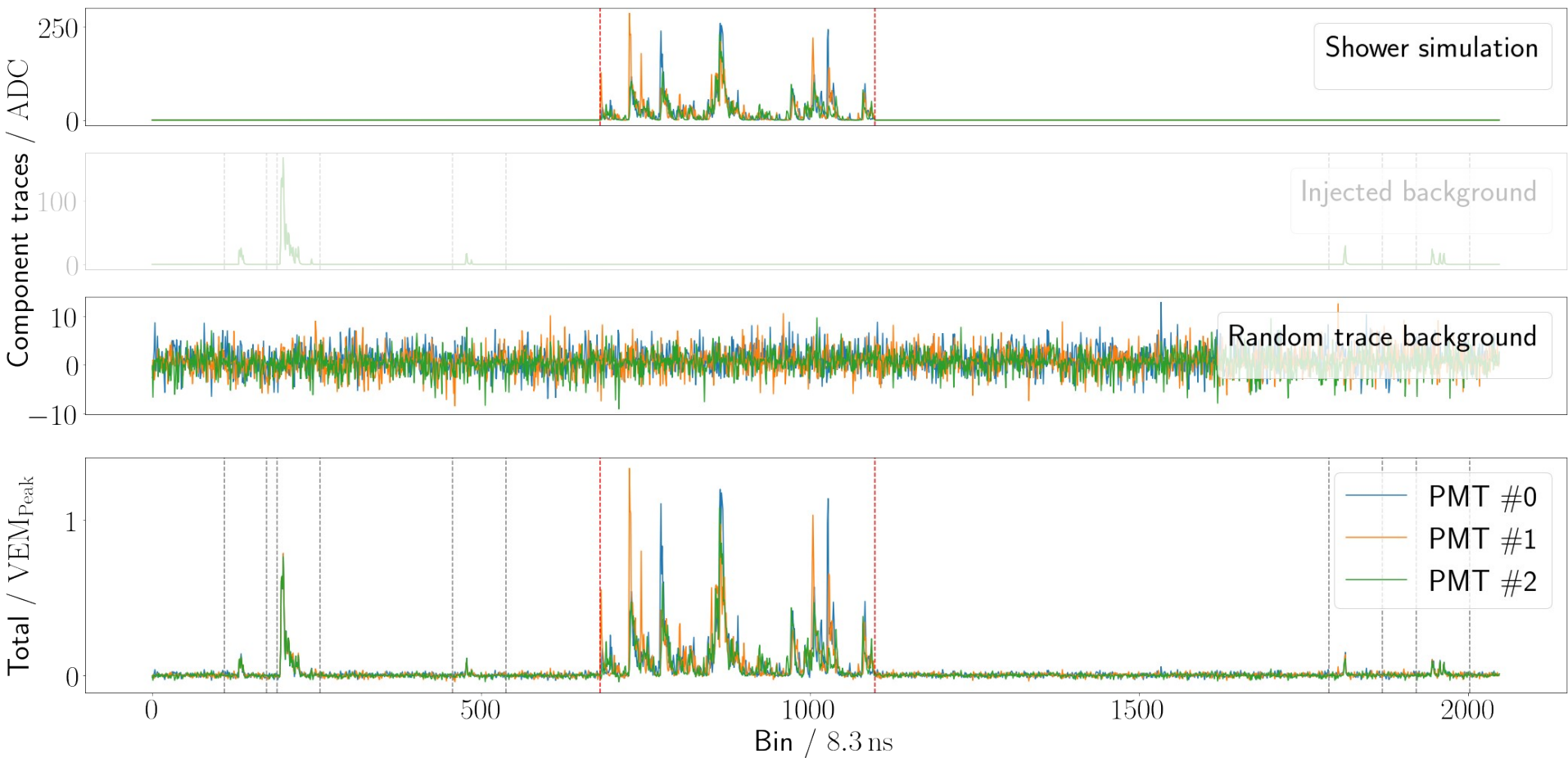
- Feed labelled subset of trace to neural network architecture
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■ NN triggers

- Feed labelled subset of trace to neural network architecture
- Teach it to distinguish between **Signal** / **Background**



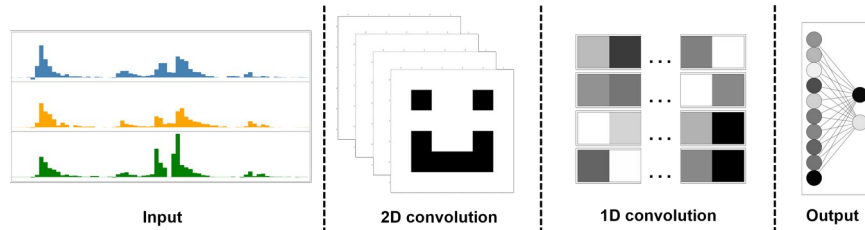


Network architectures

- 120 bins x 3 PMTs = 360 input values \rightarrow 1 binary output (1 = Shower, 0 = Background)

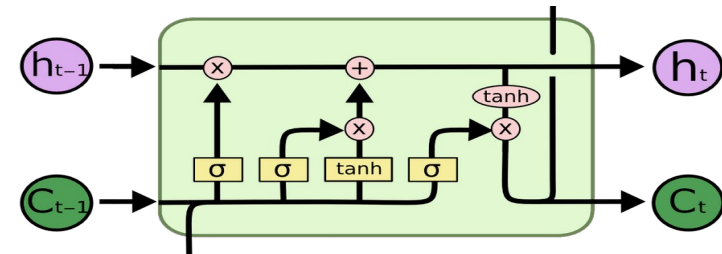
Convolutional neural networks (CNNs)

- Good at recognizing objects in images
- Treat input data as 3x120 pixel image
- Output independent of signal position in window
- 1-2 convolutional layers with dense final layer
- 84 to 890 free trainable parameters



Recurrent neural networks (LSTMs)

- Good at recognizing patterns sequential data
- Basic LSTM receives 1-dimensional input
- Implement 1 distinct LSTM for each PMT
- 12 to 44 free trainable parameters



From <https://colah.github.io/posts/2015-08-Understanding-LSTMs/>

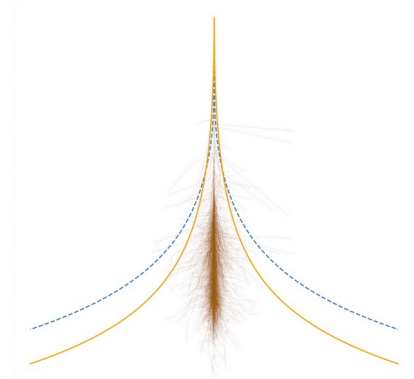
Estimating performance

- Have (after training neural network) trigger efficiency **given** signal: $P(T2 \mid \text{Signal})$
- Want trigger efficiency independent of EAS particles in tank: $P(T2)$

Estimating performance

- Have (after training neural network) trigger efficiency **given** signal: $P(T2 \mid \text{Signal})$
- Want trigger efficiency independent of EAS particles in tank: $P(T2)$
- Scale with lateral particle probability (LPP): $P(\text{Signal})$

$$\text{LPP} = \min \left(1, \text{Lateral distribution function} \right)^*$$



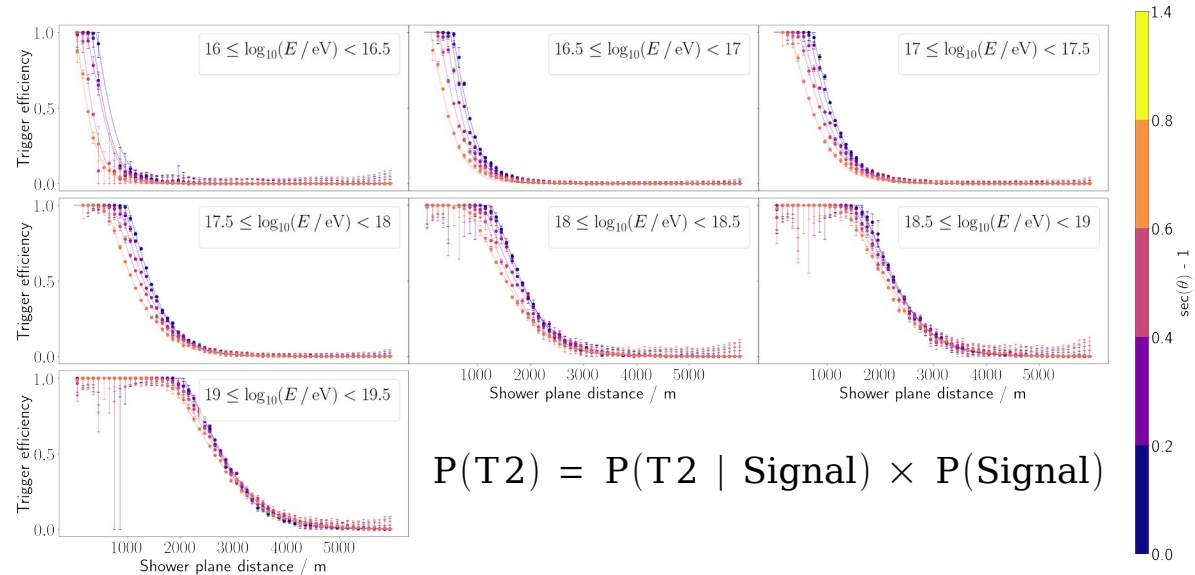
Lateral distribution function

* not really, but helps with intuition

Estimating performance

- Have (after training neural network) trigger efficiency **given** signal: $P(T2 \mid \text{Signal})$
- Want trigger efficiency independent of EAS particles in tank: $P(T2)$
- Scale with lateral particle probability (LPP): $P(\text{Signal})$

LPP =

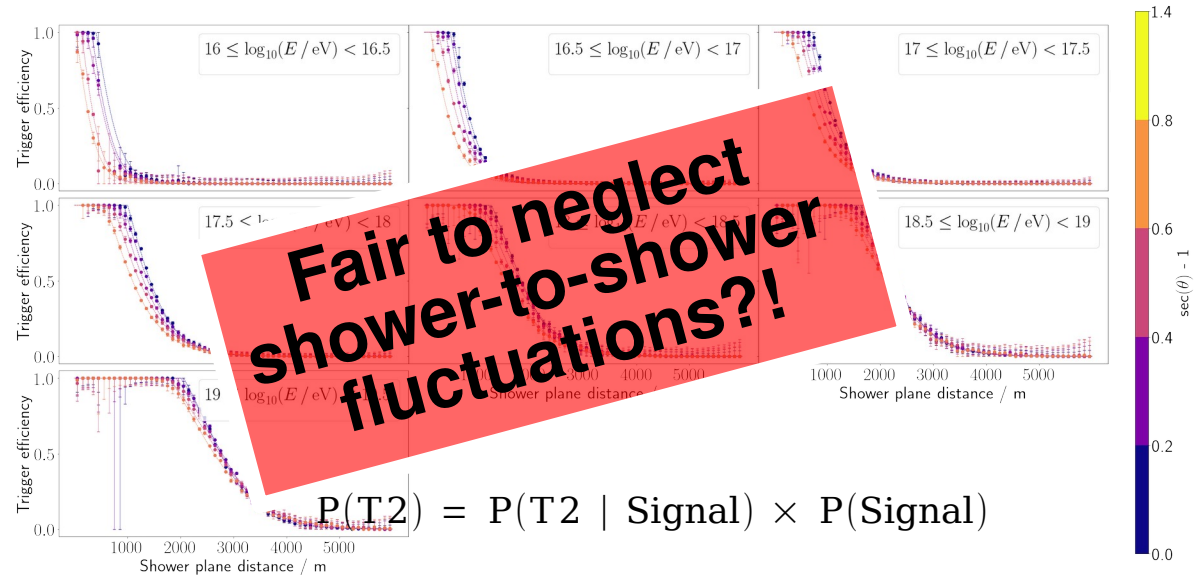


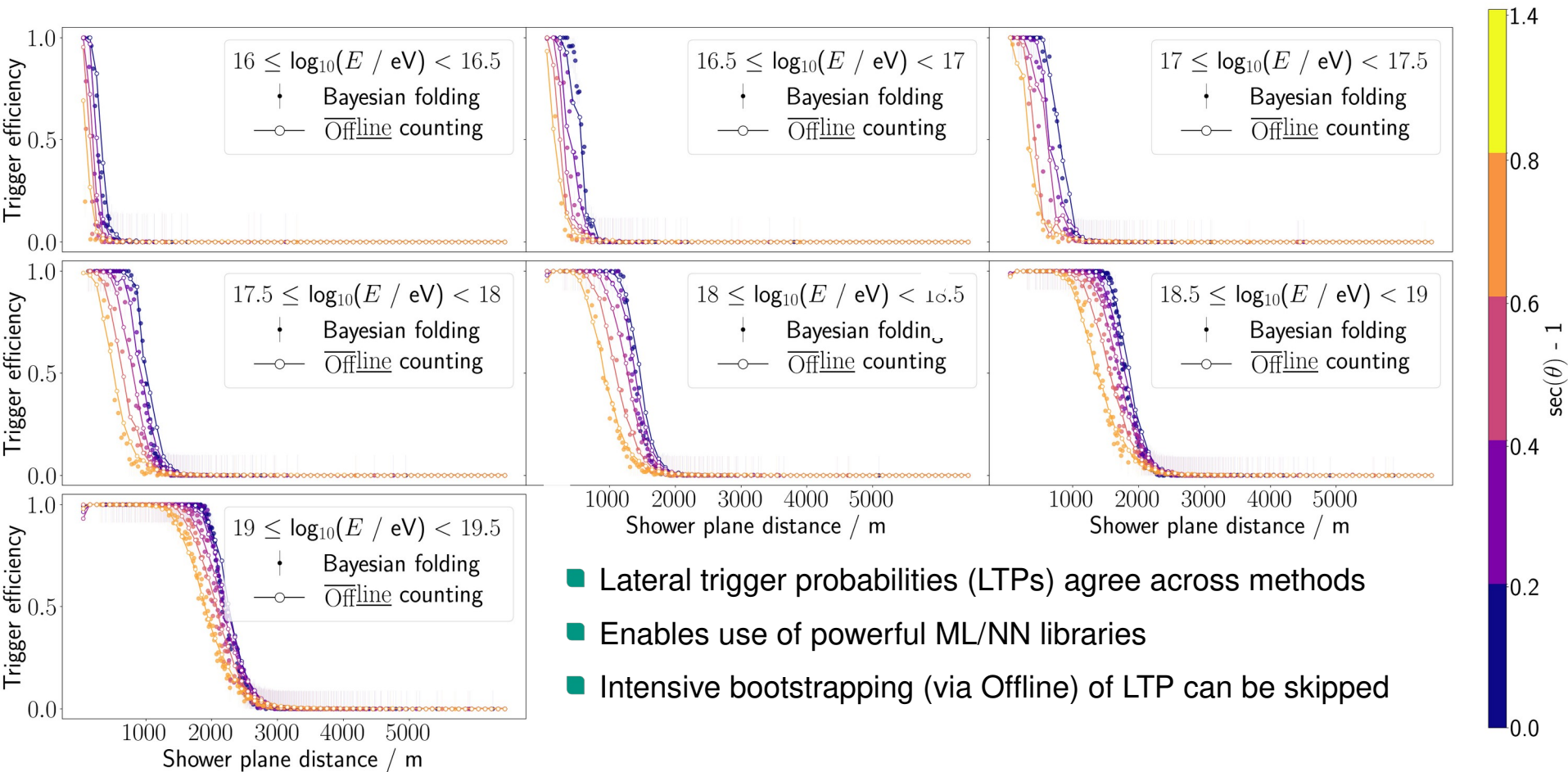
$$P(T2) = P(T2 \mid \text{Signal}) \times P(\text{Signal})$$

Estimating performance

- Have (after training neural network) trigger efficiency **given** signal: $P(T2 \mid \text{Signal})$
- Want trigger efficiency independent of EAS particles in tank: $P(T2)$
- Scale with lateral particle probability (LPP): $P(\text{Signal})$

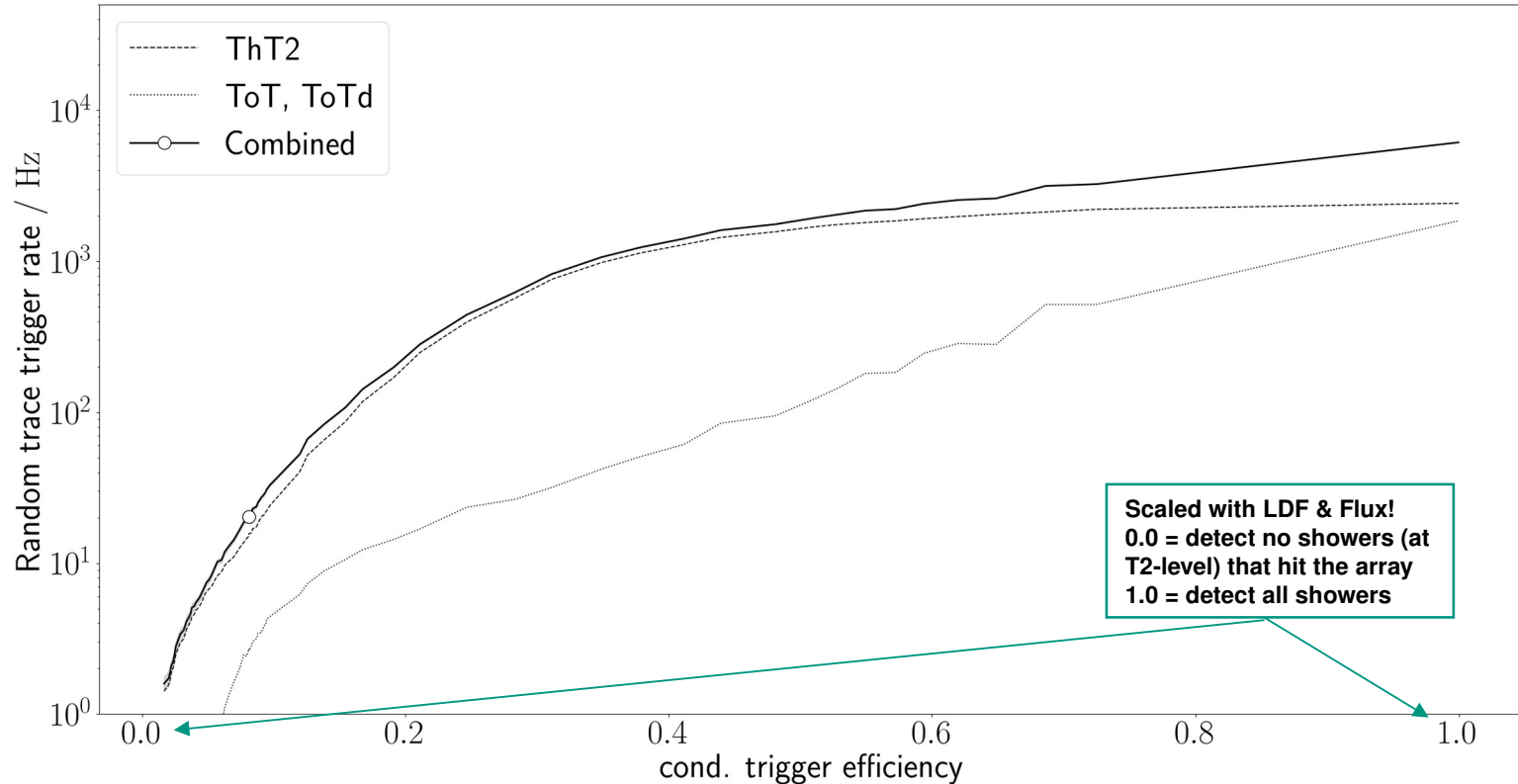
LPP =



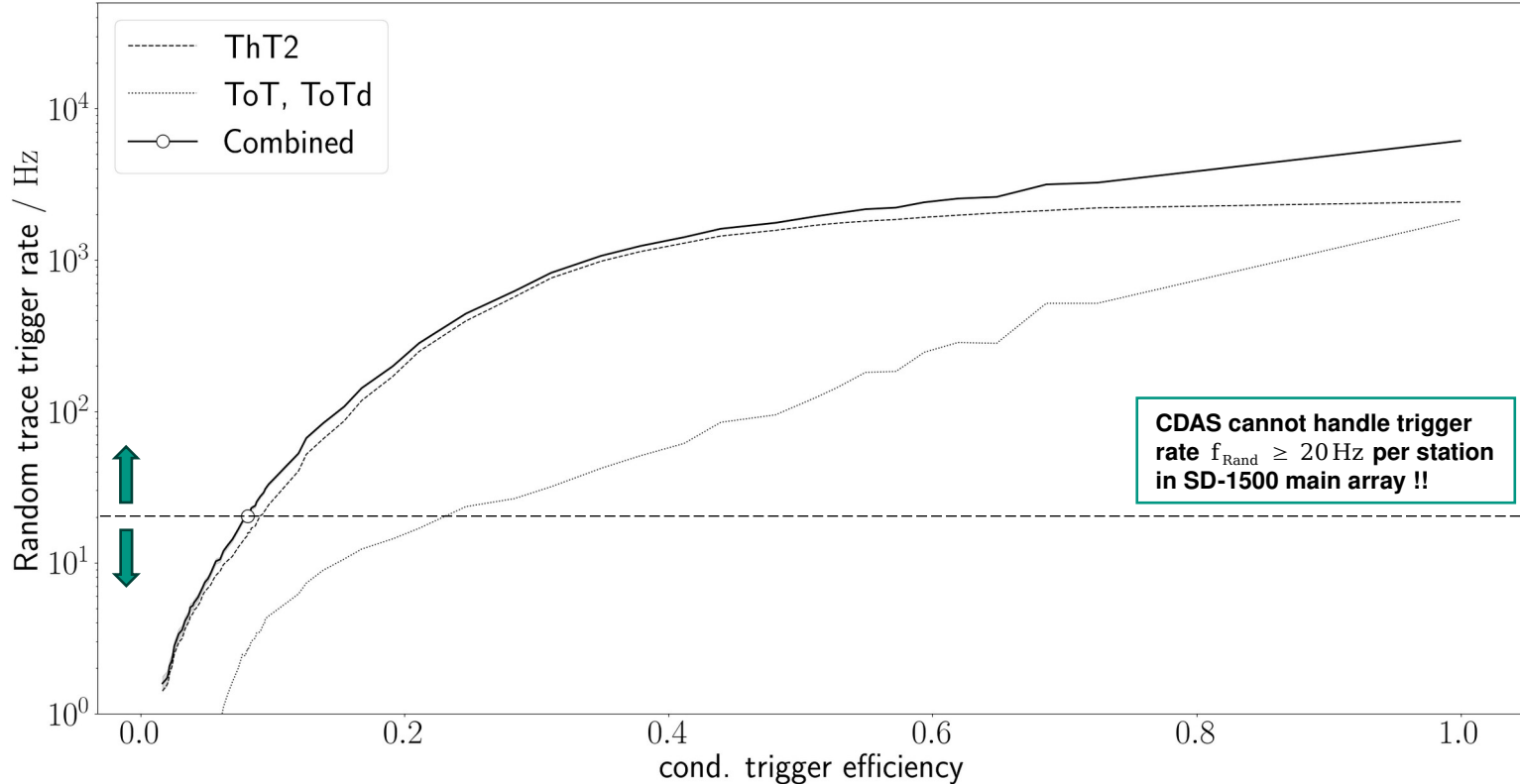


- Lateral trigger probabilities (LTPs) agree across methods
- Enables use of powerful ML/NN libraries
- Intensive bootstrapping (via Offline) of LTP can be skipped

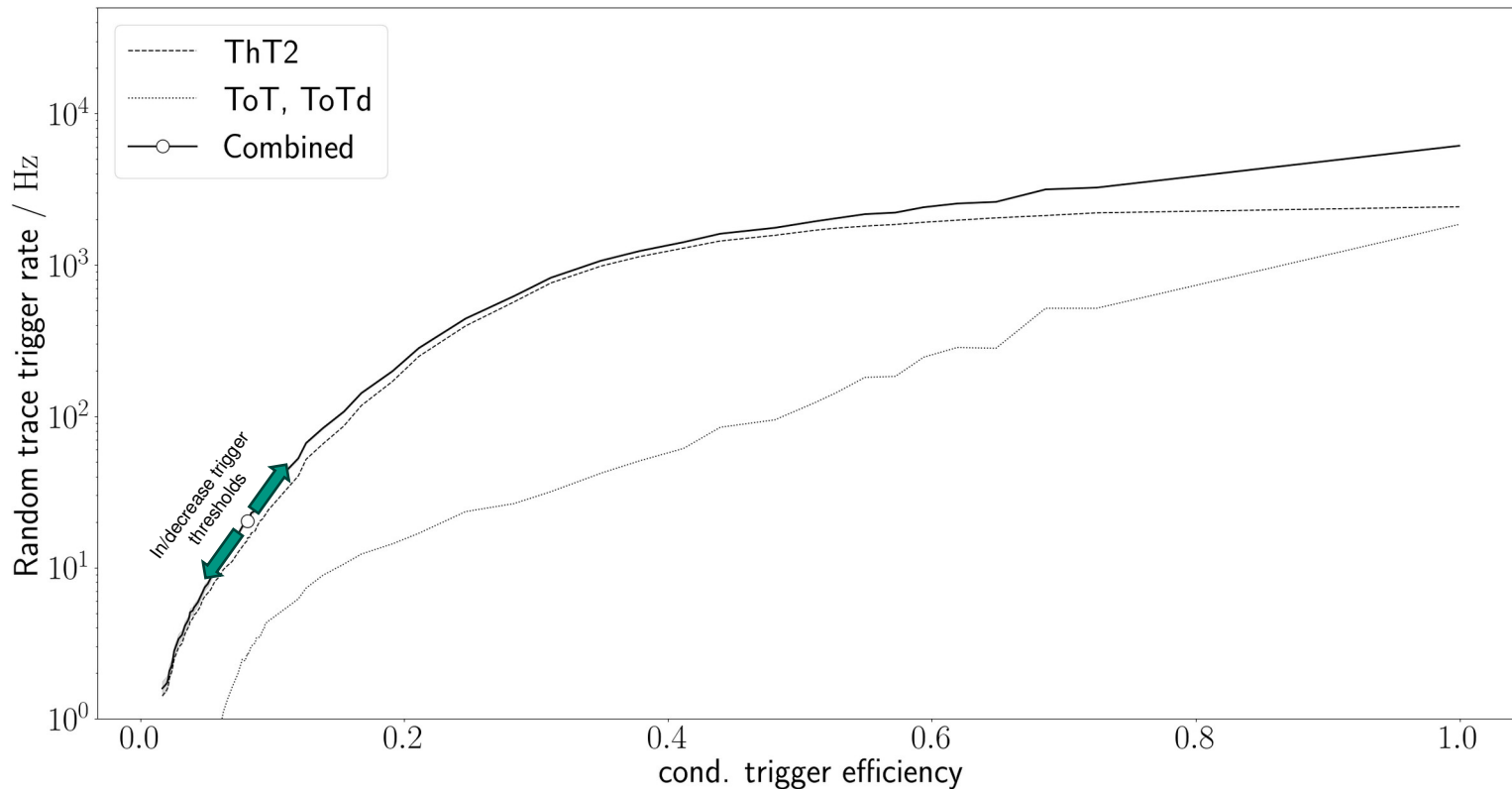
Comparing trigger efficiency



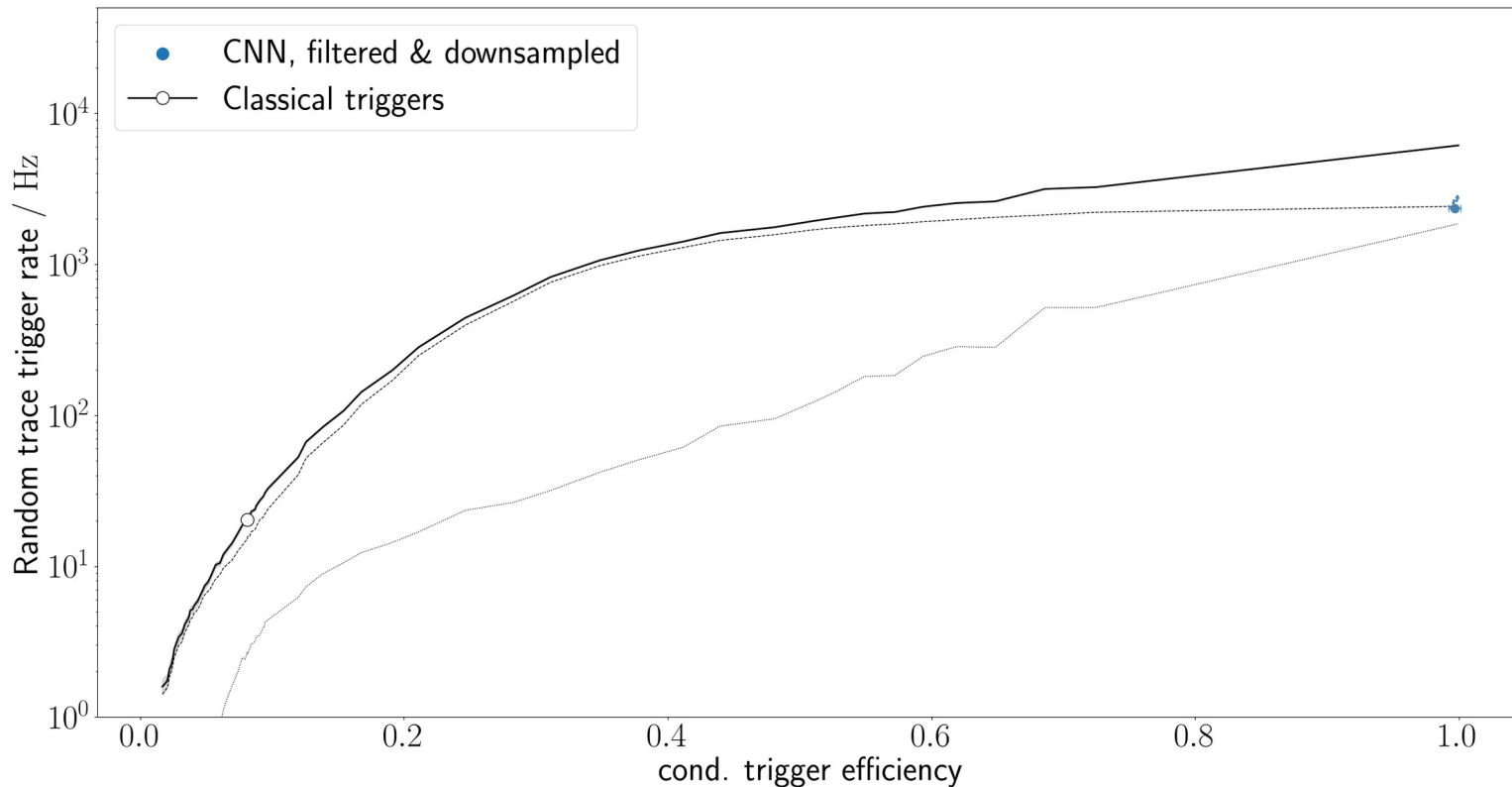
Comparing trigger efficiency



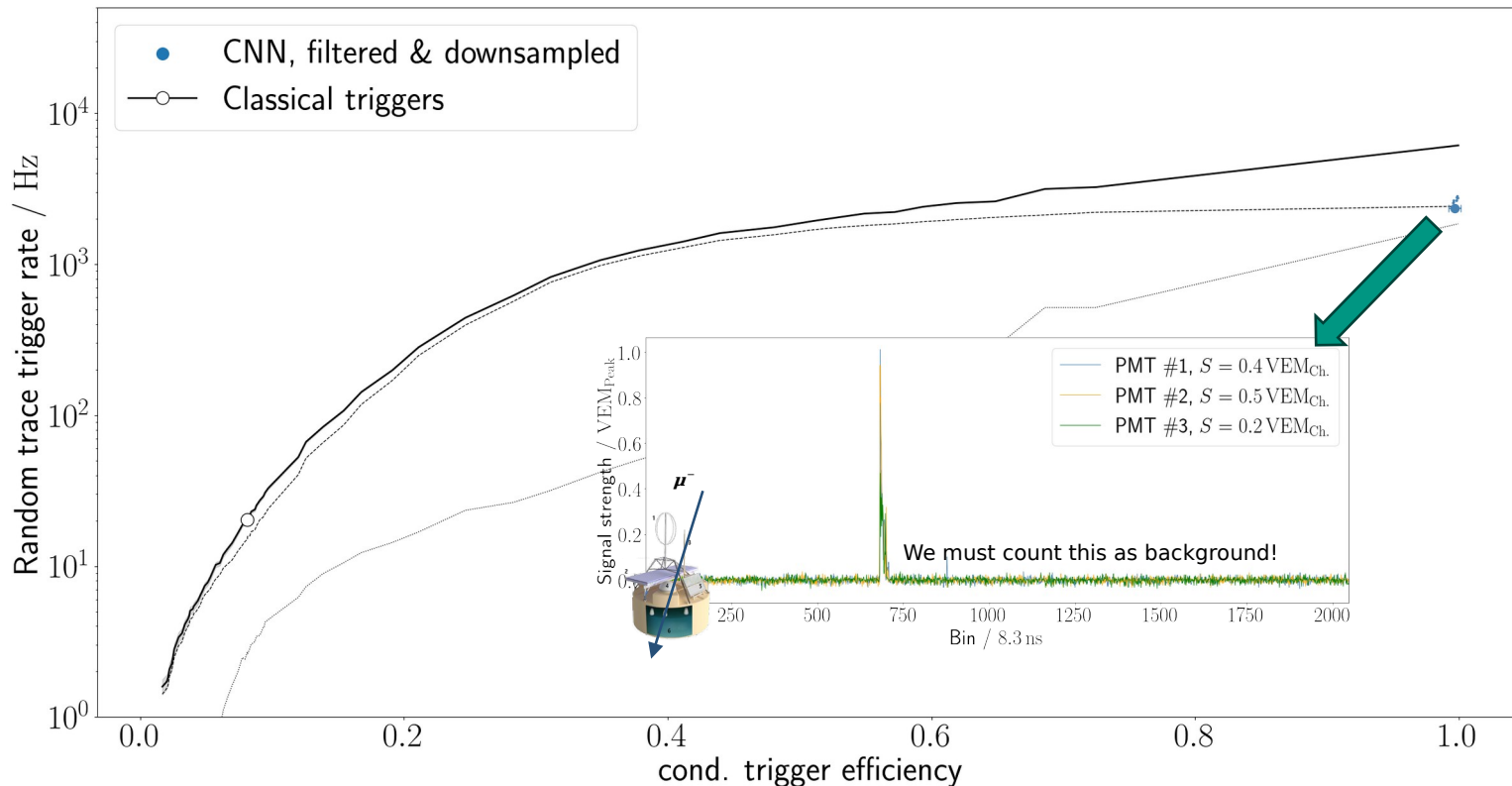
Comparing trigger efficiency



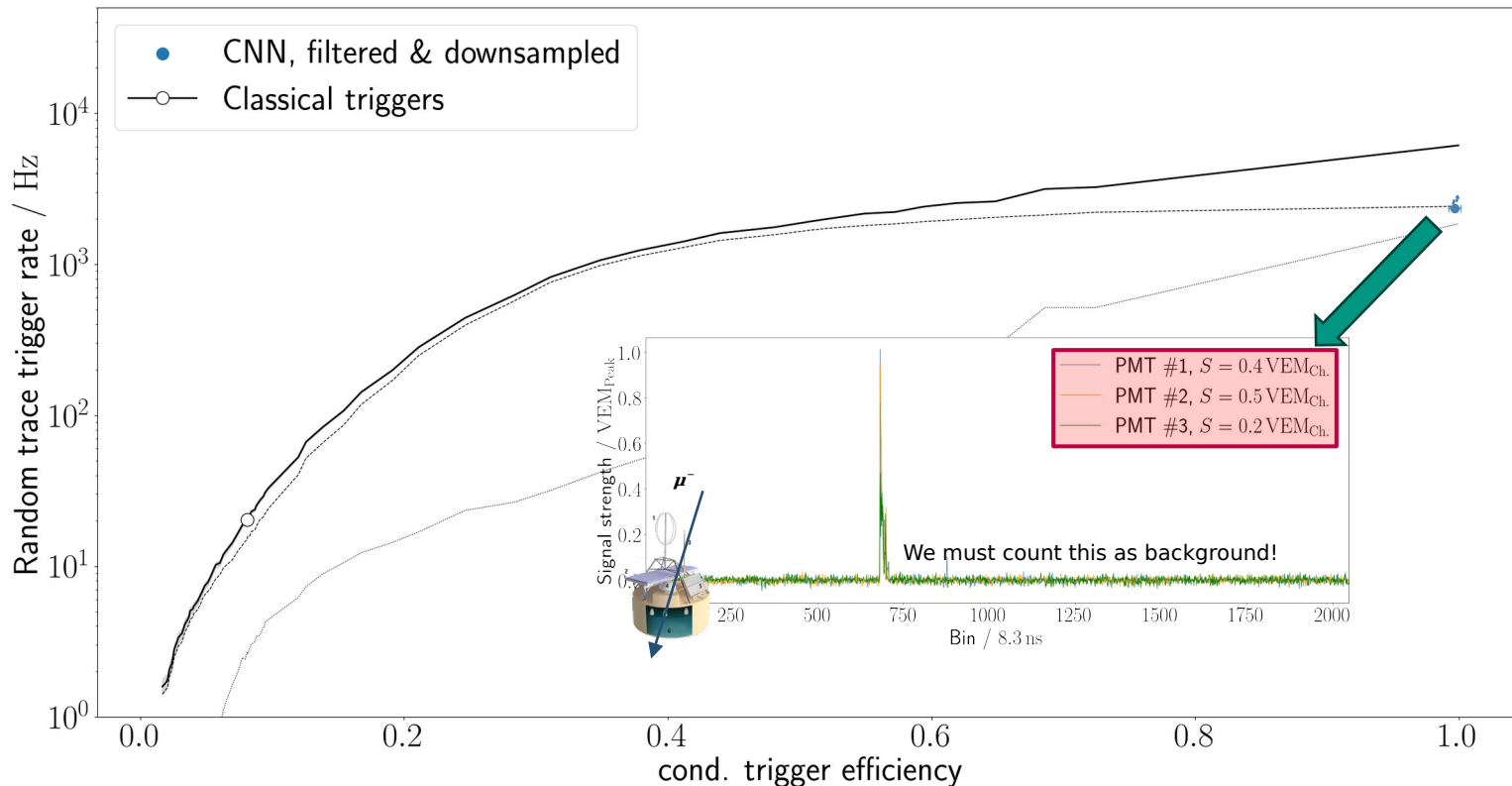
Comparing trigger efficiency



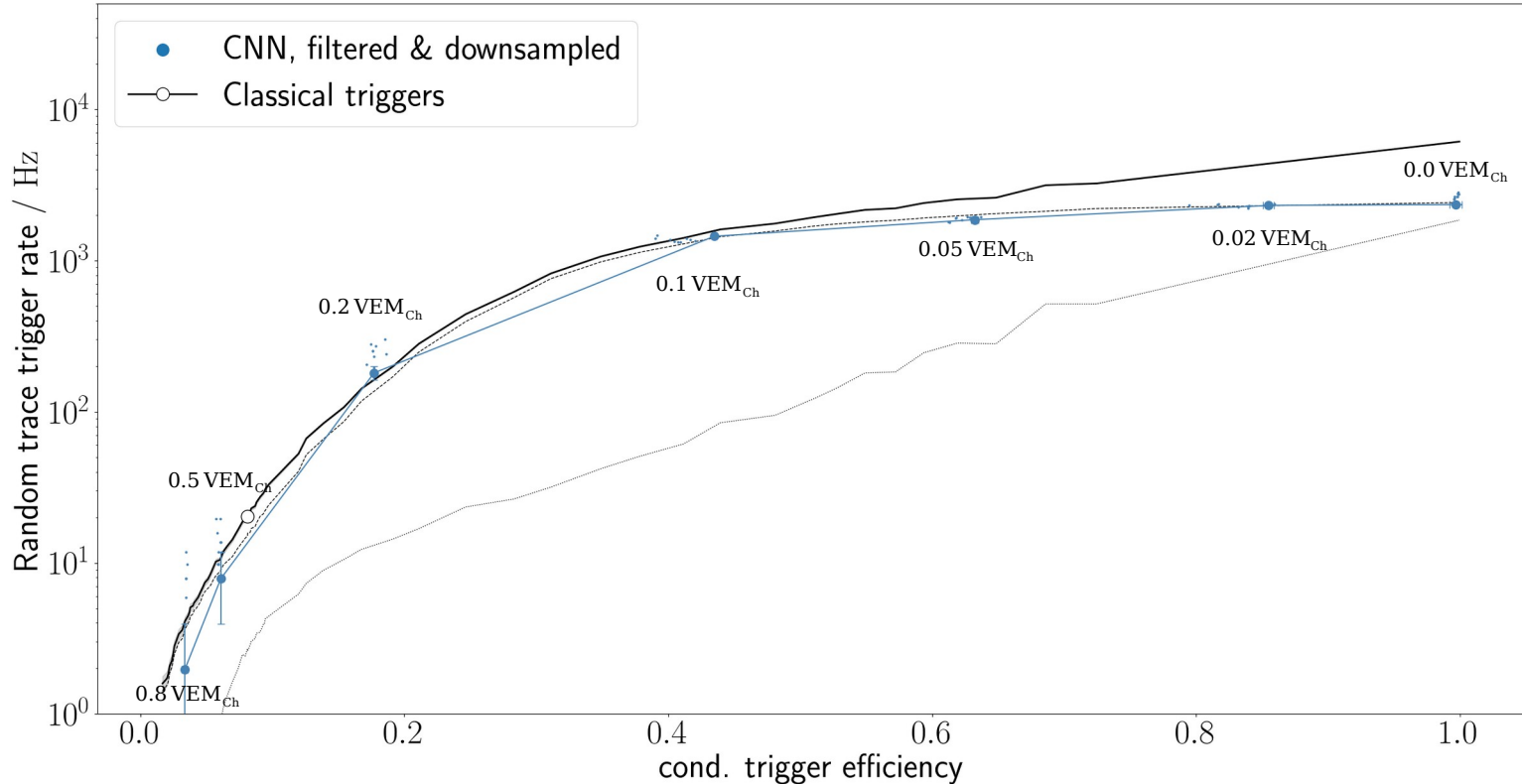
Comparing trigger efficiency



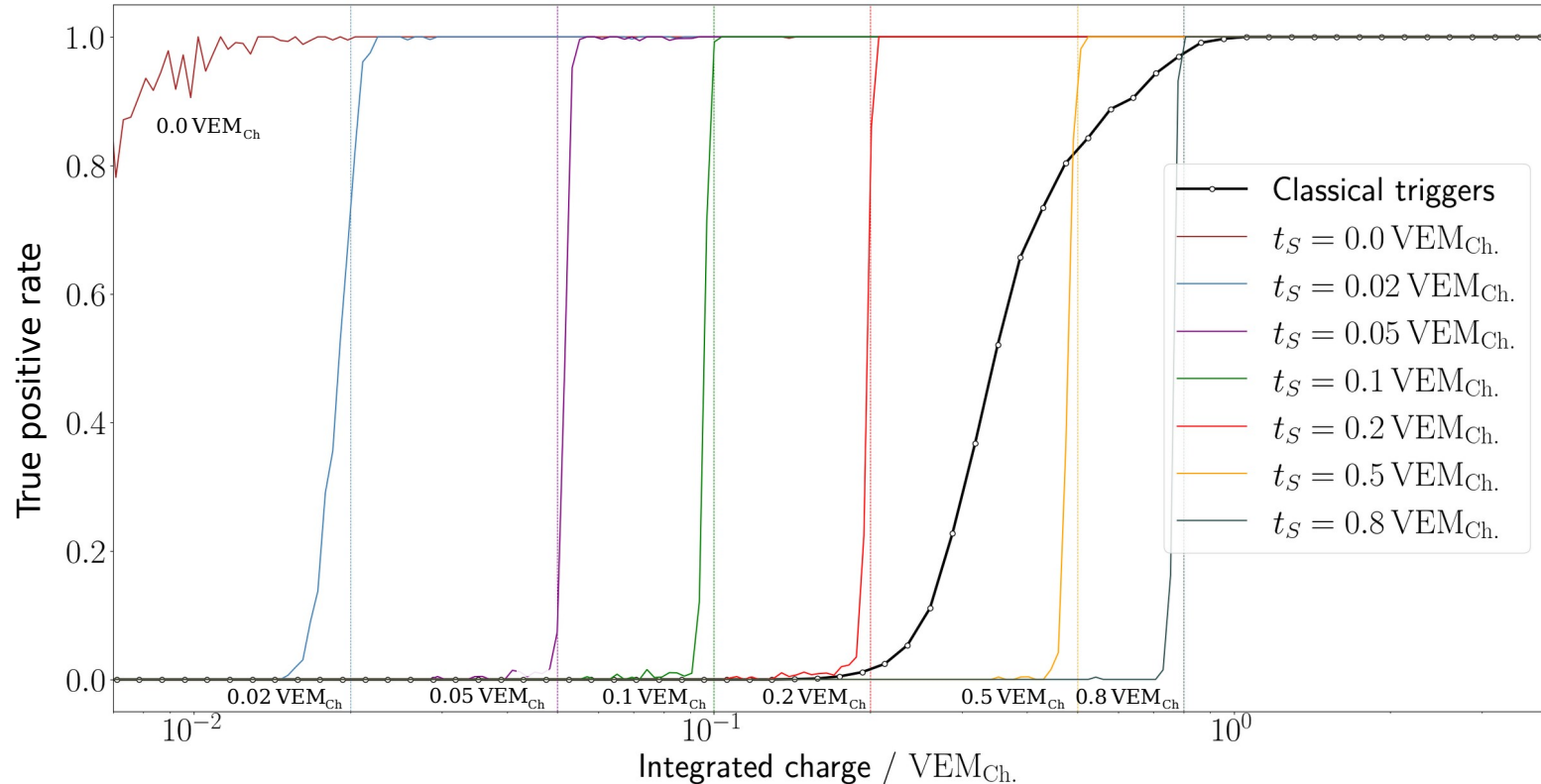
Comparing trigger efficiency



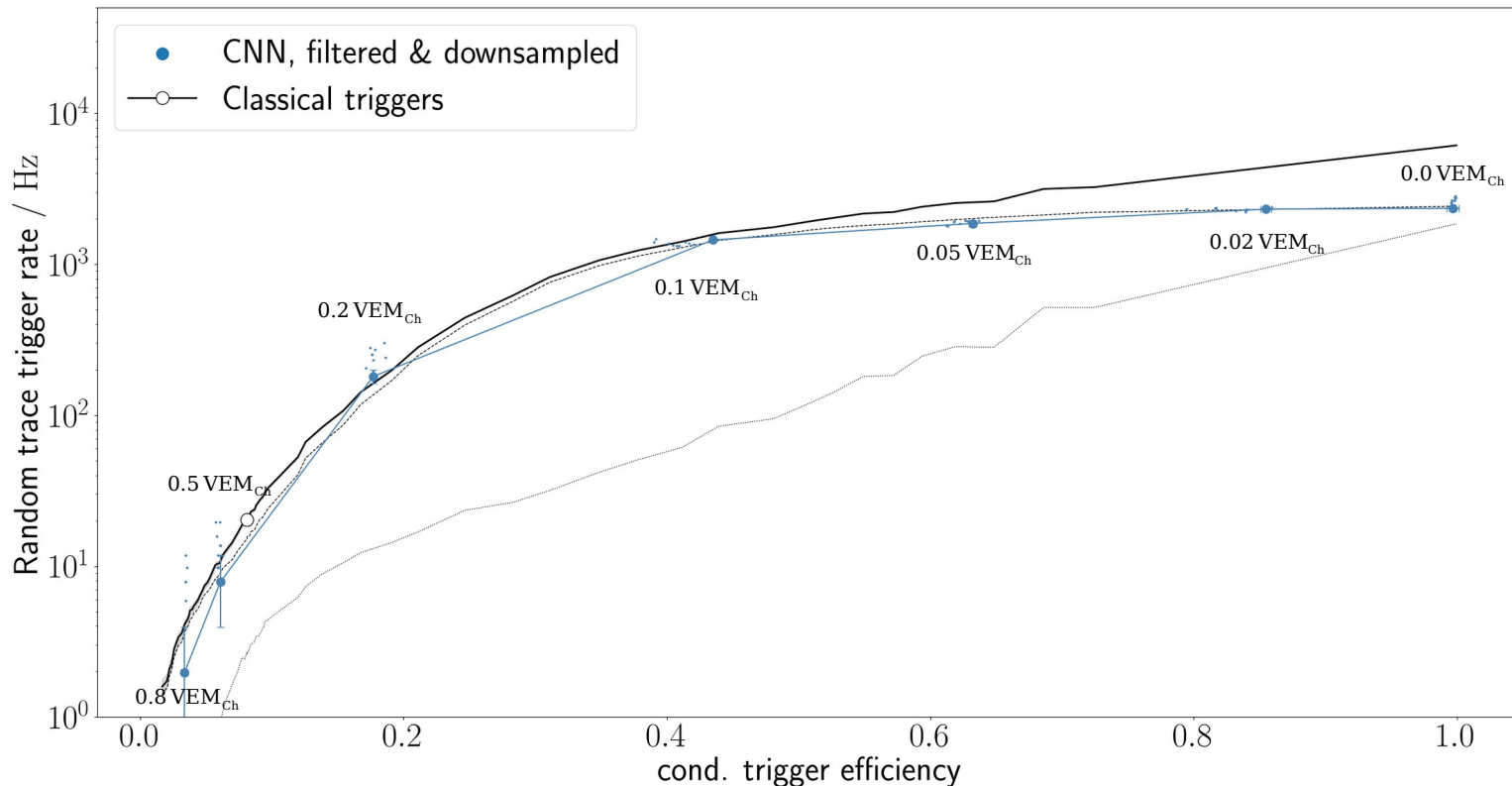
Comparing trigger efficiency



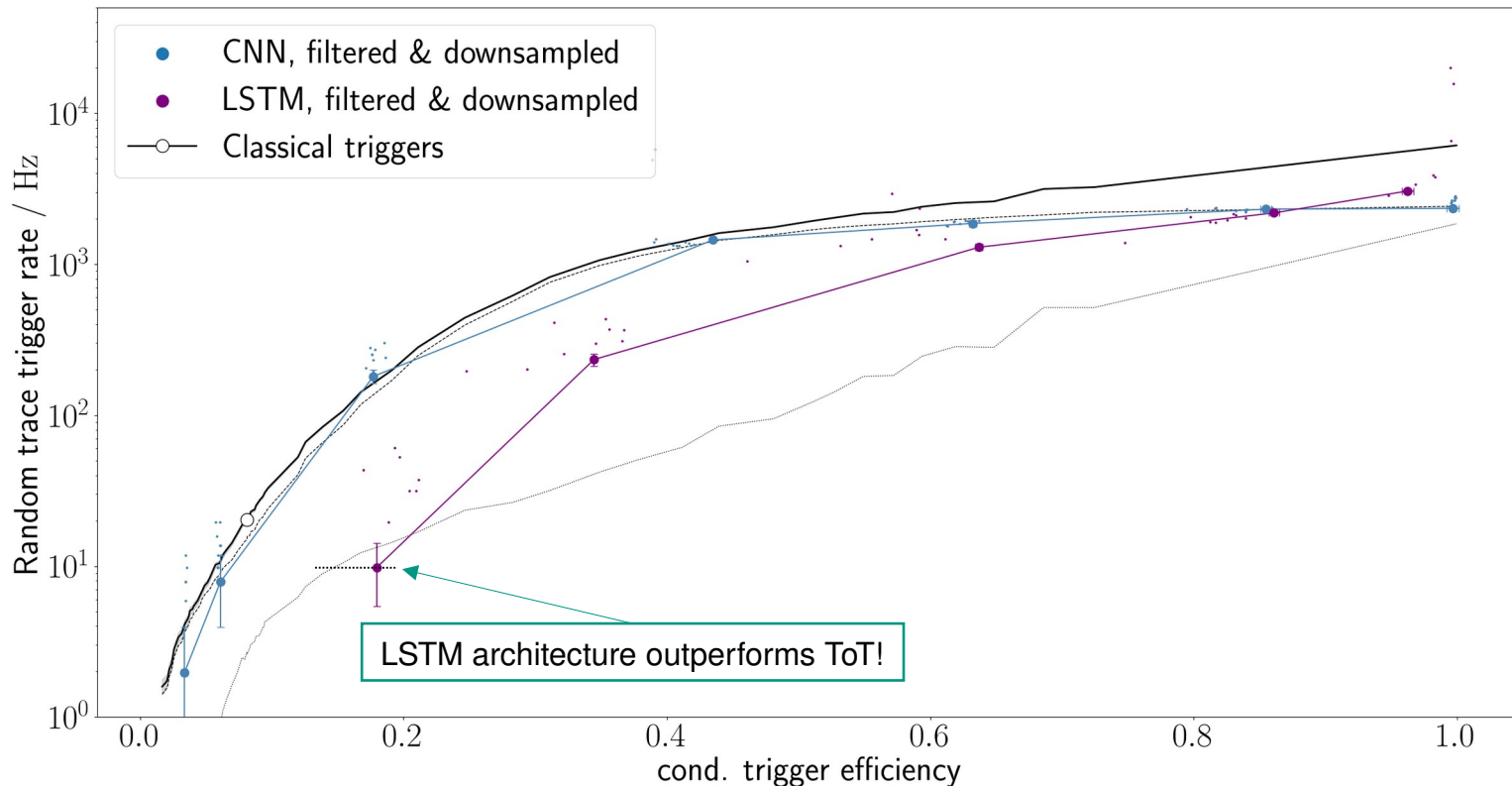
Sanity check – Charge cut



Comparing trigger efficiency

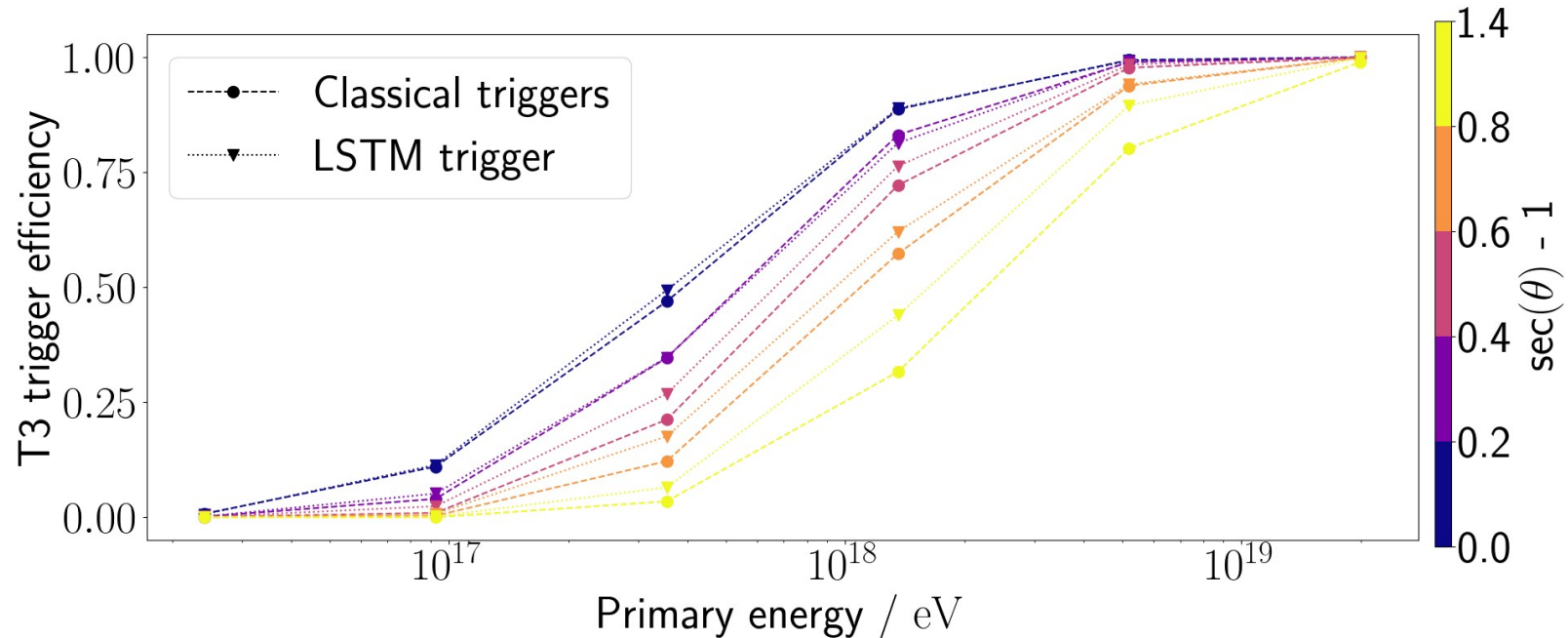


Comparing trigger efficiency



Resulting LSTM T3 efficiencies at $t_s = 0.5$ VEM

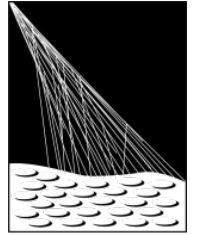
- Most drastic gains at high inclinations
- Possibly higher gains at $\theta \geq 65^\circ$



Summary

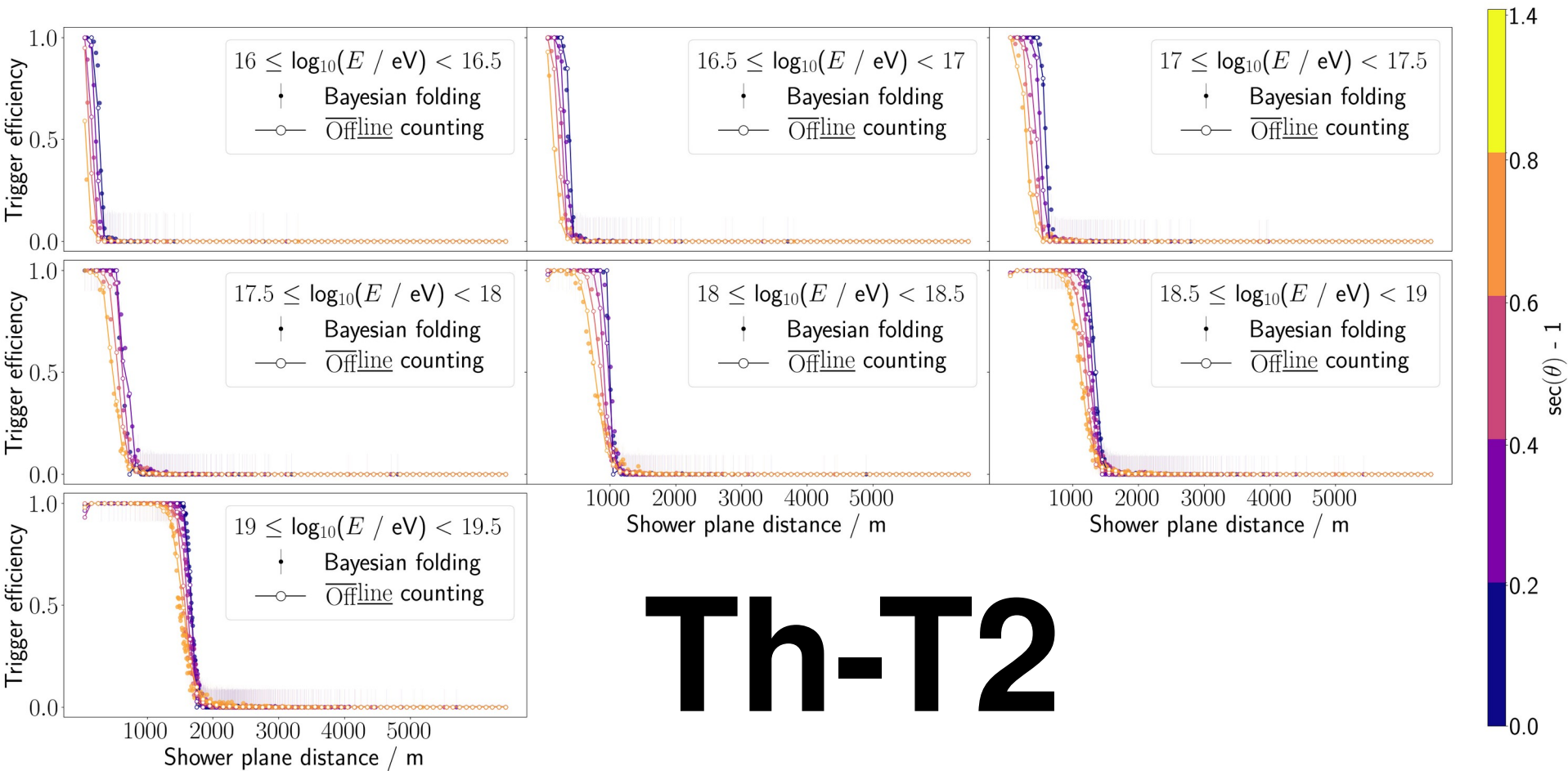
- **Test data-driven, machine learning concepts**
 - Analyse capability of shallow NNs (few parameters!) as SD T2-triggers
 - Consider convolutional (CNN) and simple recurrent neural networks (LSTM)
 - Verify performance of NNs with measured background data
 - Control trigger rate by implementing charge cut
- **Convolutional neural networks**
 - Performance of simple CNN architectures on par with Th-Trigger
 - CNN architecture has worse performance than ToT-trigger
 - Filtered & downsampled data preferred over full bandwidth input
- **LSTM / recurrent neural networks**
 - Results indicate performance on par with or better than ToT
 - Gains in event detection efficiency at high shower angles

Backup

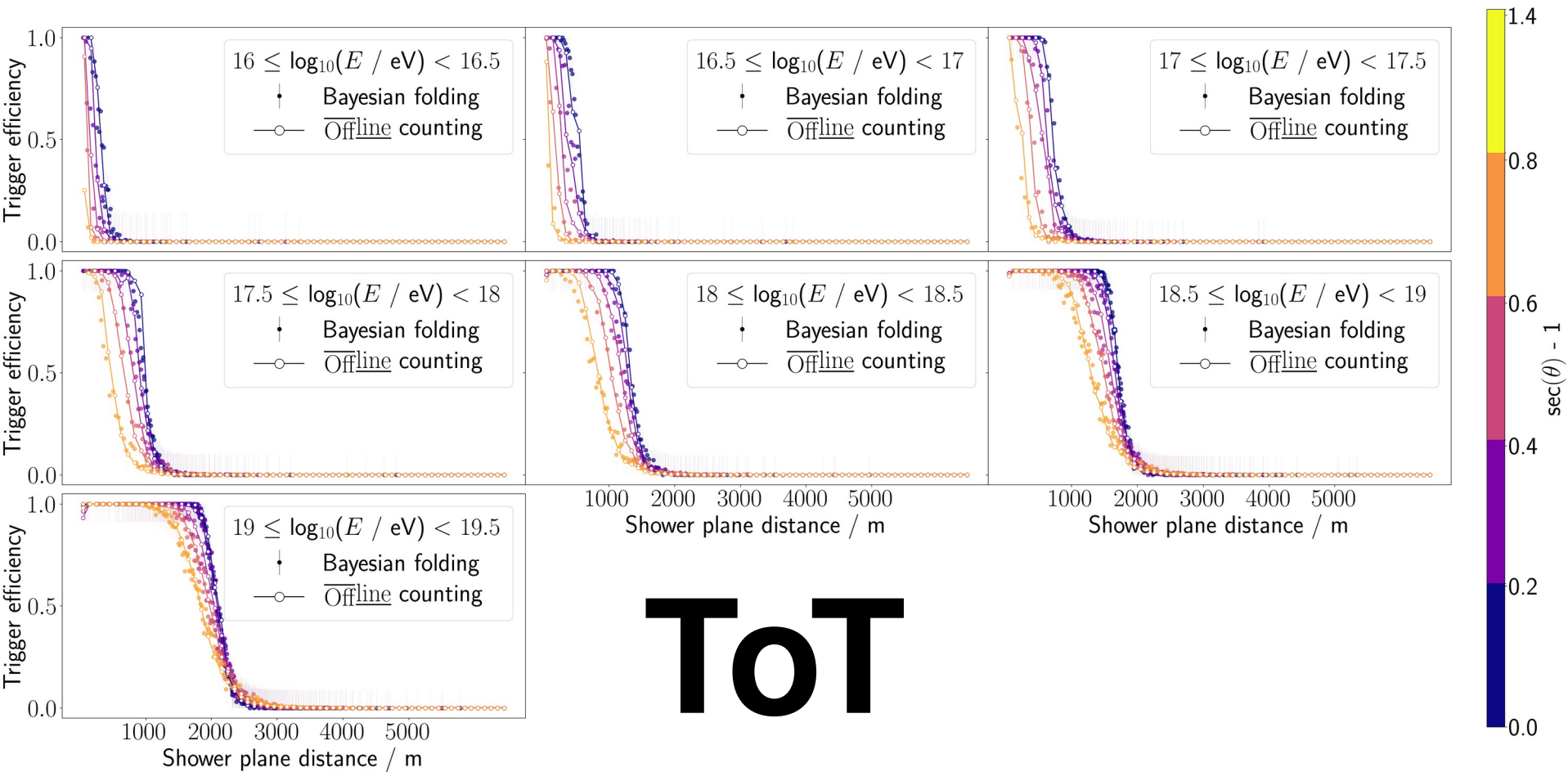


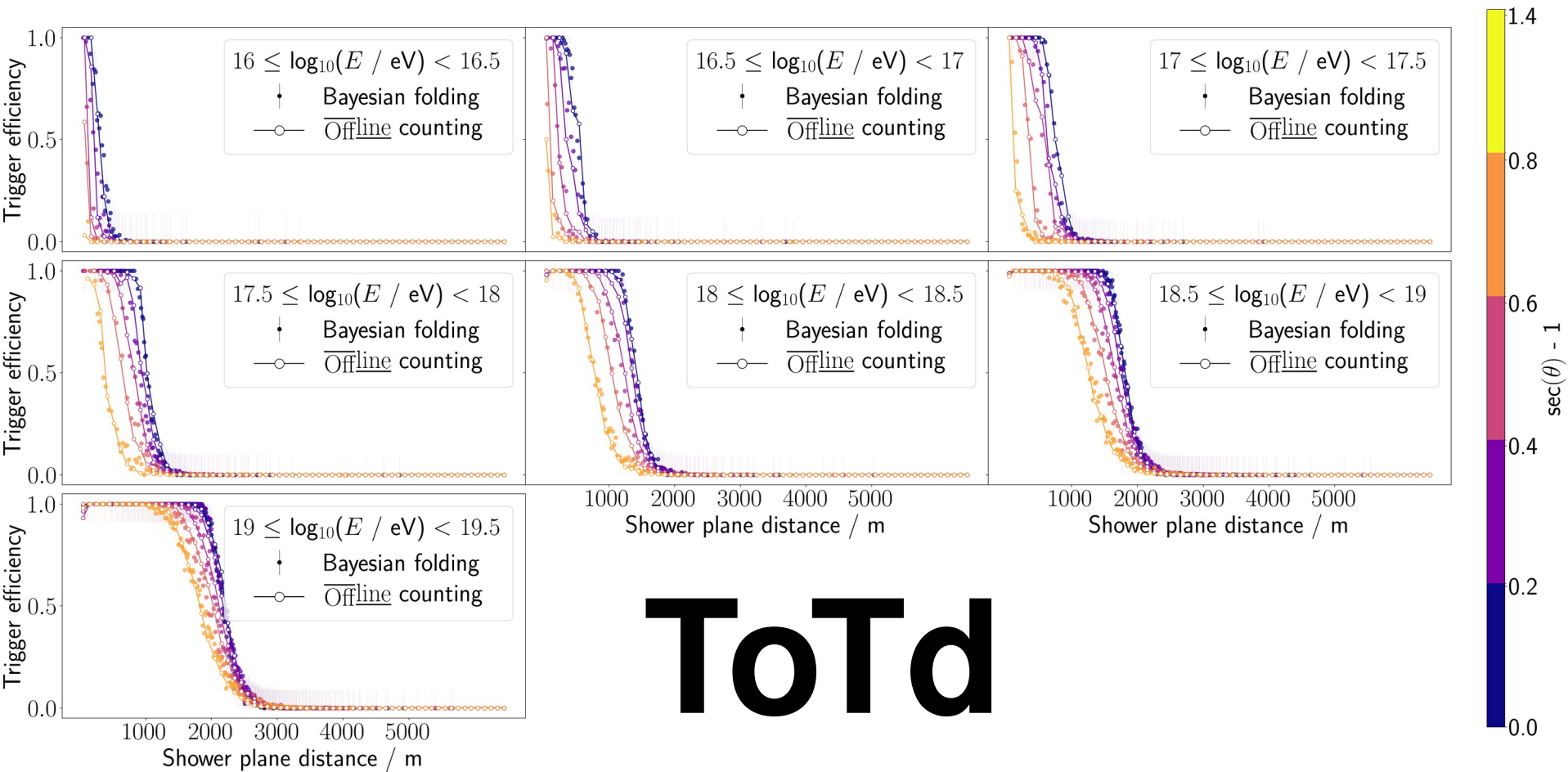
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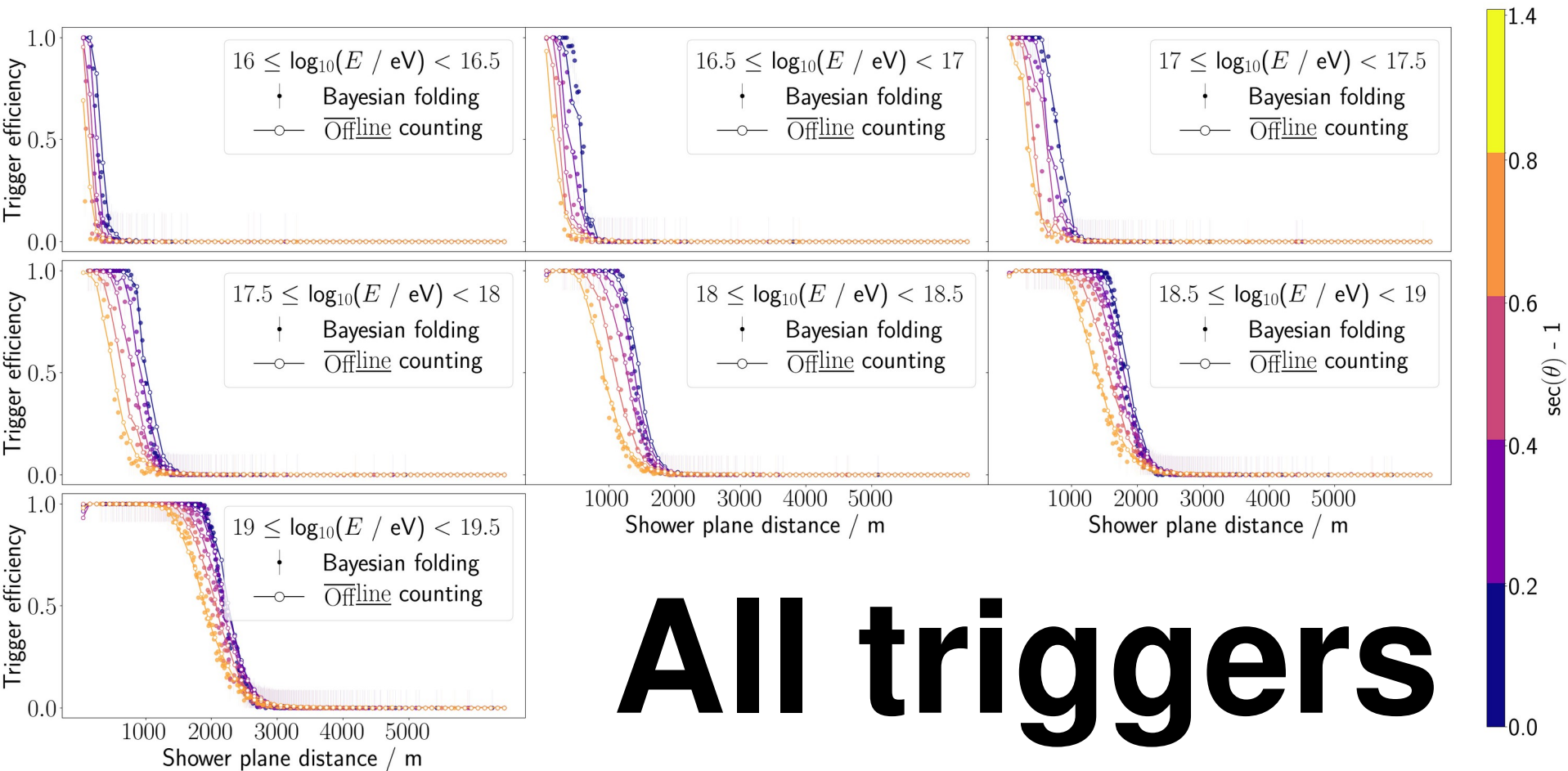


Th-T2



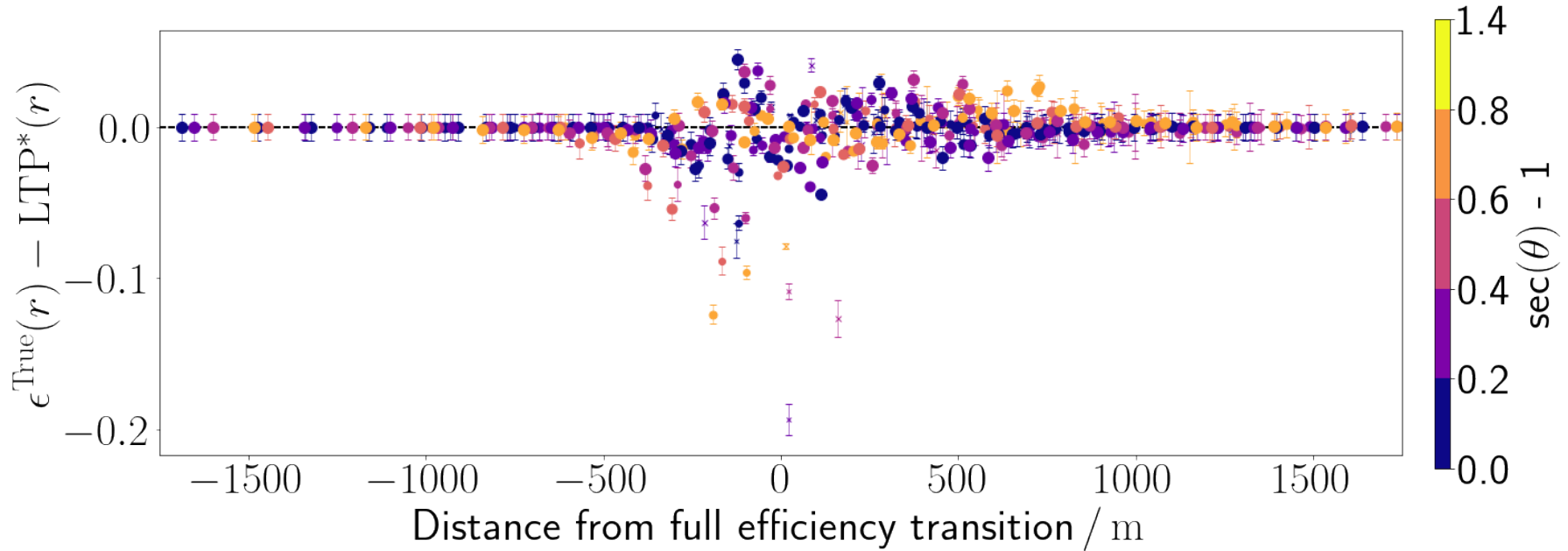


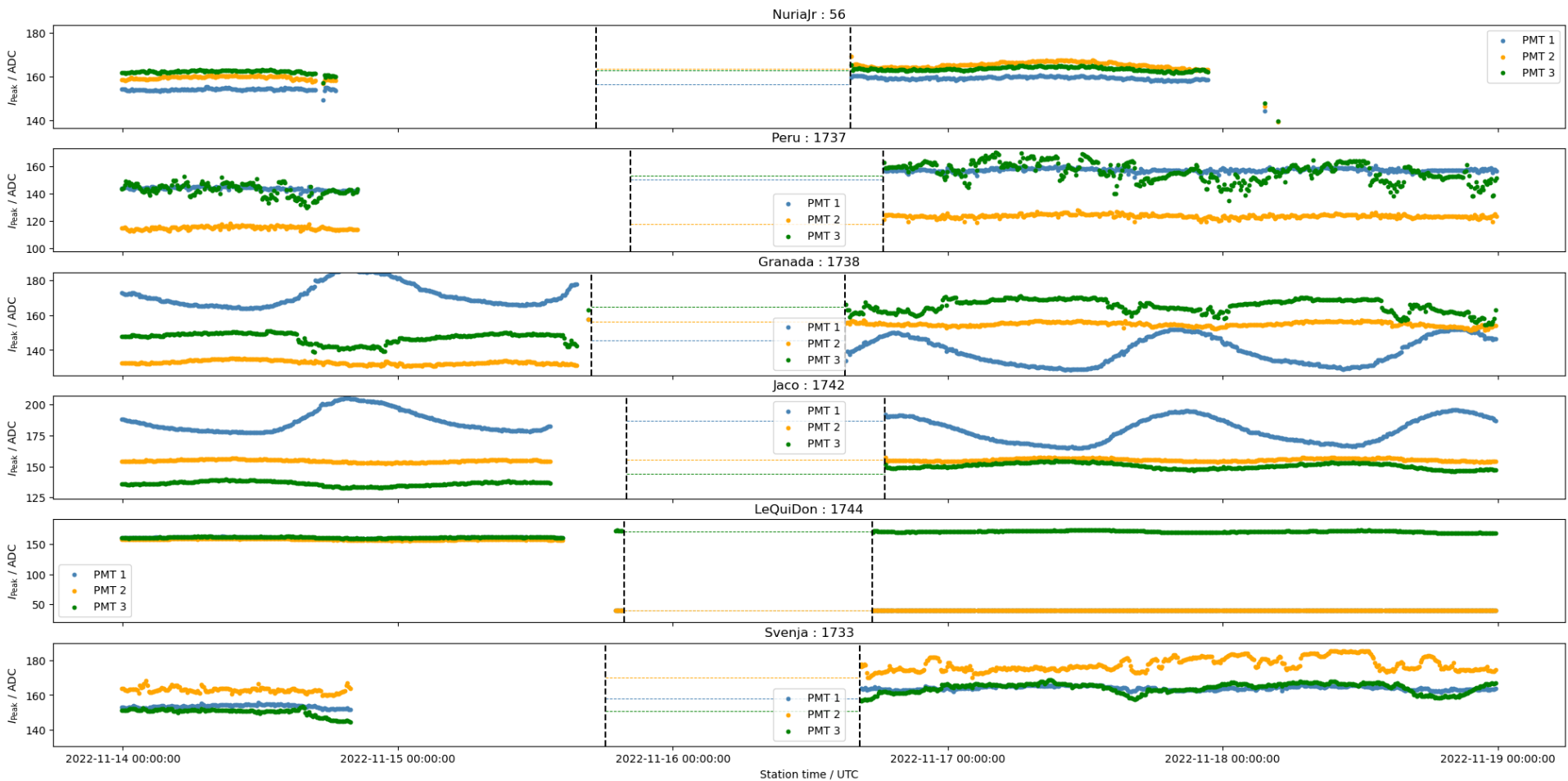
ToTd

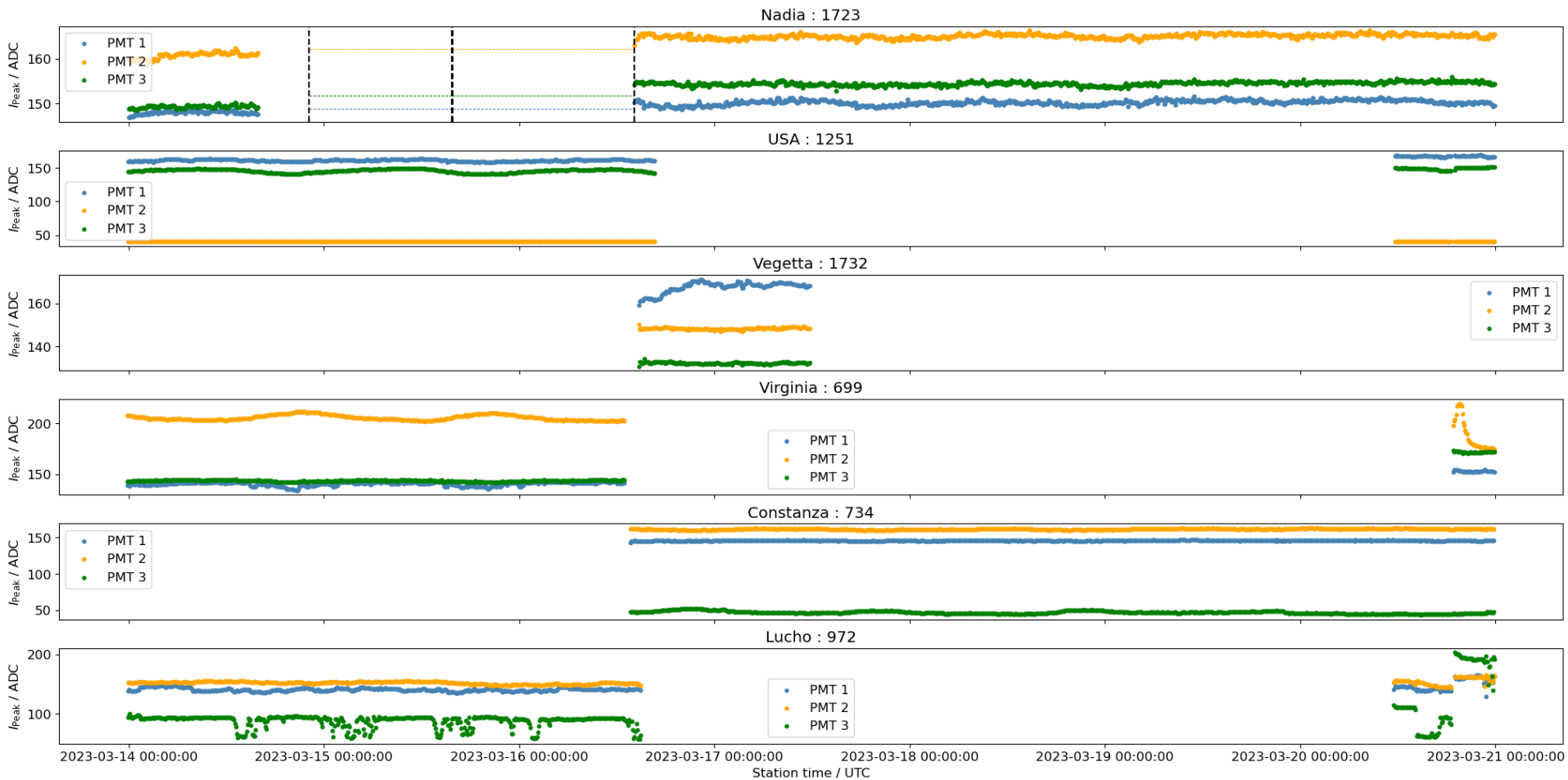


All triggers

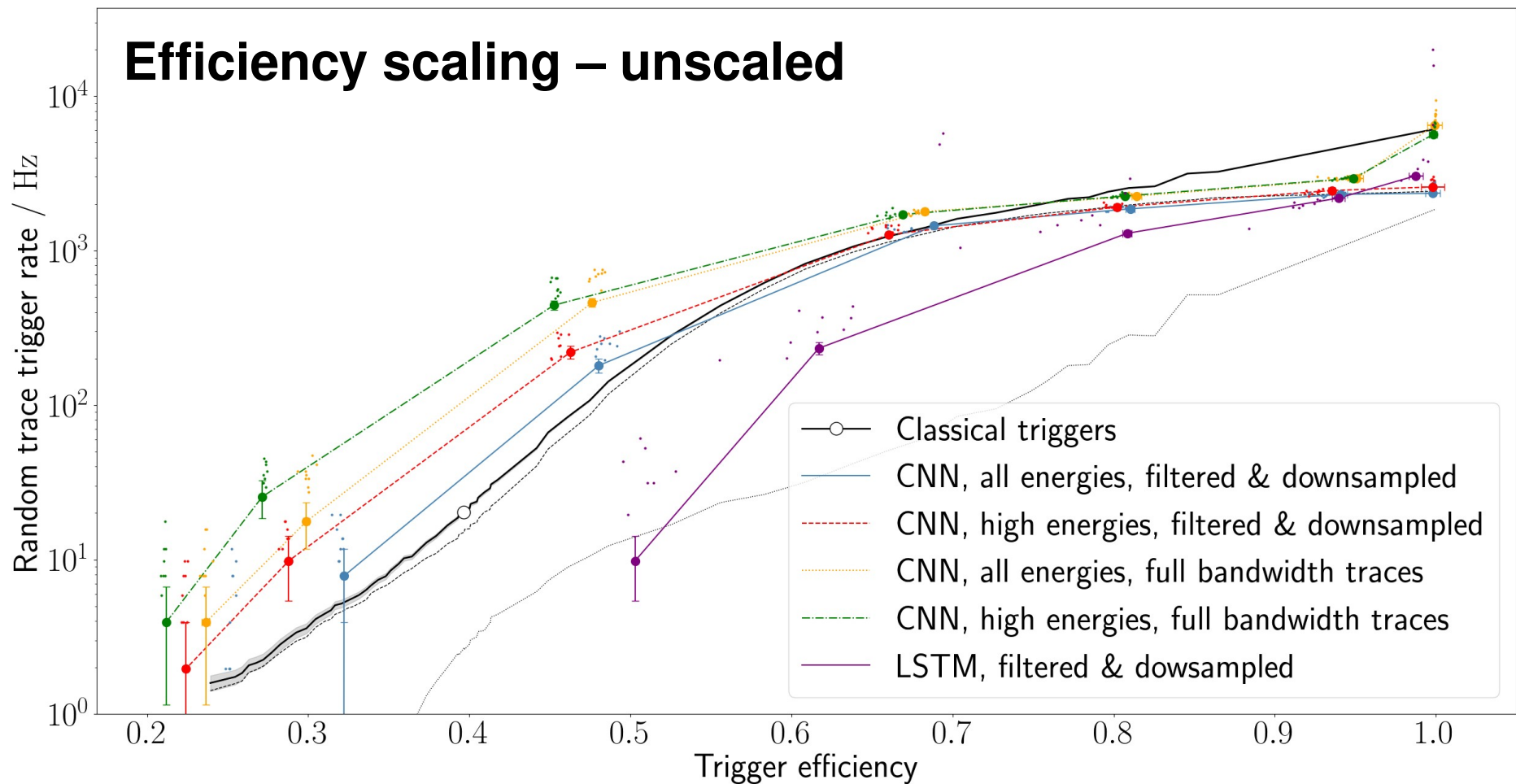
Residuals – LTP fitfunction







Efficiency scaling – unscaled



Efficiency scaling – scaled

Random trace trigger rate / Hz

10^4

10^3

10^2

10^1

10^0

0.0

0.2

0.4

0.6

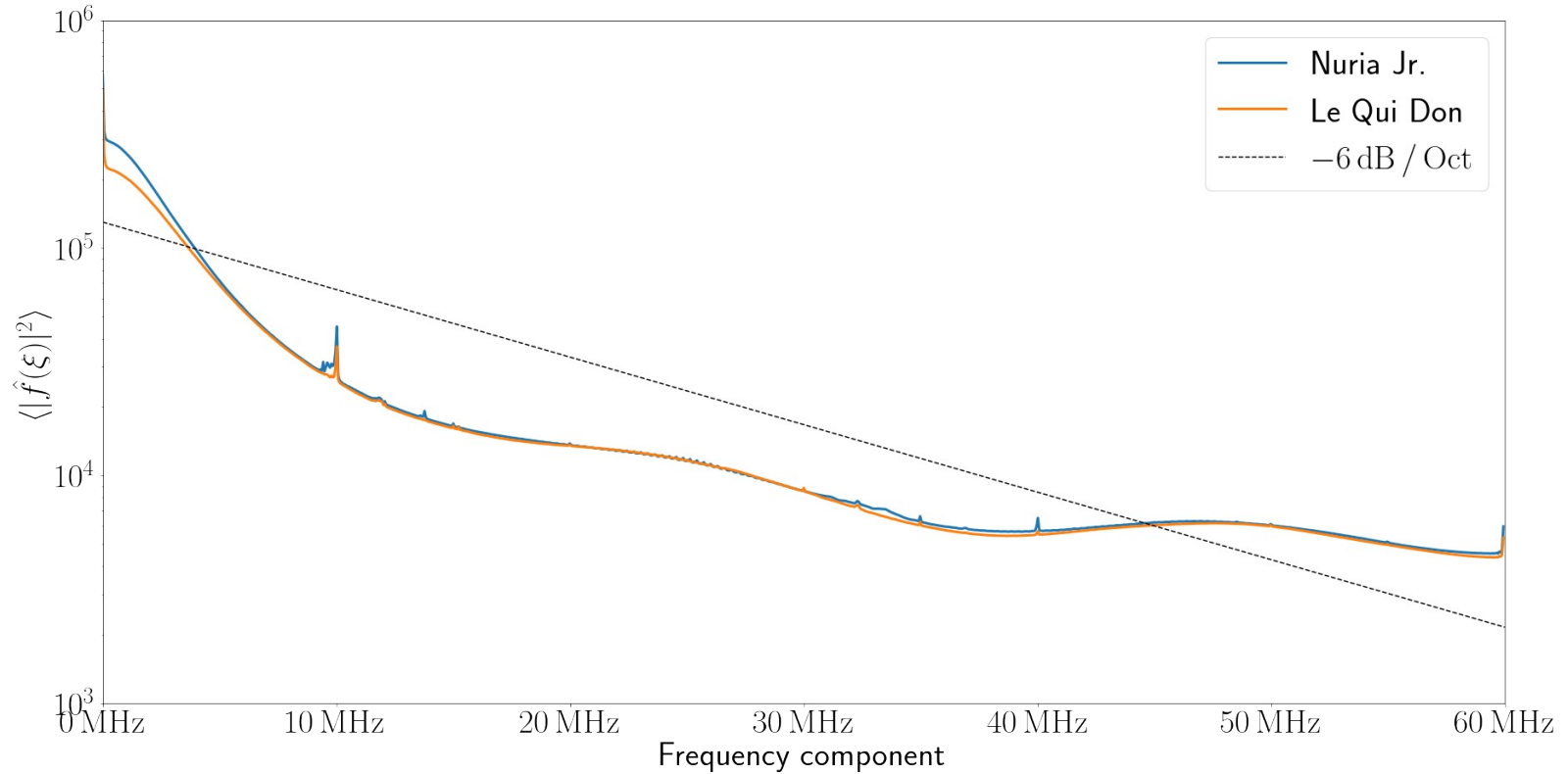
0.8

1.0

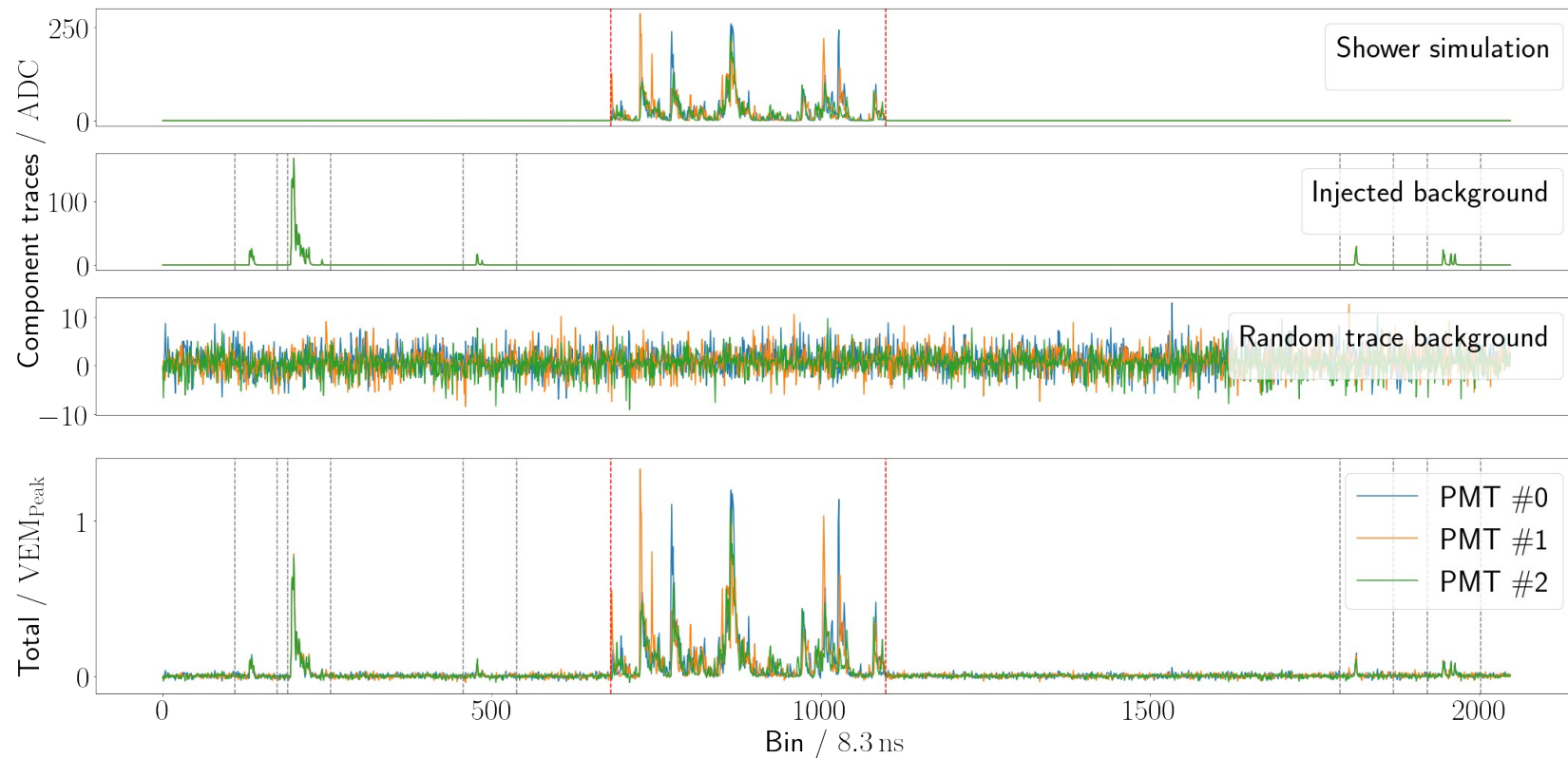
Trigger efficiency

- Classical triggers
- CNN, all energies, filtered & downsampled
- - CNN, high energies, filtered & downsampled
- ⋯ CNN, all energies, full bandwidth traces
- · - CNN, high energies, full bandwidth traces
- LSTM, filtered & downsampled

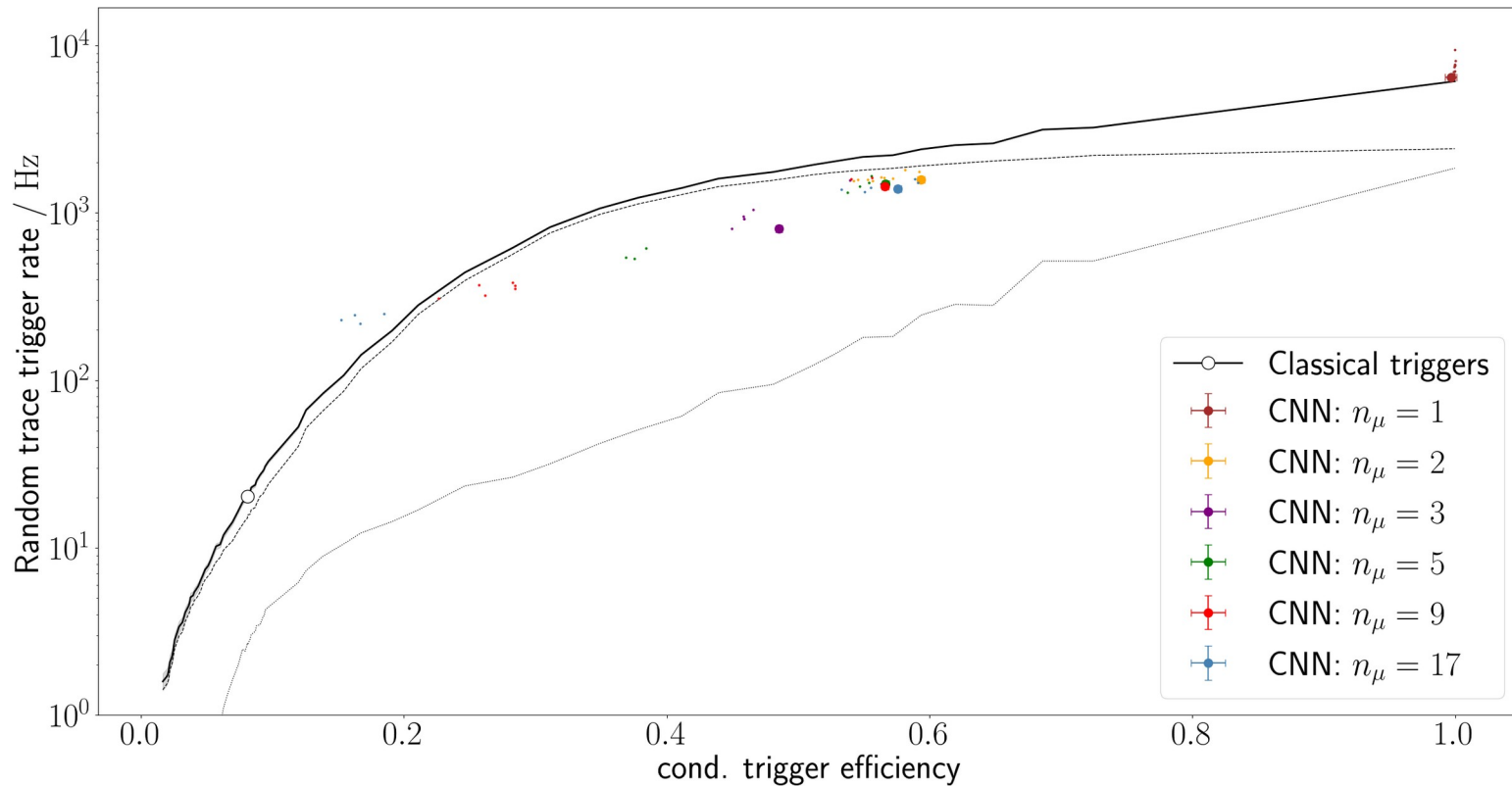
Random traces – Power spectrum



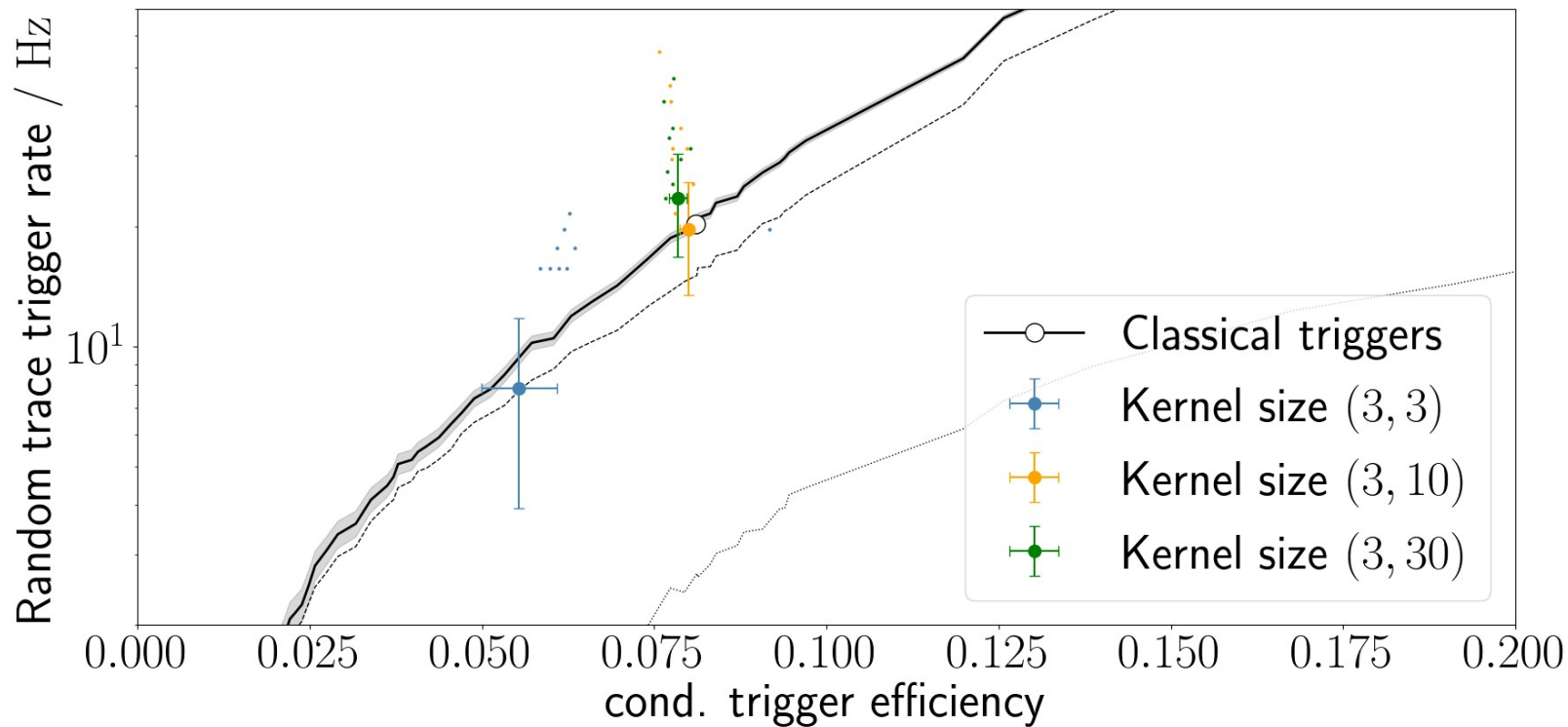
Trace building



Muon cut



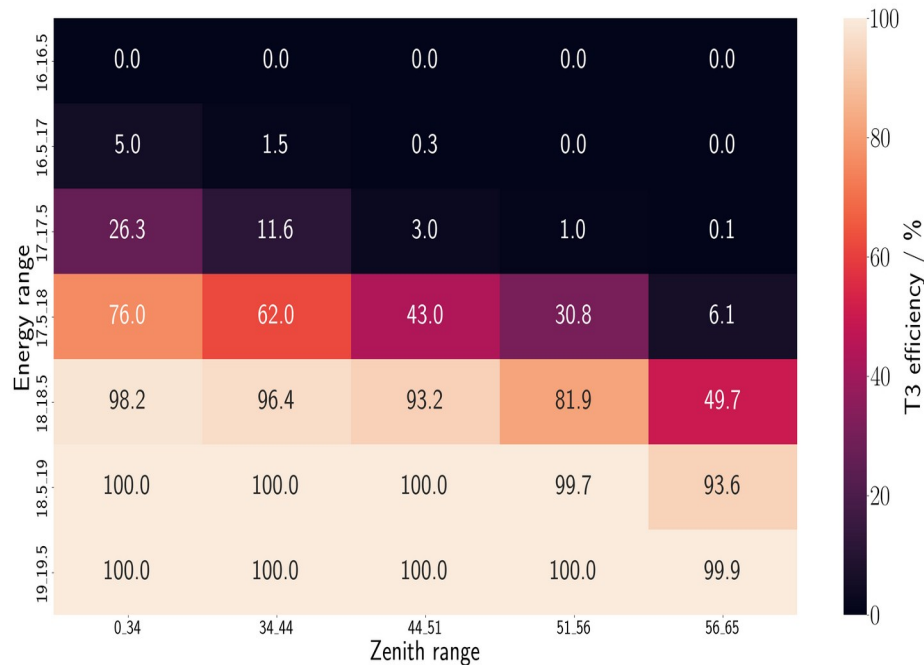
Kernel size



T3 efficiency calculation

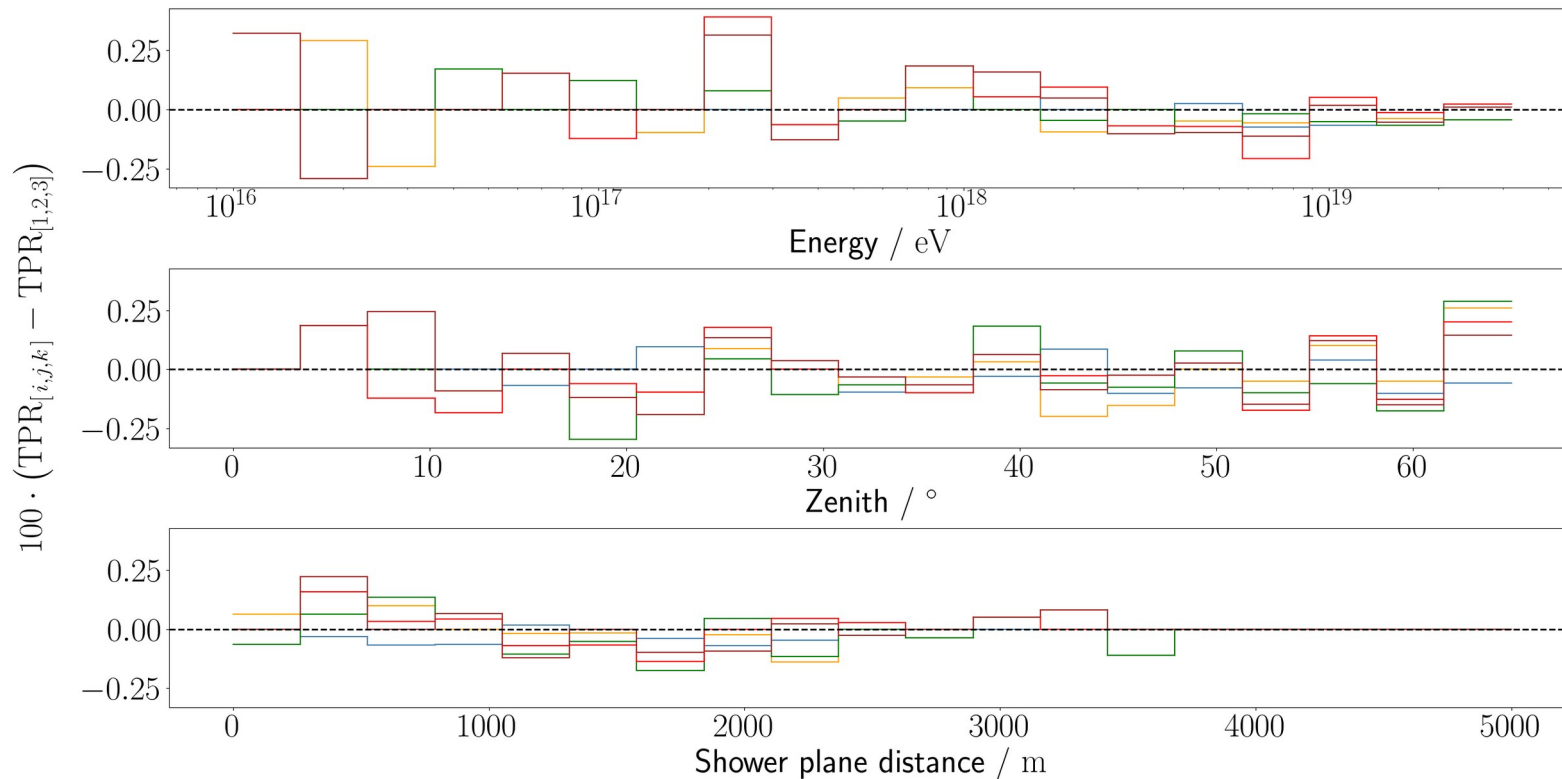


Offline approach



Bayesian folding

LSTM permutations



Network parameters

Type	Input size	Kernel size	n_{train}	w/ dense extension
CNN	(3, 120)	(3, 3)	140	834
CNN	(3, 120)	(3, 10)	216	534
CNN	(3, 120)	(3, 30)	444	714
CNN	(3, 40)	(3, 3)	84	210
CNN	(3, 60)	(3, 3)	100	290
CNN	(3, 90)	(3, 3)	120	390
CNN	(3, 240)	(3, 3)	220	890
LSTM	(3, 120)	–	12	(single layer)
LSTM	(3, 120)	–	(three layers)	44