



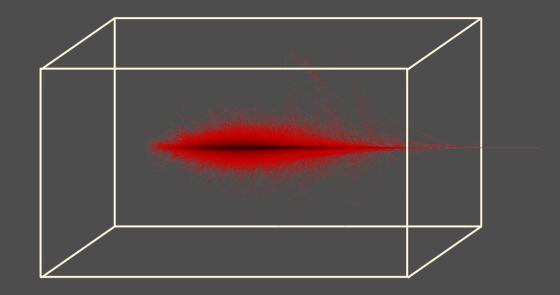
UNSAM

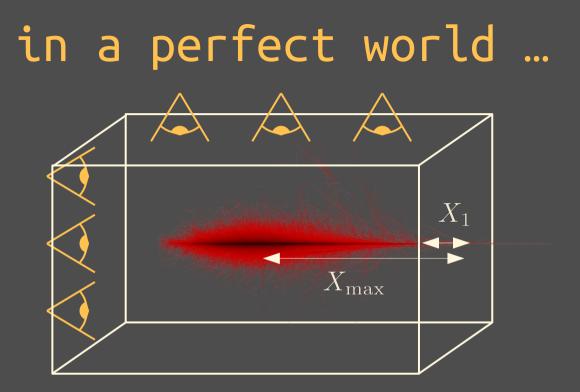
UNIVERSIDAD NACIONAL DE SAN MARTÍN



News on Universality-v2 Max Stadelmaier, supervised by Ralph Engel & Markus Roth Federico Sanchez

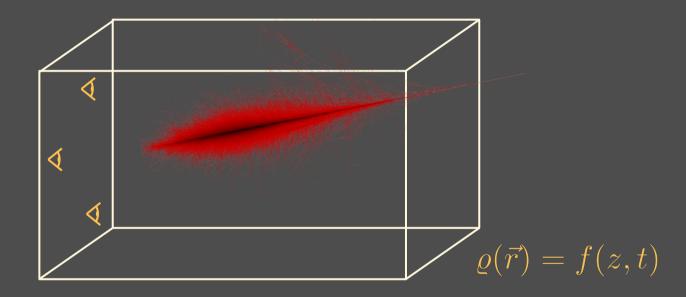
in a perfect world ...





 $\varrho(\vec{r}) = const. \Rightarrow \sigma \simeq \frac{\varrho}{\langle X_1 \rangle}$





- The atmosphere is not homogeneous, and
- we can not detect all particles or all light emitted by an air shower.

The solution: Universality

• Universality solves this issues by taking use of the fact that the development of air showers is very similar (*universal*), given only a few input parameters:

$$E, \vec{r}, R_{\mu}, X_{\max}$$

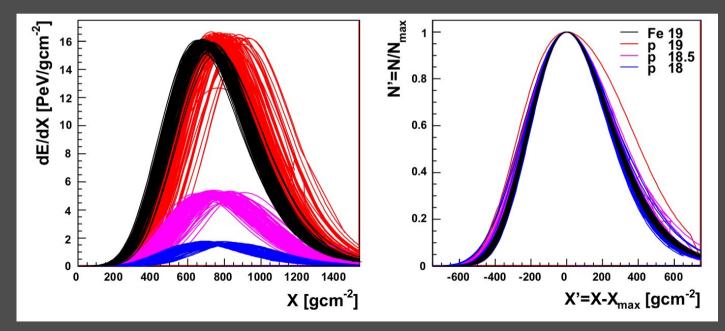
The solution: Universality

• Universality solves this issues by taking use of the fact that the development of air showers is very similar (*universal*), given only a few input parameters:

 $E, \vec{r}, (R_{\mu}, X_{\max})$

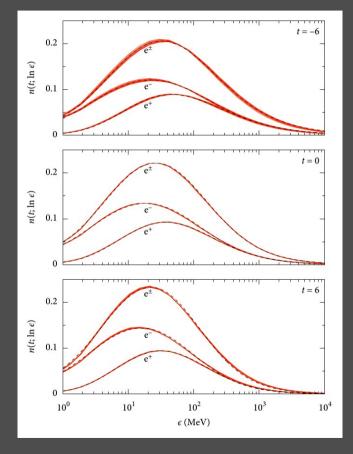
primary mass dependent!

• Shape (energy deposit per depth) is universal w.r.t. $DX := X - X_{\max}$



[S. Andringa, R. Conceição, M. Pimenta, 2010]

• Energy spectrum of most particles is universal w.r.t. $DX := X - X_{\max}$



[S. Lafebre, R. Engel, H. Falcke, J. Hörandel T. Huege, J. Kuijpers, R. Ulrich, 2009]

 The signal can be parametrized using a (modified) Gaisser-Hillas function.

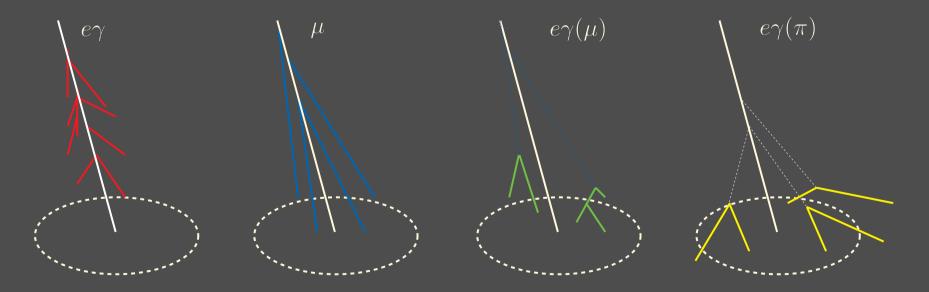
$$S(\vec{r}) = \sum_{i=1}^{4} S_{\text{ref}}^{i}(r) f_{\text{mod}}^{i}(\psi, r) f_{R_{\mu}}^{i} \left(\frac{E}{E_{\text{ref}}}\right)^{\gamma} \left(\frac{DX - DX_{0}}{DX_{\text{ref}} - DX_{0}}\right)^{\frac{DX_{\text{max}} - DX_{0}}{\lambda}} e^{-\frac{DX - DX_{\text{ref}}}{\lambda}}$$

[M. Ave, R. Engel, M. Roth, A. Schulz, 2016]

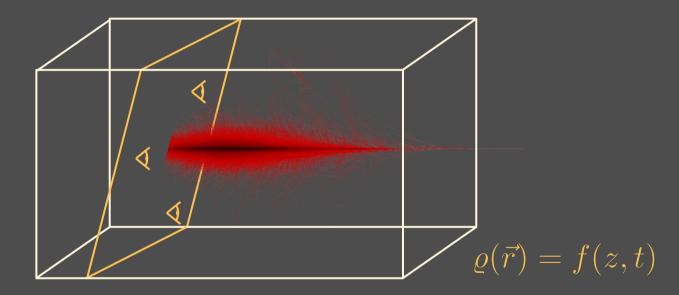
• Also the time-dependent signal structure can be parametrized, using a log-normal function.

[M. Ave, M. Roth, A. Schulz, 2016]

• The parametrization is done individually for all detectors and particle components.



Back to reality



• Given a two-dimensional cut through the shower (ground level), the whole shower shape can be reconstructed.

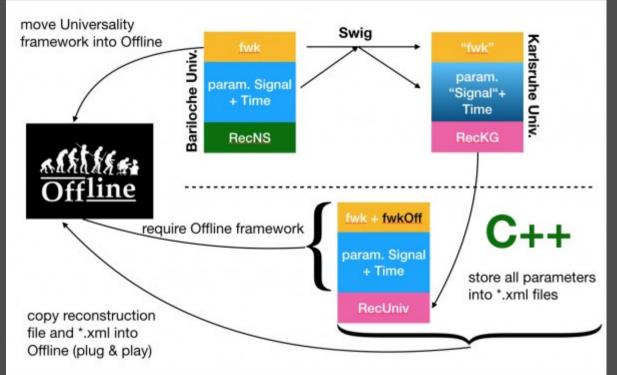
Status of Universality

- Two frameworks present: Karlsruhe and Bariloche. Both have their own advantages and disadvantages.
- Both frameworks use an ideal detector response function (not sensitive to fluctuations).
- Both frameworks hard to further develop.

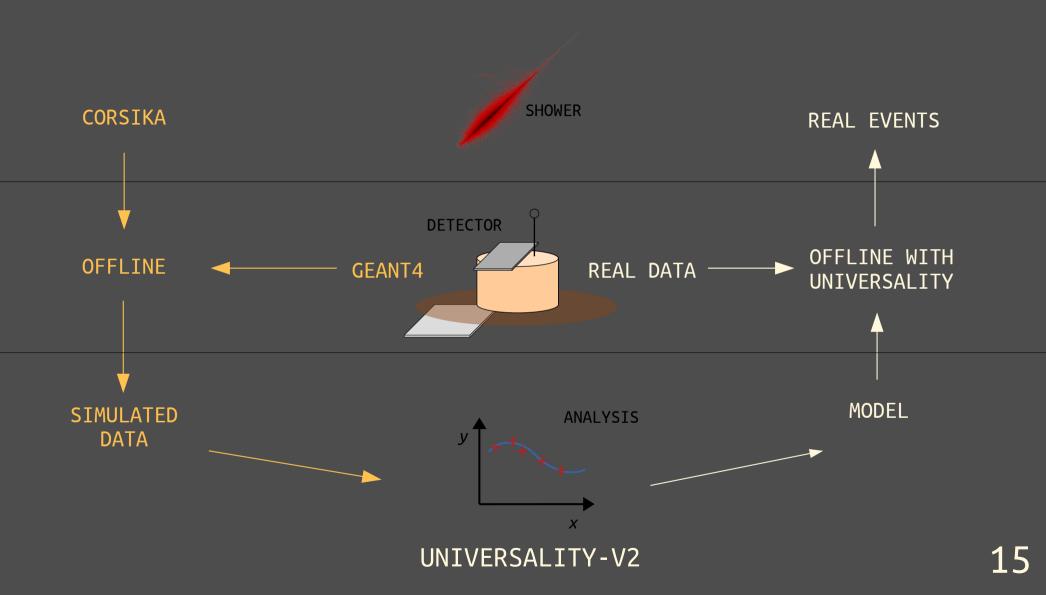
Start over! → Universality-v2

Code overview

- Avoid mixing of programming languages
- Use easy-tohandle file formats
- Use full Offline simulations



[J. Hulsman] 14



Universality-v2

• Currently in development

• Find it on git:

https://gitlab.ikp.kit.edu/showeruniversality/universality-v2

Offline simulations

45°

2000

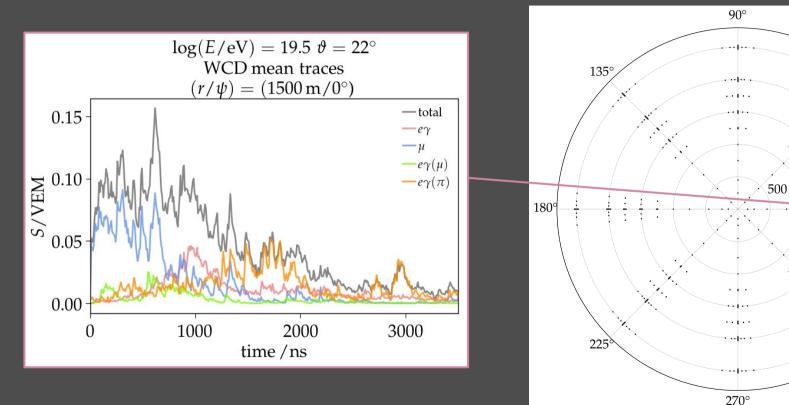
315°

1500

1000

2500

0°



https://gitlab.ikp.kit.edu/shower-universality/universality-v2/blob/master/
python/denseGenerator.py.in

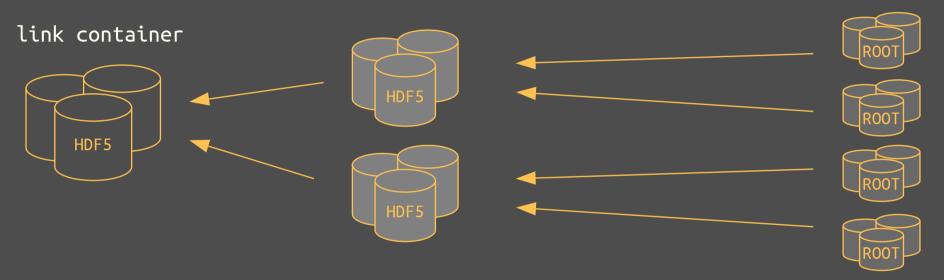
Offline simulations

 This way we can account for (and estimate) fluctuations and still produce a mean expected signal.

• Sadly, a little computing effort is required.

Data handling

thousands of Offline produced ADSTs



48 databases

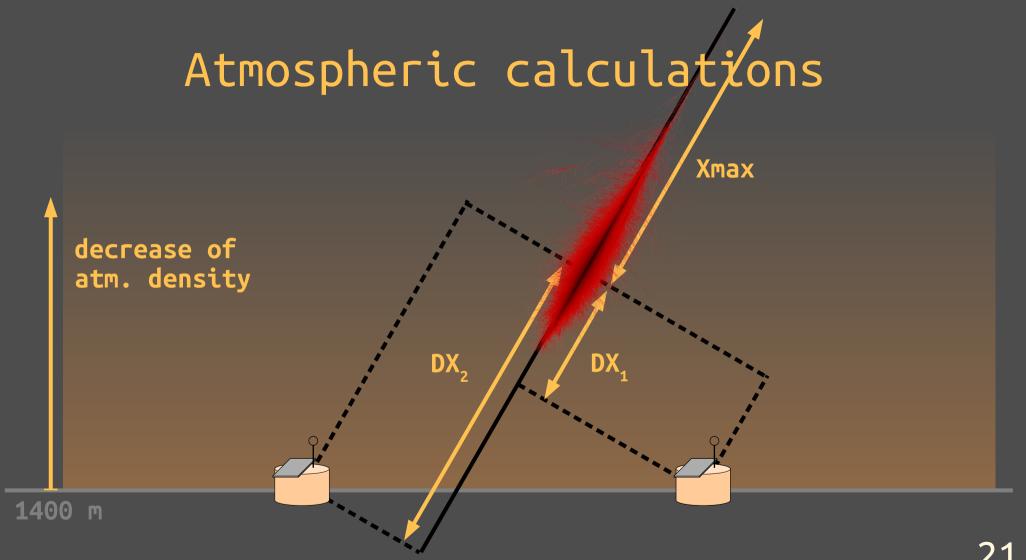
https://gitlab.ikp.kit.edu/shower-universality/universality-v2/tree/master/ data/

Data handling

• Data is compressed by a factor of ~100.

 Readout of multi-event-observables in microseconds.

https://gitlab.ikp.kit.edu/shower-universality/universality-v2/tree/master/
data/



Atmospheric calculations

• Now:

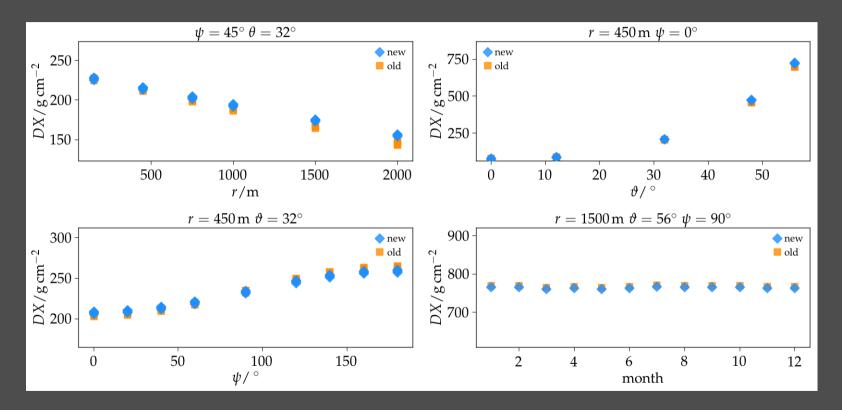
Calculating DX only with hard-coded monthly CORSIKA atmospheres Offline: include/tls/Atmosphere.h

• Future:

Use the same routines and data as FD (especially for real events), apply monthly corrections by "gauging" technique

https://gitlab.ikp.kit.edu/shower-universality/universality-v2/blob/master/
src/PowerShower.cc

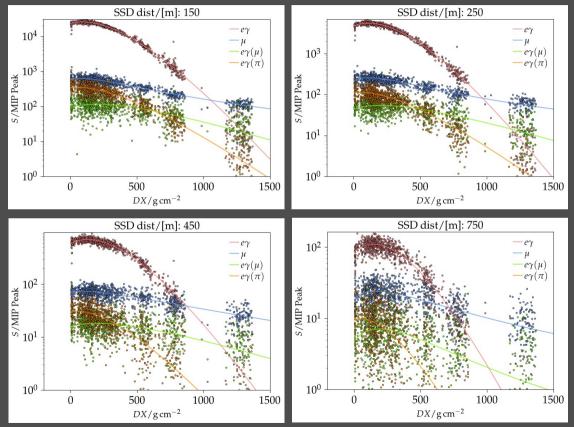
Atmospheric calculations



https://gitlab.ikp.kit.edu/shower-universality/universality-v2/blob/master/
misc/CalcDX.cc

Signal parametrization

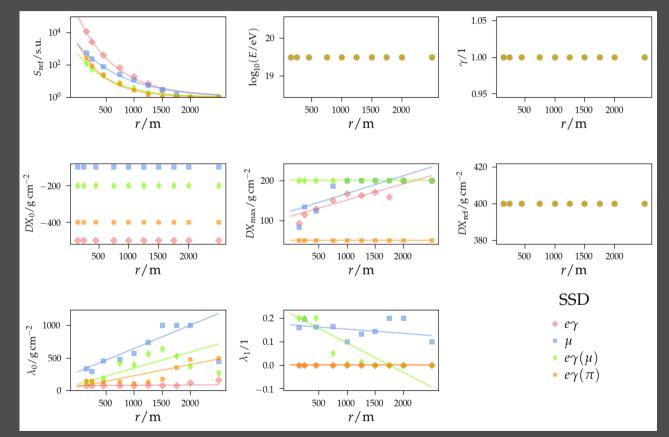
- Fit of the modified GHfunction for all events and all sampling areas.
- All fits run by Minou.
 [D. Veberic, M. Schimassek]



24

Signal parametrization

- Combined
 results yield
 the model (very
 preliminary!).
- Results stored in XML format!



Haptic of the framework

 Idea: Plug-and-play in the bootstrap.xml

• Existent parametrizations could be imported via XML. 1 <?xml version="1.0" encoding="iso-8859-1"?>5 3 <!DOCTYPE bootstrap [4 <!ENTITY standardFdIdealDetConfig SYSTEM 'SENV{AUGEROFFLINER00T}/share/auger-offline/config/standar</pre> 5 <!ENTITY standardSdIdealDetConfig SYSTEM 'SENV{AUGEROFFLINEROOT}/share/auger-offline/config/standar 8 <bootstrap xmlns:xsi="http://www.w3.org/2001/XMLSchema-instance" xsi:noNamespaceSchemaLocation='SENV{AUGEROFFLINEROOT}/share/auger-offline/config/bootstrap.xsd' xmlns:xlink="http://www.auger.org/schema/types"> &standardFdIdealDetConfig: &standardSdIdealDetConfig: this bootstrap is to be used for handling of simulations and simulations only. the detector config is therefore the ideal detectors <centralConfig>S <configLinkS = "XML" xlink:href = "\${prefix}/analysis/prototyping fit parameters.xml" <configLinkS = "AzimuthCorrectionParameters" xlink:href = "S{prefix}/analysis/azimuthal corrections.xml"/> </centralConfig> <parameterOverrides>

Haptic of the framework

 Offline and universality functions are callable and configured with the bootstrap.xml!

• Offline must be installed!

22:19 eol:~/Universality/universality-v2 (*) ➤ ./bin/CalcDX -p 1000 90 1452 850 12 3 0 0 0

master [46f9782] modified

NH PMRHELI 13

ou have chosen	
/[m]:	1000
osi /[degree]:	90
round_level /[m]:	1452 (not used for simulations!)
(max /[g/cm**2]:	850
theta /[degree]:	12
nonth /[112]:	3
additional flags	
silent:	0
<pre>Jse_DL:</pre>	0
<pre>use_old_routine:</pre>	0

[WARN] Utilities/Reader/Reader.cc:179: Parse: No schema (.xsd) document is available for file "/home/max/Un iversality/universality-v2/analysis/prototyping_fit_parameters.xml". It will not be validated!

[WARN] Utilities/Reader/Reader.cc:179: Parse: No schema (.xsd) document is available for file "/home/max/Un iversality/universality-v2/analysis/azimuthal_corrections.xml". It will not be validated!

[WARN] Framework/CentralConfig/CentralConfig.cc:741: CheckFingerprints: No configuration-time MD5 fingerpri nt found for the following configuration files. Checking the validity of these configuration files is impos sible.

azimuthal_corrections

- prototyping_fit_parameters

[INFO] Framework/FDetector/FdAlwaysUpManager.cc:39: Init: FdAlwaysUpManager initialized

[WARN] Framework/Manager/VManager.cc:32: FindConfig: Attempt to initialize an already initialized manager: FdAlwaysUpManager

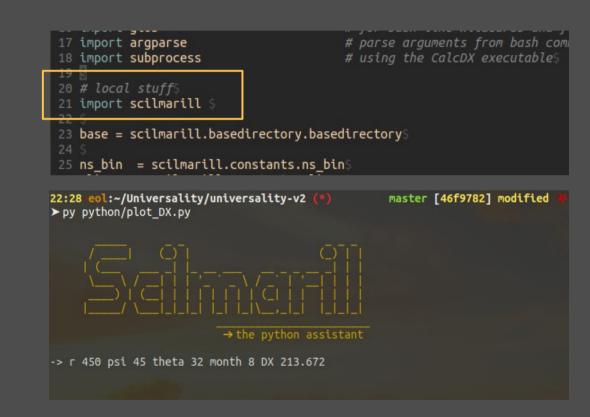
[INFO] Framework/FDetector/FFixCalibManager.cc:61: Init: fixed calibration constant is 5 ph/ADC

[INFO] Framework/Detector/Detector.cc:81: Detector: Could not access a configuration file for the RManagerR egister. The Detector interface will not be able to get information about Radio (this is not an error, unle ss you are planning to use radio detector information).

[INFO] Framework/Detector/Detector.cc:96: Detector: Could not access a configuration file for the MManagerR egister. The Detector interface will not be able to get information about the MD (this is not an error, unl ess you are planning to use muon detector information).

Haptic of the framework

 Comes with a python package to plot data/fits/... directly from HDF5 and XML



Outlook

- O(10) months: Flexible, easy to handle framework for Universality
- By the end of my thesis (*hopefully!*): Primary mass estimation on event level

Questions?